# Efficient Tate Pairing Computation Using Double-Base Chains 

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#### Abstract

Pairing-based cryptosystems have been developing very fast in the last few years. The efficiencies of the cryptosystems are determined by the computation of the Tate pairing. In this paper a new efficient algorithm based on double-base chain for computing the Tate pairing is proposed for odd characteristic $p>3$. The inherent sparseness of doublebase number system reduces the computational cost for computing the Tate pairing evidently. It is $9 \%$ faster than the previous fastest method for MOV degree $\mathrm{k}=6$.


Keywords: Tate pairing, Elliptic curves, Double-base chains.

## 1 Introduction

The bilinear pairings, namely the Weil pairing and the Tate pairing of algebraic curves, are important tools for research on algebraic geometry. The early applications of the bilinear pairings in cryptography were used to evaluate the discrete logarithm problem. For example, the MOV attack [22] (using Weil pairing) and FR attack [15] (using Tate pairing) reduce the discrete logarithm problem on some elliptic curves or hyperelliptic curves to the discrete logarithm problem in a finite field. However, the bilinear pairings have been found various applications in cryptography since the publication of the works of Joux [20] and Sakai [26]. For example, there have been many papers on identity based encryption [9, 28, 6], short signatures $[10,29,7]$, group signatures [8], and many more. Pairing-based cryptosystems are currently one of the most active areas of research in elliptic curve cryptography. More details about research on pairings can be found at Paulo Barreto's pairing-based crypto lounge [3].

However, the pairing computations are often the bottleneck to realize cryptographic applications practically. Therefore, the fast implementations of these pairings have become a subject of active research areas in elliptic curve cryptography. As the Tate pairing is about twice faster than the Weil pairing generally, here we discuss the Tate pairing mainly.

The computation of the Tate pairing can be performed using an algorithm first presented by Miller [23]. There are many improvements based in some manner on Miller's algorithm proposed. Generally the following factors would affect the efficiency of computing the pairings: the base in Miller's algorithm, the coefficients of the elliptic curves, the Hamming weight of the subgroup orders and the relation of two input points. From different angles, many techniques have been exploited to dramatically improve the performance of the algorithm. The work in $[2,17,13]$ mainly focus on reducing the large unit operations such as to remove the cost of denominator computation and denominator squaring. Eisenträer, et al. [14] combine an improved point multiplication with a parabola substitution, enables them to get an improvement to Miller's algorithm for general elliptic curves. The authors in [5] find that the times of Tate double-and-add operation in the algorithm could be reduced. Izu and Takagi [19] apply the iterated double Tate pairing and the polynomial expansion trick to the computation of Tate pairing. Recently, Kobayashi et al. introduce a pseudo-arithmetic method to computing the Tate pairing in [21]. Some special pairings for efficient fast computations are introduced, such as eta pairing [4] and ate pairing [18].

In our paper, we propose a new modified Miller's algorithm based on a representation of the multiplier as a sum of mixed powers of 2 and 3, called the double-base number system(DBNS). The sparseness of this representation leads to fewer multiplicative operations than some general modifications of Miller's algorithm. The new algorithm for computing the pairing can be applied into supersingular and ordinary elliptic curves. Here the prime order of the elliptic curve subgroup is selected randomly since a prime modulus $p$ of low Hamming weight leads to the possible lowering of discrete-logarithm security [25], while $P$ and $Q$ in the pairing $e_{l}(P, Q)$ are chosen randomly and have no special relations in our algorithm since they can be implemented widely in many cryptographic protocols for security considerations.

This paper is organized as follows. Section 2 introduces basic mathematical concepts of the Tate pairing, Miller's algorithm and DBNS. Section 3 describes the modified Miller's algorithm based on double-base chain. Section 4 discusses the efficiency of the new algorithm. In Section 5 we summarize our work.

## 2 Mathematical Preliminaries

### 2.1 The Tate Pairing

Let $q=p^{m}$, where $p>3$ is a prime number and $m$ is a positive integer. $F_{q}$ is a finite field with $q$ elements. $p$ is the characteristic of $F_{q}$, and $m$ is its extension degree.

Let $E$ be an elliptic curve defined over a finite field $F_{q}$.

$$
E: y^{2}=x^{3}+a x+b
$$

where $a, b \in F_{q}, 4 a^{3}+27 b^{2} \neq 0 \in F_{q}$.

Let $l$ be a prime integer which is coprime to $q . l$ is the order of a point $P \in E\left(F_{q}\right)$. Let $l \dagger(q-1)$, and $k$ be the smallest positive integer satisfying $l \mid\left(q^{k}-1\right) . k$ is also called the embedding degree or MOV degree. We denote the $l$-torsion points on the elliptic curve as $\mathrm{E}[l]$.

A divisor is a formal sum of points on the elliptic curve $E\left(F_{q^{k}}\right)$ (see [27]). The degree of a divisor $D=\sum_{P} a_{P}(P)$ is the $\operatorname{sum} \operatorname{deg}(D)=\sum_{P} a_{P}$. Let $f$ be a function on the elliptic curve and let $D_{R}=\sum_{R} a_{R}(R)$ which satisfies $\operatorname{deg}\left(D_{R}\right)=0$. Then we define $f\left(D_{R}\right)=\prod_{R} f(R)^{a_{R}}$.

Let $P \in E\left(F_{q}\right)[l]$ and $Q \in E\left(F_{q^{k}}\right)[l] . D_{P}$ and $D_{Q}$ are the divisors of $E$, satisfying $D_{P} \sim(P)-(\mathcal{O})$ and $D_{Q} \sim(Q)-(\mathcal{O})$, respectively. Let $f_{P}$ be a function on the elliptic curve whose divisor is $\operatorname{div}\left(f_{P}\right)=l D_{P}$.

The reduced Tate pairing $e_{l}$ is a mapping

$$
e_{l}: E\left(F_{q}\right) \cap E[l] \times E\left(F_{q^{k}}\right) \cap E[l] \rightarrow F_{q^{k}}^{*}
$$

defined as

$$
e_{l}(P, Q)=\left(f_{P}\left(D_{Q}\right)\right)^{\left(q^{k}-1\right) / l}
$$

By Theorem 1 in [2], one can define the reduced Tate pairing as

$$
e_{l}(P, Q)=f_{P}(Q)^{\left(q^{k}-1\right) / l}
$$

The Tate pairing satisfies the following properties:

1. Well-defined $e_{l}(\mathcal{O}, Q)=1$ for all $Q \in E\left(F_{q^{k}}\right)$ and $e_{l}(P, Q)=1$ for all $P \in E\left(F_{q}\right) \cap E[l], Q \in l E\left(F_{q^{k}}\right)$.
2. Bilinearity For any $P \in E\left(F_{q}\right)[l], Q \in E\left(F_{q^{k}}\right)$ and any integer $n$, $e_{l}(n P, Q)=e_{l}(P, n Q)=e_{l}(P, Q)^{n}$.
3. Non-degeneracy If $e_{l}(P, Q)=1$ for all $Q \in E\left(F_{q^{k}}\right)$, then $P=\mathcal{O}$.

### 2.2 Miller's Algorithm

The main part of the computation of the Tate pairing is calculating $f_{P}(Q)$. Miller [23] first proposed an efficient algorithm for computing the Tate pairing. The main idea of Miller's algorithm is to combine the 'double-add' algorithm for elliptic curve point multiplication with an evaluation of the straight lines passing the related points used in the addition process. Now we describe Miller's original algorithm simply.

For $P, Q \in E\left(F_{q^{k}}\right)$, we define $l_{P, Q}$ to be the equation of the line through points $P$ and $Q$ (if $P=Q$, then $l_{P, Q}$ is the tangent to the curve at $P$ or $Q$, and if one of $P$ or $Q$ is the point at infinity $\mathcal{O}$, then the $l_{P, Q}$ is a vertical line at the other point). We define $v_{P}$ to be the equation of the line between P and $\mathcal{O}$ if $P$ is not equal to $\mathcal{O}$.

Let $P$ be a point in $E\left(F_{q}\right)[l]$ and $f_{j}$ be a function on the elliptic curve with its divisor $\left(f_{j}\right)=j(P)-(j P)-(j-1) \mathcal{O}, j \in Z$. Then for $i, j \in Z$, we have

$$
f_{i+j}(Q)=f_{i}(Q) f_{j}(Q) l_{i P, j P}(Q) / v_{(i+j) P}(Q)
$$

Note that $\left(f_{0}\right)=\left(f_{1}\right)=0$, so that $f_{0}(Q)=f_{1}(Q)=1$. A second useful remark is that $f_{i}=-\left(f_{-i}\right)-\left(v_{i P}\right)$ for $i<0$. Thus we have $f_{i}(Q)=1 /\left(f_{-i}(Q) v_{i P}(Q)\right)$. Particularly, we have $f_{-1}(Q)=1 /\left(x_{Q}-x_{P}\right)$ for $P=\left(x_{P}, y_{P}\right)$ and $Q=\left(x_{Q}, y_{Q}\right)$.

Miller's original algorithm is described as follows.

## Miller's original algorithm

Input An prime integer $l=\sum_{i=0}^{n} l_{i} 2^{i}$, where $l_{i} \in\{0,1\} . P \in E\left(F_{q}\right)[l]$ and $Q \in E\left(F_{q^{k}}\right)[l]$
Output $e_{l}(P, Q)$

1. $T \leftarrow P, f_{1} \leftarrow 1$
2. for $i=n-1, n-2, \ldots, 1,0$ do
$2.1 f_{1} \leftarrow f_{1}^{2} \cdot \frac{l_{T, T}(Q)}{v_{2 T}(Q)}, T \leftarrow 2 T$
2.2 if $l_{i}=1$ then
$2.3 f_{1} \leftarrow f_{1} \cdot \frac{l_{T, P}(Q)}{v_{T+P}(Q)}, T \leftarrow T+P$
3. return $f_{1}^{\left(q^{k}-1\right) / l}$

### 2.3 Double-base Number System

The double-base number system (DBNS) [12] is a representation for integers. It can reduce plus or minus signs for representing an positive integer highly. Every positive integer $n$ can be represented as the sum of $\{2,3\}$-integers (i.e., numbers of the form $2^{b} 3^{t}$ ) as

$$
k=\sum_{i=1}^{m} s_{i} 2^{b_{i}} 3^{t_{i}}
$$

where $s_{i} \in\{-1,1\}, b_{i}, t_{i} \geq 0$.
The work of [12] gives an efficient greedy algorithm for representing $k$ sparsely using double-base chain. Let $b_{\max }$ and $t_{\max }$ be the highest power of 2 and 3 in double-base chain, respectively. We cite Table 7 in [12] generated by using 10000 randomly chosen 160-bit integers.

Table 1. Average number of terms and different largest binary and ternary exponents

| $b_{\max }$ | $t_{\max }$ | m | $b_{\max }$ | $t_{\max }$ | m |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 57 | 65 | 45 | 95 | 41 | 37 |
| 76 | 53 | 38 | 103 | 36 | 39 |

## 3 Miller's Algorithm Using Double-base Chain

In general, affine coordinates are more efficient than projective coordinates[16, 21] in the computation of the Tate pairing. Therefore affine coordinate system is
employed in our algorithm. We will borrow the point tripling [11] and the point quadrupling [1] in affine coordinates for computing the Tate pairing efficiently.

Point tripling algorithm [11] and quadrupling algorithm [1] in affine coordinates are described respectively as follows.

## Point Tripling Algorithm in [11]

Input $P\left(x_{1}, y_{1}\right) \in E\left(F_{q}\right)$
Output $3 P=\left(x_{3}, y_{3}\right)$

1. $t_{1} \leftarrow\left(2 y_{1}\right)^{2}, m \leftarrow 3 x_{1}^{2}+a, s \leftarrow m^{2}$
2. $d_{1} \leftarrow\left(3 x_{1}\right) \cdot t_{1}-s$
3. $d \leftarrow\left(2 y_{1}\right) \cdot d_{1} ; I \leftarrow d^{-1}$
4. $\lambda_{1} \leftarrow d_{1} \cdot I \cdot M ; \lambda_{2} \leftarrow-\lambda_{1}+t_{1}^{2} \cdot I$
5. $x_{3} \leftarrow\left(\lambda_{2}-\lambda_{1}\right) \cdot\left(\lambda_{2}+\lambda_{1}\right)+x_{1}$
6. $y_{3} \leftarrow \lambda_{2} \cdot\left(x_{1}-x_{3}\right)-y_{1}$

It is easily checked that the cost of point tripling algorithm is $1 \mathrm{I}+7 \mathrm{M}+4 \mathrm{~S}$.

## Point Quadrupling Algorithm in [1]

Input $P\left(x_{1}, y_{1}\right) \in E\left(F_{q}\right)$
Output $2 P=\left(x_{2}, y_{2}\right), 4 P=\left(x_{4}, y_{4}\right) \in E\left(F_{q}\right)$

1. $m \leftarrow 3 x_{1}^{2}+a, s \leftarrow x_{1} \cdot\left(2 y_{1}\right)^{2}, t \leftarrow\left(2 y_{1}\right)^{4}$
2. $e \leftarrow 2 m \cdot\left(3 s-m^{2}\right)-t, E \leftarrow\left(2 y_{1}\right) \cdot e$,
3. $I \leftarrow E^{-1},\left(2 y_{1}\right)^{-1} \leftarrow e \cdot I,\left(2 y_{2}\right)^{-1} \leftarrow t \cdot I$
4. $\lambda_{1} \leftarrow m \cdot\left(2 y_{1}\right)^{-1}$,
5. $x_{2} \leftarrow \lambda_{1}^{2}-2 x_{1}, y_{2} \leftarrow \lambda_{1} \cdot\left(x_{1}-x_{2}\right)-y_{1}$
6. $\lambda_{2} \leftarrow\left(3 x_{2}^{2}+a\right) \cdot\left(2 y_{2}\right)^{-1}$
7. $x_{4} \leftarrow \lambda_{2}^{2}-2 x_{2}, y_{4} \leftarrow \lambda_{2} \cdot\left(x_{2}-x_{4}\right)-y_{2}$

It is easily checked that the cost of point quadrupling algorithm is $1 \mathrm{I}+9 \mathrm{M}+7 \mathrm{~S}$.
We denote the computational cost of point addition, doubling, tripling and quadrupling in affine coordinates on the elliptic curve as ECADD, ECDBL, ECTRL and ECQDL respectively. Table 2 summarizes these simple operations on $E\left(F_{q}\right)$.

Table 2. Cost of simple operations on $E\left(F_{q}\right)$

| operation | cost |
| :--- | :---: |
| ECADD | $1 I+2 M+1 S$ |
| ECDBL | $1 I+2 M+2 S$ |
| ECTRL [11] | $1 I+7 M+4 S$ |
| ECQDL [1] | $1 I+9 M+7 S$ |

### 3.1 Miller's Algorithm Using Double-base Chain

Let $l$ be a positive integer represented in double-base chain. Let $P \in E\left(F_{q}\right)[l]$ and $Q \in E\left(F_{q^{k}}\right)[l]$. Miller's algorithm based on double-base chain is described as follows.

## Miller's Algorithm using Double-Base Chain

Input An integer $l=\sum_{i=1}^{m} s_{i} 2^{b_{i}} 3^{t_{i}}$, with $s_{i} \in\{-1,1\}$, and such that $b_{1} \geq$ $b_{2} \geq \ldots \geq b_{m} \geq 0$, and $t_{1} \geq t_{2} \geq \ldots \geq t_{m} \geq 0 ;$ and $P=\left(x_{P}, y_{P}\right) \in$ $E\left(F_{q}\right)[l]$ and $Q=\left(x_{Q}, y_{Q}\right) \in E\left(F_{q^{k}}\right)[l]$
Output $e_{l}(P, Q)$

1. $T \leftarrow P, f_{-1}=1 /\left(x_{Q}-x_{P}\right)$; if $s_{1}=1$, then $f_{1} \leftarrow 1$; else $f_{1} \leftarrow f_{-1}$
2. for $i=1, \ldots, m-1$ do
$2.1 u \leftarrow b_{i}-b_{i+1}, v \leftarrow t_{i}-t_{i+1}$
2.2 if $u=0$ then
2.2.1 for $j=1, \ldots, v$ do
2.2.2 $\quad f_{1} \leftarrow f_{1}^{3} \cdot \frac{l_{T, T}(Q) l_{T, 2 T}(Q)}{v_{2 T}(Q) v_{3 T}(Q)}, T \leftarrow 3 T$
2.3 else
2.3.1 if $v=0$ then
2.3.2 for $j=1, \ldots, u$ do
2.3.3 $\quad f_{1} \leftarrow f_{1}^{2} \cdot \frac{l_{T, T}(Q)}{v_{2 T}(Q)}, T \leftarrow 2 T$
2.3.4 else
2.3.5 for $j=1, \ldots, u$ do
2.3.6 $\quad f_{1} \leftarrow f_{1}^{2} \cdot \frac{l_{T, T}(Q)}{v_{2 T}(Q)}, T \leftarrow 2 T$
2.3.7 for $j=1, \ldots, v$ do
2.3.8 $\quad f_{1} \leftarrow f_{1}^{3} \cdot \frac{l_{T, T}(Q) l_{T, 2 T}(Q)}{v_{2 T}(Q) v_{3} T(Q)}, T \leftarrow 3 T$
2.4 if $s_{i+1}=1$, then $f_{1} \leftarrow f_{1} \cdot \frac{l_{T, P}(Q)}{v_{T+P}(Q)}, T \leftarrow T+P$
2.5 else $f_{1} \leftarrow f_{1} \cdot f_{-1} \frac{l_{T,-P}(Q)}{v_{T-P}(Q)}, T \leftarrow T-P$
3. return $f_{1}^{\left(q^{k}-1\right) / l}$

It seems that our new algorithm would be fast because of the sparseness of an integer represented in double-base chain. In the following section we will analyze the complexity of the addition, subtraction, doubling and tripling part of computing the Tate pairing. In Section 5 We will show that our modified Miller's algorithm is more efficient than the previous fastest method indeed.

## 4 The Complexity of Computing the Tate Pairing

We neglect the cost of field additions and subtractions, as well as the cost of multiplication by small constants. The computational cost of a multiplication, a squaring, an inversion in $F_{q}^{*}$ can be denoted the same as above. The computational cost of a multiplication, a squaring, and an inversion in $F_{q^{k}}^{*}$ can be represented by $M_{k}, S_{k}$ and $I_{k}$. A multiplication between elements in $F_{q^{k}}^{*}$ and $F_{q}^{*}$ is denoted as $M_{b}$. We will take $M_{k}=k^{1.6} M$ and $M_{b}=k M$ in the efficiency consideration.

The computational cost of the addition, subtraction, doubling and tripling part of the computation of the Tate pairing is represented by TADD, TSUB, TDBL and TTRL, respectively. We consider their computational cost in detail in this section. Some useful remarks are given as below.

For an element $g \in F_{q^{k}}$, the conjugates of $g$ is denoted by $\bar{g}$. Notice that we can replace $\left(x_{Q}-x_{1}\right)^{-1}$ by $\overline{x_{Q}}-x_{1}$ since $\overline{x_{1}}=x_{1} \in F_{q}^{*}$ in the computation of the Tate pairing generally. This replacement is similar to the pseudo-inversion method in [21] and leads to the reducibility of inversive operations in Miller's algorithm. In the sequel, we analyze the complexity of TADD, TSUB, TDBL, TTRL, and iterated TDBL respectively.

### 4.1 The Computational Cost of TADD

Let $T\left(x_{1}, y_{1}\right), P\left(x_{P}, y_{P}\right) \in E\left(F_{q}\right)$. TADD algorithm is described as below.

$$
\begin{aligned}
& \text { TADD Algorithm } \\
& \text { Input } f \in F_{p^{k}}^{*}, T\left(x_{1}, y_{1}\right), P\left(x_{P}, y_{P}\right) \in E\left(F_{q}\right), Q\left(x_{Q}, y_{Q}\right) \in E\left(F_{q^{k}}\right) \\
& \text { Output the updated } f \\
& \text { 1. } T_{5}\left(x_{5}, y_{5}\right) \leftarrow \operatorname{ECADD}(T, P) \\
& \text { 2. } l_{1} \leftarrow\left(y_{Q}-y_{P}\right)-\lambda\left(x_{Q}-x_{P}\right) \\
& \text { 3. } l_{2} \leftarrow x_{Q}-x_{5} \\
& \text { 4. } f \leftarrow f \cdot l_{1} \bar{l}_{2} \\
& \text { 5. return } f
\end{aligned}
$$

If we take advantage of the polynomial expansion method $[21,19]$ and the fact that $\overline{x_{5}}=x_{5}$, we have

$$
\begin{aligned}
l_{1} \overline{l_{2}} & =\left(\left(y_{Q}-y_{P}\right)-\lambda\left(x_{Q}-x_{P}\right)\right)\left(\overline{x_{Q}}-x_{5}\right) \\
& =\left(y_{Q}-y_{P}\right) \overline{x_{Q}}-\lambda\left(x_{Q}-x_{P}\right) \overline{x_{Q}}-x_{5}\left(y_{Q}-y_{P}\right)+\lambda x_{5}\left(x_{Q}-x_{P}\right)
\end{aligned}
$$

Notice that $\left(y_{Q}-y_{P}\right) \overline{x_{Q}}$ and $\left(x_{Q}-x_{P}\right) \overline{x_{Q}}$ can be precomputed. Calculating $\lambda x_{5}$ requires $1 M$ and calculating three scalar multiplications, $\lambda \cdot\left(x_{Q}-x_{P}\right) \overline{x_{Q}}$, $x_{5} \cdot\left(y_{Q}-y_{P}\right), \lambda x_{5} \cdot\left(x_{Q}-x_{P}\right)$ requires $3 M_{b}$. In addition, computing $f \cdot l_{1} \bar{l}_{2}$ requires $1 M_{k}$. Therefore the total cost of TADD is $M_{k}+3 M_{b}+M+\mathrm{ECADD}$ as discussed in [21]. If the pseudo-multiplication [21] method is applied, it can be reduced to $M_{k}+2.5 M_{b}+M+$ ECADD with $k \geq 3$. The precomputed cost of TADD is $2 M_{k}+7 M_{k / 2}+I_{k / 2}$.

### 4.2 The Computational Cost of TSUB

Let $T\left(x_{1}, y_{1}\right), P=\left(x_{P}, y_{P}\right) \in E\left(F_{q}\right)$. Since

$$
f_{-1} l_{1}(Q)=\frac{\left(y_{Q}+y_{P}\right)-\lambda\left(x_{Q}-x_{P}\right)}{x_{Q}-x_{P}}=\frac{y_{Q}+y_{P}}{x_{Q}-x_{P}}-\lambda
$$

we can substitute $f_{-1} l_{1}(Q)$ with $\frac{y_{Q}+y_{P}}{x_{Q}-x_{P}}-\lambda$ in the subtraction part of the computation of the Tate pairing. Notice that $\frac{y_{Q}+y_{P}}{x_{Q}-x_{P}}$ can be precomputed. TSUB algorithm is described as follows.

## TSUB Algorithm

Input $f \in F_{p^{k}}^{*}, T\left(x_{1}, y_{1}\right), P\left(x_{P}, y_{P}\right) \in E\left(F_{q}\right), Q\left(x_{Q}, y_{Q}\right) \in E\left(F_{q^{k}}\right)$
Output the updated $f$

1. $T_{6}\left(x_{6}, y_{6}\right) \leftarrow \operatorname{ECADD}(T,-P)$
2. $f_{-1} l_{1} \leftarrow \frac{y_{Q}+y_{P}}{x_{Q}-x_{P}}-\lambda$
3. $l_{2} \leftarrow x_{Q}-x_{6}$
4. $f \leftarrow f \cdot\left(f_{-1} l_{1}\right) \overline{l_{2}}$
5. return $f$

It is easily checked that the total cost of TSUB is $M_{k}+(2 k+1) M+$ ECADD if the polynomial expansion method $[21,19]$ is applied. The precomputed cost of TSUB is $2 M_{k}+I_{k}$.

### 4.3 The Computational Cost of TDBL

Let $T\left(x_{1}, y_{1}\right), T_{2}=2 T=\left(x_{2}, y_{2}\right) \in E\left(F_{q}\right)$. TDBL algorithm is described in the following.

## TDBL Algorithm

Input $T=\left(x_{1}, y_{1}\right) \in E\left(F_{q}\right), Q=\left(x_{Q}, y_{Q}\right) \in F_{q^{k}}$, and $f \in F_{q^{k}}^{*}$
Output the updated $f$

1. $T_{2}=\left(x_{2}, y_{2}\right) \leftarrow \operatorname{ECDBL}(T)$
2. $l_{1} \leftarrow\left(y_{Q}-y_{1}\right)-\lambda\left(x_{Q}-x_{1}\right)$
3. $l_{2} \leftarrow x_{Q}-x_{2}$
4. $f \leftarrow f^{2} \cdot\left(l_{1} \overline{l_{2}}\right)$
5. return $f$

The total cost of TDBL is $M_{k}+S_{k}+4 M_{b}+2 M+$ ECDBL by using the polynomial expansion method [19, 21]. If the pseudo-multiplication [21] method is applied, it can be reduced to $M_{k}+S_{k}+3.5 M_{b}+2 M+$ ECDBL. The precomputed cost of TDBL is $2 M_{k}$.

### 4.4 The Computational Cost of TTRL

In this part we study the computational of TTRL. TTRL algorithm is described as follows.

## TTRL Algorithm

Input $T=\left(x_{1}, y_{1}\right) \in E\left(F_{q}\right), Q=\left(x_{Q}, y_{Q}\right) \in F_{q^{k}}$, and $f \in F_{q^{k}}^{*}$
Output the updated $f$

1. $T_{3}=\left(x_{3}, y_{3}\right) \leftarrow \operatorname{ECTRL}(T)$
2. $l_{1} \leftarrow \frac{l_{T, T}(Q) l_{T, 2 T}(Q)}{v_{2 T}(Q)}$
3. $l_{2} \leftarrow x_{Q}-x_{3}$
4. $f \leftarrow f^{3} \cdot\left(l_{1} \overline{l_{2}}\right)$
5. return $f$

Let $T=\left(x_{1}, y_{1}\right), T_{3}=3 T=\left(x_{3}, y_{3}\right) \in E\left(F_{q}\right)$ Let $T_{2}=2 T=\left(x_{2}, y_{2}\right)$, where $x_{2}=\lambda_{1}^{2}-2 x_{1}$ as an intermediate. We apply the parabola method [14] to computing TTRL. Notice that $l_{T, T}$ passes through $T$ and $-2 T$, whose slope is $\lambda_{1}$, and $l_{T, 2 T}$ passes through $T$ and $2 T$, whose slope is $\lambda_{2}$. We obtain

$$
\begin{aligned}
\frac{l_{T, T}(Q) l_{T, 2 T}(Q)}{v_{2 T}(Q)}= & \frac{\left(\left(y_{Q}+y_{2}\right)-\lambda_{1}\left(x_{Q}-x_{2}\right)\right)\left(\left(y_{Q}-y_{2}\right)-\lambda_{2}\left(x_{Q}-x_{2}\right)\right)}{x_{Q}-x_{2}} \\
= & \frac{y_{Q}^{2}-y_{2}^{2}}{x_{Q}-x_{2}}+\lambda_{1} \lambda_{2}\left(x_{Q}-x_{2}\right)-\lambda_{1}\left(y_{Q}-y_{2}\right)-\lambda_{2}\left(y_{Q}+y_{2}\right) \\
= & x_{Q}^{2}+x_{2} x_{Q}+x_{2}^{2}+a+\lambda_{1} \lambda_{2}\left(x_{Q}-x_{2}\right)-\lambda_{1}\left(y_{Q}-y_{2}\right)-\lambda_{2}\left(y_{Q}+y_{2}\right) \\
= & x_{Q}^{2}+\left(x_{2}+\lambda_{1} \lambda_{2}\right) x_{Q}-\left(\lambda_{1}+\lambda_{2}\right) y_{Q}+x_{2}^{2}+a-\lambda_{1} \lambda_{2} x_{2}+\left(\lambda_{1}-\lambda_{2}\right) y_{2} \\
= & \left(x_{Q}-x_{1}\right)\left(x_{Q}+x_{1}+x_{2}+\lambda_{1} \lambda_{2}\right)-\left(\lambda_{1}+\lambda_{2}\right)\left(y_{Q}-y_{1}\right)+x_{1}^{2}+x_{1} x_{2} \\
& +\lambda_{1} \lambda_{2} x_{1}-\left(\lambda_{1}+\lambda_{2}\right) y_{1}+x_{2}^{2}+a-\lambda_{1} \lambda_{2} x_{2}+\left(\lambda_{1}-\lambda_{2}\right) y_{2} \\
= & \left(x_{Q}-x_{1}\right)\left(x_{Q}+x_{1}+x_{2}+\lambda_{1} \lambda_{2}\right)-\left(\lambda_{1}+\lambda_{2}\right)\left(y_{Q}-y_{1}\right) \\
& +\frac{y_{1}^{2}-y_{2}^{2}}{x_{1}-x_{2}}+\lambda_{1} \lambda_{2}\left(x_{1}-x_{2}\right)+\left(\lambda_{1}-\lambda_{2}\right) y_{2}-\left(\lambda_{1}+\lambda_{2}\right) y_{1} \\
= & \left(x_{Q}-x_{1}\right)\left(x_{Q}+x_{1}+x_{2}+\lambda_{1} \lambda_{2}\right)-\left(\lambda_{1}+\lambda_{2}\right)\left(y_{Q}-y_{1}\right) \\
& +\left(\lambda_{1}-\lambda_{2}\right)\left(\left(y_{2}+y_{1}\right)-\lambda_{1}\left(x_{1}-x_{2}\right)\right) \\
= & \left(x_{Q}-x_{1}\right)\left(x_{Q}+x_{1}+x_{2}+\lambda_{1} \lambda_{2}\right)-\left(\lambda_{1}+\lambda_{2}\right)\left(y_{Q}-y_{1}\right)
\end{aligned}
$$

by using $y_{2}=\lambda_{1}\left(x_{1}-x_{2}\right)-y_{1}$.
We can expand the above polynomial in powers of $x_{Q}$. The expansive polynomial is

$$
\begin{aligned}
l_{1} & =x_{Q}^{2}+\left(x_{2}+\lambda_{1} \lambda_{2}\right) x_{Q}-\left(\lambda_{1}+\lambda_{2}\right)\left(y_{Q}-y_{1}\right)-x_{1}\left(x_{1}+x_{2}+\lambda_{1} \lambda_{2}\right) \\
& =x_{Q}^{2}+\left(\left(\lambda_{1}\left(\lambda_{1}+\lambda_{2}\right)-2 x_{1}\right) x_{Q}-\left(\lambda_{1}+\lambda_{2}\right)\left(y_{Q}-y_{1}\right)-\left(\lambda_{1}\left(\lambda_{1}+\lambda_{2}\right)-x_{1}\right) x_{1}\right.
\end{aligned}
$$

Computing $\lambda_{1} \cdot\left(\lambda_{1}+\lambda_{2}\right)$ and $\left(\lambda_{1}\left(\lambda_{1}+\lambda_{2}\right)-x_{1}\right) \cdot x_{1}$ requires $2 M$, and computing $\left(\left(\lambda_{1}\left(\lambda_{1}+\lambda_{2}\right)-2 x_{1}\right) \cdot x_{Q}\right.$ and $\left(\lambda_{1}+\lambda_{2}\right) \cdot\left(y_{Q}-y_{1}\right)$ requires $2 M_{b}$. Therefore we need $2 M_{b}+2 M$ for computing $l_{1}$. Notice that $x_{Q}^{2}$ can be precomputed.

We require $1 S_{k}+3 M_{k}$ for computing $f \cdot f^{2} \cdot l_{1} \cdot \overline{l_{2}}$. Thus the total cost of TTRL is $3 M_{k}+S_{k}+2 M_{b}+2 M+$ ECTRL. The precomputed cost is $1 S_{k}$.

### 4.5 The Computational Cost of Iterated TDBL

The iterated TDBL algorithm was first proposed in the work [19] of Izu. The work of [21] gave an improved iterated TDBL algorithm. We give a modified iterated TDBL algorithm by using point quadrupling in affine coordinates.

## Iterated TDBL Algorithm

Input $f \in F_{q^{k}}, T=\left(x_{1}, y_{1}\right) \in E\left(F_{q}\right)$, and $Q=\left(x_{Q}, y_{Q}\right) \in F_{q^{k}}$
Output the updated $f$

1. $T_{2}\left(x_{2}, y_{2}\right)=2 T_{1}, T_{4}\left(x_{4}, y_{4}\right)=4 T_{1} \leftarrow \operatorname{ECQDL}(T)$
2. $l_{1} \leftarrow y_{Q}-y_{1}-\lambda_{1}\left(x_{Q}-x_{1}\right)$
3. $l_{2} \leftarrow x_{Q}-x_{2}$
4. $f^{\prime} \leftarrow f^{2} \cdot l_{1} \cdot \overline{l_{2}}$
5. $l_{1}^{\prime} \leftarrow y_{Q}-y_{2}-\lambda_{2}\left(x_{Q}-x_{2}\right)$
6. $l_{2}^{\prime} \leftarrow x_{Q}-x_{4}$
7. $f \leftarrow f^{\prime 2} \cdot l_{1}^{\prime} \cdot \overline{l_{2}^{\prime}}$

Now we study the computation of $f$ in iterated TDBL. Since
the updated $f=f^{\prime 2} \cdot l_{1}^{\prime} \cdot \overline{l_{2}^{\prime}}=f^{4} \cdot l_{1}^{2} \cdot \overline{l_{2}^{2}} \cdot l_{1}^{\prime} \cdot \overline{l_{2}^{\prime}}=\left(f^{2} \cdot l_{1}\right)^{2} \cdot l_{1}^{\prime} \cdot \overline{l_{2}^{2} l_{2}^{\prime}}$
We can apply the polynomial expansion method in $l_{2}^{2} l_{2}^{\prime}$. Then

$$
l_{2}^{2} l_{2}^{\prime}=\left(x_{Q}-x_{2}\right)^{2}\left(x_{Q}-x_{4}\right)=x_{Q}^{3}-\left(x_{4}+2 x_{2}\right) x_{Q}^{2}+\left(2 x_{2} x_{4}+x_{2}^{2}\right) x_{Q}-x_{2}^{2} x_{4}
$$

Since $x_{2}^{2}$ is computed in $\operatorname{ECQDL}\left(T_{1}\right), x_{2} \cdot x_{4}$ and $x_{2}^{2} \cdot x_{4}$ require 2 M . $\left(x_{4}+2 x_{2}\right) \cdot x_{Q}^{2}$ and $\left(2 x_{2} x_{4}+x_{2}^{2}\right) \cdot x_{Q}$ require $2 M_{b}$. Therefore, the total cost of iterated TDBL is

$$
3 M_{k}+2 S_{k}+4 M_{b}+2 M+\mathrm{ECQDL}
$$

It is obviously more efficient than the iterated TDBL in [21] if the cost of 1ECQDL is lower than the cost of 2 ECDBL .

We summarize these results in the following table.

Table 3. Cost of elementary operations for computing the Tate pairing

| operation | cost |
| :---: | :---: |
| TADD | $M_{k}+2.5 M_{b}+1 I+3 M+1 S$ |
| TSUB | $M_{k}+1 I+(2 k+3) M+1 S$ |
| TDBL | $M_{k}+S_{k}+3.5 M_{b}+1 I+4 M+2 S$ |
| Iterated TDBL | $3 M_{k}+2 S_{k}+4 M_{b}+1 I+11 M+7 S$ |
| TTRL | $3 M_{k}+S_{k}+2 M_{b}+1 I+9 M+4 S$ |

## 5 Efficiency Consideration

In this section we put our emphasis on studying the efficiency of new proposed algorithm and comparing it with the previous methods in [21] and [19]. Since it is necessary that the order $l$ of elliptic curve subgroup have at least 160 bits and $q^{k}$ have at least 1000 bits for security and efficiency in many cryptographic protocols, we mainly give our efficiency analysis for $\log _{2} l=160$.

### 5.1 Efficiency of Our Proposed Algorithm

The total precomputed cost of new proposed algorithm is

$$
T_{p r e}=6 M_{k}+S_{k}+I_{k}+7 M_{k / 2}+I_{k / 2}
$$

We assume that plus signs and minus signs appear on average if $l$ is represented in double-base chain. The total cost of our algorithm is

$$
\begin{aligned}
& b_{\max } \mathrm{TDBL}+t_{\max } \mathrm{TTRL}+\frac{m}{2}(\mathrm{TADD}+\mathrm{TSUB})+T_{p r e} \\
= & \left(\left(b_{\max }+3 t_{\max }+m+6\right) M_{k}+\left(\left(b_{\max }+t_{\max }+1\right) S_{k}\right.\right. \\
& +\left(\frac{7}{2} b_{\max }+2 t_{\max }+\frac{5}{4} m\right) M_{b}+\left(b_{\max }+t_{\max }+m\right) I \\
& +\left(4 b_{\max }+9 t_{\max }+(k+3) m\right) M+\left(2 b_{\max }+4 t_{\max }+m\right) S+I_{k}+7 M_{k / 2}+I_{k / 2}
\end{aligned}
$$

Here we take $M_{4}=9 M, M_{6}=18 M, M_{8}=27 M, S=0.8 M, I=10 M, M_{b}=$ $k M, I_{k}=I+k^{2} M$. We estimate the cost of new proposed algorithm by Table 1 since the 160 bit length of $l$ is enough for security in many cryptographical protocols. Notice that we do not use the iterated TDBL technique [19, 21] for simplicity.

Table 4. Cost of new proposed algorithm by Table 1

| $b_{\max }$ | $t_{\max }$ | m | $\operatorname{cost}(\mathrm{k}=4)$ | $\operatorname{cost}(\mathrm{k}=6)$ | $\operatorname{cost}(\mathrm{k}=8)$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 57 | 65 | 45 | 8287 M | 12744 M | 17222 M |
| 76 | 53 | 38 | 8350 M | 12554 M | 17085 M |
| 95 | 41 | 37 | 8395 M | 12552 M | 17052 M |
| 103 | 36 | 39 | 8493 M | 12676 M | 17186 M |

### 5.2 Comparisons

In this part, we compare our algorithm with the previous methods in [19] and [21] mainly.

If we assume that $k$ is a randomly chosen $n$-bit integer, it is well known that the double-and-add algorithm requires $n$ doubling and $n / 2$ additions on average. Using the signed digit representation, the average density of non-zero digits is reduced to $1 / 3$. Therefore the computational cost of Miller's original algorithm on average is the sum of $n$ TDBL and $\frac{n}{2}$ TADD. The computational cost of signed Miller's algorithm is

$$
n \mathrm{TDBL}+\frac{n}{3}\left(\frac{1}{2} \mathrm{TADD}+\frac{1}{2} \mathrm{TSUB}\right)
$$

The computational cost of Miller's algorithm described in [19] is

$$
\begin{aligned}
& (n-1)\left(2 M_{k}+2 S_{k}+(3 k+7) M+6 S\right)+\frac{n}{2}\left(2 M_{k}+(3 k+10) M+3 S\right) \\
= & (3 n-2) M_{k}+(2 n-2) S_{k}+\left(\frac{9 n-6}{2} k+12 n-7\right) M+\frac{15 n-12}{2} S .
\end{aligned}
$$

The computational cost of signed Miller's algorithm described in [21] is

$$
\begin{aligned}
& (n-1) \mathrm{TDBL}+\frac{n}{6}(\mathrm{TADD}+\mathrm{TADD})+T_{p r e} \\
= & \left(\frac{4}{3} n+5\right) M_{k}+(n-1) S_{k}+I_{k}+7 M_{k / 2}+1 I_{k / 2} \\
& +\left(\frac{17 n-14}{4} k+(5 n-4)\right) M+\left(\frac{7}{3} n-2\right) S+\left(\frac{4}{3} n-1\right) I .
\end{aligned}
$$

Now we compare our algorithm with the proposed methods in [21] and [19]. The assumptions of $M_{k}, I$ and $n$ are the same as above. The computational cost of these algorithms is shown in the following Table.

Table 5. Cost comparison of proposed algorithms

| Algorithm | $\operatorname{cost}(\mathrm{k}=4)$ | $\operatorname{cost}(\mathrm{k}=6)$ | $\operatorname{cost}(\mathrm{k}=8)$ |
| :---: | :---: | :---: | :---: |
| new proposed algorithm | 8350 M | 12554 M | 17085 M |
| signed Miller's algorithm in $[21]$ | 9196 M | 13685 M | 18121 M |
| Miller's algorithm in $[19]$ | 12328 M | 20353 M | 28379 M |

Table 5 implies that our proposed algorithm is $9 \%$ faster and $62 \%$ faster than the previous proposed algorithms in [21] and [19] for $k=6$, respectively. the sparseness of DBNS leads to fewer multiplications than the previous methods in $[21,19]$. We also point out that our proposed algorithm can be applied for $k=2$.

## 6 Conclusion

In this paper, A new algorithm based on the double-base chain is proposed for computing the Tate pairing. The proposed algorithm can be applied to supersingular and ordinary elliptic curves. It is more efficient than the previous proposed algorithms in [21] and [19].

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