

# Analysis of the Non-Perfect Table Fuzzy Rainbow Tradeoff

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**Abstract.** Time memory tradeoff algorithms are tools for inverting one-way functions, and they are often used to recover passwords from unsalted password hashes. There are many publicly known tradeoff algorithms, and the rainbow tradeoff is widely believed to be the best algorithm. This work provides an accurate complexity analysis of the fuzzy rainbow tradeoff algorithm, which has not yet received much attention. Based on the analysis results, we show that, when the pre-computation cost and the online efficiency are both taken into consideration, the fuzzy rainbow tradeoff may be seen as preferable to the original rainbow tradeoff in many situations.

**Keywords:** time memory tradeoff, rainbow table, fuzzy rainbow, distinguished point

## 1 Introduction

Cryptanalytic time memory tradeoff algorithms are tools for quickly inverting one-way functions with the help of pre-computed data. They are used by law enforcement agencies and hackers to recover passwords from unsalted password hashes, and the multi-target variants of the algorithms have been used [7, 10, 11, 15] to show that the GSM mobile phones are insecure.

There are a multitude of publicly known tradeoff algorithms. However, a search for password recovery tools on the Web reveals [1–4] that the rainbow tradeoff [23] is by far the most popular algorithm, and this seems to indicate that the rainbow tradeoff is widely believed, at least among implementers, to be the best tradeoff algorithm.

Although it is difficult to clearly specify what is meant by one tradeoff algorithm to be better than another, the recent work [19] has given a plausible method for comparing the performances of different tradeoff algorithms. Unlike previous comparison attempts that had focused mainly on the optimal online phase behavior of the algorithms, the suggested method takes both the pre-computation cost and the online efficiency into account. Hence, the new method reflects our intuition concerning the practicality, usefulness, or value of the algorithms more closely. This approach was used in [19, 20] to show that the perfect and non-perfect rainbow tradeoffs perform better than the classical Hellman [16],

perfect distinguished point [12–14], and non-perfect distinguished point tradeoff algorithms, under typical situations, thus supporting the aforementioned beliefs.

In this work, we analyze the execution behavior of the non-perfect table fuzzy rainbow tradeoff [6, 8], which has not yet received much attention. The results are then used to compare the performance of the fuzzy rainbow tradeoff against those of the usual perfect and non-perfect rainbow tradeoffs.

We find that, with the appropriate choice of parameters, the usual rainbow tradeoffs can achieve a certain degree of online efficiency that cannot be reached by the fuzzy rainbow tradeoff through any choice of its parameters. However, we also find that, for online efficiency levels that can be reached by both the fuzzy rainbow and usual rainbow tradeoff algorithms, the fuzzy rainbow tradeoff calls for less pre-computation effort than the usual rainbow tradeoffs. In other words, up to a certain point, for the same pre-computation investment, better online efficiency is returned by the fuzzy rainbow tradeoff. Since the massive pre-computation requirement stands as a significant barrier to any large scale deployment of the tradeoff technique, the fuzzy rainbow tradeoff will often be preferable to the original rainbow tradeoffs.

The main contribution of this article is in providing an accurate execution behavior analysis of the non-perfect table fuzzy rainbow tradeoff. The final part of this article, concerning algorithm comparisons, is mostly a careful application of the framework set by [19].

The fuzzy rainbow tradeoff is a combination of the distinguished point tradeoff and the rainbow tradeoff. In fact, both the distinguished point and rainbow tradeoffs are special cases of the fuzzy rainbow tradeoff, corresponding to certain extreme parameter choices. Hence, one might expect the performance of the fuzzy rainbow tradeoff to come somewhere in between those of the distinguished point and rainbow tradeoffs. The findings of this paper, which indicate otherwise, could be seen as slightly surprising.

Arguments supporting the efficiency of the fuzzy rainbow tradeoff were given in the publications [6, 8] that introduced the algorithm. However, the arguments were based on the concept of hidden states, which totally disregards pre-computation cost, and the complexity claims made there were not tight enough to be accurate up to small constant factors. Since the performances of tradeoff algorithms often differ only by small constant factors, which nevertheless have heavy consequences in practice, it was not possible to provide an appropriate comparison of algorithms based on their results.

The only work concerning the fuzzy rainbow tradeoff that we are aware of, other than the articles introducing the algorithm, are the two presentations [21, 22] of a fully implemented attack on GSM phones. The tradeoff algorithm they explained as having used was the multi-target version of the fuzzy rainbow tradeoff<sup>1</sup>, but they did not provide any theoretic analysis of the algorithm.

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<sup>1</sup> The authors claim themselves to be the first in combining the distinguished point tradeoff and the rainbow tradeoff, hence it seems they were unaware of the preceding works [6, 8].

The rest of this paper is organized as follows. In Section 2, we review the fuzzy rainbow tradeoff algorithm. The subsequent three sections are devoted to analyzing the execution behavior of the fuzzy rainbow tradeoff. Section 3 gives the probability of success, Section 4 gives the accurate online time complexity that takes the effects of false alarms into account, and Section 5 discusses the physical storage size required to record the pre-computation tables. The main parts of our arguments made during the analyses are experimentally verifying in Section 6. A method for fixing one fuzzy rainbow tradeoff parameter that is not used in other tradeoff algorithms is discussed in Section 7. Our theoretic findings are finally used in Section 8 to present a fair comparison between the fuzzy rainbow tradeoff and the usual rainbow tradeoffs. Concluding remarks are made in Section 9.

## 2 Preliminaries

The reader is assumed to be familiar with the basic tradeoff techniques. In this section, we fix the terminology and quickly recall the fuzzy rainbow tradeoff algorithm.

Throughout this paper, the one-way function  $f : \mathcal{N} \rightarrow \mathcal{N}$  is taken to acts on a search space  $\mathcal{N}$  of size  $N$ . The composition of the one-way function and the reduction function of  $i$ -th color will be written as  $f_i$ . The standard notation for the number of chains per table  $m$ , the chain length  $t$ , and the number of tables  $\ell$  will be used. When dealing with DPs (distinguished points), the distinguishing property will always be assumed to be of probability  $\frac{1}{t}$ , so that the expected length of a random chain is  $t$ . The collection of all  $m$  chains, associated with one pre-computation table, is referred to as a pre-computation matrix.

The fuzzy rainbow tradeoff [6, 8] is a combination of the rainbow tradeoff and the DP tradeoff. Recall that the rainbow tradeoff uses length- $t$  pre-computation chains of the form

$$\text{SP} \xrightarrow{f_1} \circ \xrightarrow{f_2} \circ \dots \circ \xrightarrow{f_t} \text{EP}, \quad (1)$$

where SP and EP denote the starting and ending points, respectively. An online chain for the rainbow tradeoff starts from one of the colors  $1 \leq i \leq t$  and continues to the final  $t$ -th color. Also recall that the DP tradeoff uses variable length pre-computation and online chains of the form

$$\text{SP} \xrightarrow{f_i} \circ \xrightarrow{f_i} \circ \dots \circ \xrightarrow{f_i} \text{DP} = \text{EP}, \quad (2)$$

with a preset distinguishing property that defines DPs.

In the case of the fuzzy rainbow tradeoff, a distinguishing property and a positive integer  $s$  are fixed, and pre-computation chains of the form

$$\begin{aligned} \text{SP} \xrightarrow{f_1} \circ \dots \circ \xrightarrow{f_1} \text{DP} \xrightarrow{f_2} \circ \dots \circ \xrightarrow{f_2} \text{DP} \xrightarrow{f_3} \circ \dots \\ \dots \xrightarrow{f_{s-1}} \text{DP} \xrightarrow{f_s} \circ \dots \circ \xrightarrow{f_s} \text{DP} = \text{EP} \end{aligned} \quad (3)$$

are used. That is, the one-way function iterations are continued under a fixed color until a DP is reached, after which the iterations are continued under a different color. A total of  $s$  colors are used for each pre-computation chain, so that the average chain length becomes  $ts$ . An online chain for the fuzzy rainbow tradeoff starts from one of the colors  $1 \leq i \leq s$  and terminates at the DP for the final  $s$ -th color.

As with other tradeoff algorithms, in the pre-computation phase of the fuzzy rainbow tradeoff,  $m$  chains are generated for each of the  $\ell$  pre-computation tables, and only the starting point and ending point pairs, sorted according to the ending points, are stored in the pre-computation tables.

One can also consider the perfect tables version of this algorithm, obtained by retaining just one chain from every set of merging chains. However, only the non-perfect table version of the fuzzy rainbow tradeoff will be studied in this work. The perfect table version is likely to be more efficient during the online phase, but will require higher pre-computation cost. The results of this paper indicate that the perfect table fuzzy rainbow tradeoff is well worth analyzing, and this will be a subject of our future study.

The fuzzy rainbow tradeoff analogue of the matrix stopping rules is  $mt^2s \approx N$ . In other words, we always assume that the parameters  $m$ ,  $t$ , and  $s$ , for the fuzzy rainbow tradeoff, are chosen in such a way that the matrix stopping constant  $F_{\text{msc}} = \frac{mt^2s}{N}$  is neither too large nor very close to zero. We shall often express such a condition simply as  $F_{\text{msc}} = \Theta(1)$ . Appropriateness of the matrix stopping rule  $mt^2s \approx N$  is explained in [6]. The theoretic arguments of this paper will be easier to comprehend when  $s$  is assumed to be much smaller than  $m$  or  $t$ , even though no such assumption appears in [6, 8]. It will later become clear that the  $s$  values of interest will mostly be in the range  $15 \sim 100$ .

To complete the description of the fuzzy rainbow tradeoff algorithm, the order of online chain creation needs to be clarified. In short, all the tables are processed in parallel, in the sense that the usual rainbow tradeoff processes tables in parallel.

Let us explain this in more detail. In the initial pass, for each of the  $\ell$  pre-computation tables, the online chain that starts from the  $s$ -th color for the table is generated. Then all the alarms generated by these  $\ell$  online chains are fully resolved. All computation associated with this first pass is fully executed even if the correct answer is found during this process. The second pass is executed only if the first pass did not return the correct answer. In the second pass, the online chains that start from the  $(s - 1)$ -th colors and extend into the  $s$ -th colors are generated for all the pre-computation tables. The subsequent passes are similarly continued until either the correct answer is found or all the  $s$  passes are complete.

Just as with the usual rainbow tradeoff, in real implementations, the  $\ell$  online chains may or may not be generated simultaneously. It suffices to have all of them generated and all the associated alarms treated, in any order, before moving onto the next pass. Our theoretic arguments are placing a slight disadvantage on the fuzzy rainbow tradeoff by assuming the full processing of any single pass that has

started, but our results will still be good approximations of the true situation, as long as  $s$  is not too small.

The fuzzy rainbow tradeoff algorithm introduced by [6, 8] was a time memory data tradeoff algorithm that aimed to invert just one of multiple inversion targets. Since it is known [9] that the multi-target application of the original rainbow tradeoff results in a tradeoff curve that is quite inferior to those of the multi-target classical Hellman or distinguished point tradeoffs, the intention of [6, 8] was to create a variant of the rainbow tradeoff with a multi-target tradeoff curve of the  $TM^2D^2 \approx N^2$  form. However, in this work, we will restrict ourselves to the  $D = 1$  case and treat the fuzzy rainbow tradeoff as a single target inversion algorithm. The multi-target version of the fuzzy rainbow tradeoff must be compared against the multi-target versions of the classical Hellman and DP tradeoffs, but nothing similar to [19, 20] has yet appeared for these multi-target algorithms. Furthermore, preliminary analysis seems to indicate that the analyses for the single target inversion algorithms will carry over to the multi-target algorithms almost word for word.

The fuzzy rainbow matrix may be viewed as a concatenation of  $s$  DP sub-matrices, with the ending points of one DP sub-matrix used as the starting points for the next DP sub-matrix. Throughout this work, the  $i$ -th ( $1 \leq i \leq s$ ) DP sub-matrix will be denoted by  $DM_i$ . The only difference between  $DM_i$  and a normal non-perfect DP matrix is that  $DM_i$  may contain duplicate starting points, that bring about fully identical chains.

Any implementation of a tradeoff algorithm that relies on DPs will set a chain length bound to detect chains falling into loops. In this work, we assume that a sufficiently large chain length bound is used. This is not exactly equivalent to taking the limit where the chain length bound is sent to infinity. A more detailed discussion of the exact meaning of this assumption may be found in [19, 20].

There will be many approximations made throughout this paper. Most of these will depend on the relation  $(1 - \frac{1}{b})^a \approx e^{-\frac{a}{b}}$ , which is appropriate when  $a = O(b)$ . A more precise statement can be found in [19]. Under any reasonable choice of tradeoff parameters, these approximations will be very accurate whenever we apply the relation, and they will be written as equalities rather than as approximations. Another class of approximations appearing in this paper will involve interpretation of finite sums as definite integrals. Once again, when the summation is made over a large index set so that the approximation is accurate, we shall silently write the relation as an equality rather than as an approximation.

As is done by any theoretic treatment of the tradeoff algorithms, the one-way function is assumed to be a random function throughout this article.

### 3 Probability of Success

The number of one-way function invocations required to construct all the pre-computation tables is expected to be  $mts\ell$ . Let us define the *pre-computation coefficient* of the fuzzy rainbow tradeoff that uses parameters  $m$ ,  $t$ ,  $s$ , and  $\ell$  to

be

$$F_{\text{pc}} = \frac{mts\ell}{N}, \quad (4)$$

so that, when the effort of table sorting, which is of much smaller  $m\ell \log m$  order, is ignored, we may state  $F_{\text{pc}}N$  as the cost of pre-computation.

We also define the *coverage rate* of a fuzzy rainbow matrix to be

$$F_{\text{cr}} = \frac{1}{mts} (|\text{DM}_1| + |\text{DM}_2| + \dots + |\text{DM}_s|), \quad (5)$$

where  $|\text{DM}_i|$  denotes the number of distinct points expected in the  $i$ -th DP sub-matrix. Readers familiar with the definitions of the coverage rate appearing in previous works should note the slight difference. The current definition does not refer to the total number of distinct points in the pre-computation matrix. Nevertheless, the following proposition shows that the above is the natural definition to use in the case of fuzzy rainbow tradeoffs.

**Proposition 1.** *Given an inversion target created from a random input to the one-way function, the fuzzy rainbow tradeoff will succeed in recovering the correct input with probability*

$$F_{\text{ps}} = 1 - e^{-F_{\text{cr}}F_{\text{pc}}}.$$

*Proof.* The probability of successful inversion expected from the single DP sub-matrix  $\text{DM}_i$  is  $\frac{|\text{DM}_i|}{N}$ . Since the DP sub-matrices that were created with different reduction functions can be treated as being independent, the success rate of the complete online phase is

$$F_{\text{ps}} = 1 - \prod_{i=1}^s \left(1 - \frac{|\text{DM}_i|}{N}\right)^\ell.$$

This may be approximated by

$$\begin{aligned} F_{\text{ps}} &= 1 - \prod_{i=1}^s \exp\left(-\frac{|\text{DM}_i|\ell}{N}\right) = 1 - \exp\left(-\sum_{i=1}^s |\text{DM}_i|\frac{\ell}{N}\right) \\ &= 1 - \exp\left(-F_{\text{cr}}\frac{mts\ell}{N}\right) = 1 - \exp\left(-F_{\text{cr}}F_{\text{pc}}\right), \end{aligned}$$

as claimed. □

This proposition does not regard the finding of a pre-image of the inversion target that is different from the exact input used to create the inversion target as being successful. Note also that it does not deal with the situation where the inversion target, rather than the one-way function input, is chosen at random. These different versions of the inversion problem behave sufficiently differently to require separate analyses, if the accuracy aimed for by this paper is to be obtained. A more careful definition of  $|\text{DM}_i|$ , suitable for the inversion problem considered in this work, would have counted only the points that were used as

inputs to the one-way function during the pre-computation, disregarding the ending points. Careful treatment of these technical details, which we do not illustrate fully in the remainder of this paper, can be found in [19].

To utilize the above proposition, we need a way to express the coverage rate in terms of the tradeoff algorithm parameters. Recall from [18, 20] that the number of distinct entries  $|\text{DM}|$  contained in a non-perfect DP matrix satisfies

$$|\text{DM}| = m_{\text{ep}}t, \quad (6)$$

where  $m_{\text{ep}}$  denotes the number of distinct ending points of the DP matrix. The work [20] uses this fact in conjunction with another expression for  $|\text{DM}|$ , found in [19], to obtain the formula

$$m_{\text{ep}} = m_{\text{sp}} \frac{2}{1 + \sqrt{1 + \frac{2m_{\text{sp}}t^2}{N}}}, \quad (7)$$

that relates the number of distinct starting points  $m_{\text{sp}}$  to the number of distinct ending points  $m_{\text{ep}}$  in a normal DP matrix.

Returning to the fuzzy rainbow matrices, let us use  $m_{i-1}$  and  $m_i$  to denote the number of distinct starting points and ending points, respectively, expected in each DP sub-matrix  $\text{DM}_i$ . In particular,  $m_0 = m$  and  $m_s$  are the numbers of distinct starting and ending points, respectively, of the full fuzzy rainbow matrix. We shall refer to each collection of  $m_i$  points as the  $i$ -th *color boundary points* of a fuzzy rainbow matrix, where  $0 \leq i \leq s$ . Adopting the above two facts to our situation, we can state that

$$|\text{DM}_i| = m_i t \quad (8)$$

and

$$m_{i+1} = m_i \frac{2}{1 + \sqrt{1 + \frac{2m_i t^2}{N}}} \quad \text{with} \quad m_0 = m \quad (9)$$

are to be expected at each applicable color index  $i$ . The following closed-form formula for  $m_i$  is easier to utilize than the iterative formula (9).

**Lemma 1.** *When the number of colors  $s$  used in each pre-computation table is large, the number of  $i$ -th color boundary points in a fuzzy rainbow matrix is expected to be*

$$m_i = \frac{2m}{2 + \mathbf{F}_{\text{msc}} \frac{i}{s}},$$

for  $i = 0, 1, \dots, s$ .

*Proof.* The iterative formula (9), written in a series expansion form, is

$$m_{i+1} = m_i \left( 1 - \frac{1}{2} \frac{m_i t^2}{N} \right) + O \left( m_i \left( \frac{m_i t^2}{N} \right)^2 \right).$$

Since the lemma statement assumes  $\frac{m_i t^2}{N} = O\left(\frac{1}{s}\right)$  to be small, we can ignore the big- $O$  part and rewrite this as the difference equation

$$\frac{m_{i+1}}{m} - \frac{m_i}{m} = -\frac{\mathbf{F}_{\text{msc}}}{2s} \left(\frac{m_i}{m}\right)^2.$$

As an application of the Euler method, we can interpret this as the differential equation

$$y' = -\frac{\mathbf{F}_{\text{msc}}}{2s} y^2,$$

with the initial condition  $y(0) = \frac{m_0}{m} = 1$ , and solve for  $y$  to obtain

$$\frac{m_i}{m} = \frac{2}{2 + \mathbf{F}_{\text{msc}} \frac{i}{s}},$$

which is the claimed formula.  $\square$

The coverage rate, at least for the large  $s$  values, follows directly from this lemma.

**Proposition 2.** *When the number of colors  $s$  used in each pre-computation table is large, the coverage rate of a fuzzy rainbow matrix is*

$$\mathbf{F}_{\text{cr}} = \frac{2}{\mathbf{F}_{\text{msc}}} \ln \left(1 + \frac{\mathbf{F}_{\text{msc}}}{2}\right).$$

*Proof.* Combining Lemma 1 and (8), one can check that

$$\mathbf{F}_{\text{cr}} = \frac{1}{mts} \sum_{k=1}^s |\text{DM}_k| = \frac{1}{s} \sum_{k=1}^s \frac{m_k}{m} = \sum_{k=1}^s \frac{2}{2 + \mathbf{F}_{\text{msc}} \frac{k}{s}} \frac{1}{s} = \int_0^1 \frac{2}{2 + \mathbf{F}_{\text{msc}} u} du.$$

Computation of the final definite integral results in what is claimed.  $\square$

The computation done in this proof also gives the partial coverage rate

$$\frac{1}{mts} \sum_{k=i+1}^s |\text{DM}_k| = \frac{1}{s} \sum_{k=i+1}^s \frac{m_k}{m} = \frac{2}{\mathbf{F}_{\text{msc}}} \ln \left(\frac{2 + \mathbf{F}_{\text{msc}}}{2 + \mathbf{F}_{\text{msc}} \frac{i}{s}}\right), \quad (10)$$

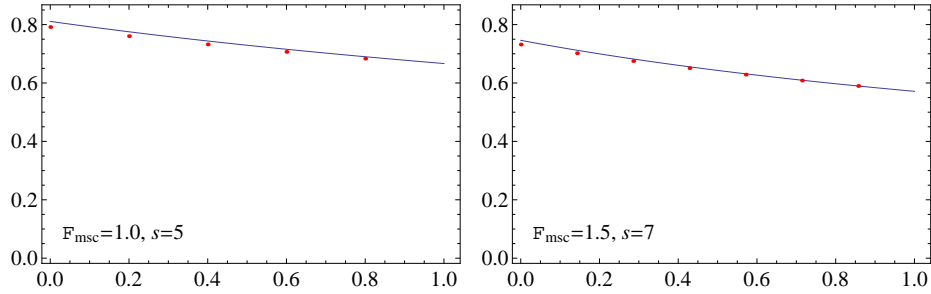
which contains Proposition 2 as the special case of  $i = 0$ .

The arguments given so far supports the validity of formula (10) only for large  $s$  values. There are two sources of inaccuracy, the first being the Euler method used in Lemma 1 and the second being the interpretation of a summation as a definite integral. However, as explained below, one can verify through explicit computations that formula (10) is accurate even when  $s$  is very small.

After rewriting (9) in the form

$$\frac{m_{i+1}}{m} = \frac{m_i}{m} \frac{2}{1 + \sqrt{1 + 2 \frac{\mathbf{F}_{\text{msc}}}{s} \frac{m_i}{m}}} \quad \text{with} \quad \frac{m_0}{m} = 1, \quad (11)$$





**Fig. 1.** Comparisons between closed-form formula (*line*) and iteratively computed values (*dots*) of the partial coverage rate at small  $s$ . ( $x$ -axis:  $\frac{i}{s}$ ;  $y$ -axis:  $\frac{s}{s-i} \sum_{k=i+1}^s \frac{|DM_k|}{mts}$ )

one can iteratively compute all  $\frac{m_i}{m}$ , for any given  $F_{\text{msc}}$  and any  $s$  that is not too large. In Figure 1, we have compared

$$\frac{s}{s-i} \times \frac{1}{s} \sum_{k=i+1}^s \frac{m_k}{m}, \quad (12)$$

with  $\frac{m_k}{m}$  iteratively computed through (11), against the graphs of

$$\frac{s}{s-i} \times \frac{2}{F_{\text{msc}}} \ln \left( \frac{2 + F_{\text{msc}}}{2 + F_{\text{msc}} \frac{i}{s}} \right), \quad (13)$$

at very small  $s$  values. The  $\frac{s}{s-i}$  factor has been multiplied to the partial coverage rates so that all values are close to 1 and they may be gathered within a single figure. The figures testify that Lemma 1, Proposition 2, and formula (10) are accurate even at these very small  $s$  values. Since it will become clear, later in Section 7.3, that the  $s$  values of interest will be somewhat larger than those given by these explicitly computed examples, henceforth, we shall treat Lemma 1, Proposition 2, and formula (10) as being valid for all  $s$  values of interest.

*Remark 1.* Proposition 1 implies that any set of parameters  $m$ ,  $t$ ,  $s$ , and  $\ell$  that achieves the success rate  $F_{\text{ps}}$  must satisfy the relation

$$\frac{\ell}{t} = \frac{F_{\text{pc}}}{F_{\text{msc}}} = \frac{\{-\ln(1 - F_{\text{ps}})\}}{F_{\text{msc}} F_{\text{cr}}}, \quad (14)$$

and Proposition 2 gives the coverage rate  $F_{\text{cr}}$  as a function of the single variable  $F_{\text{msc}}$ . Hence, when parameter sets are restricted to those that achieve a fixed requirement  $F_{\text{ps}}$  on the success rate, the ratio  $\frac{\ell}{t}$  may also be seen as a function of the single variable  $F_{\text{msc}}$ .

*Remark 2.* Recall that we are working with parameters for which  $F_{\text{msc}}$  is of  $\Theta(1)$  order. This fact and Proposition 2 imply that the coverage rate

$$F_{\text{cr}} = 1 - \frac{1}{2} \left( \frac{F_{\text{msc}}}{2} \right) + \frac{1}{3} \left( \frac{F_{\text{msc}}}{2} \right)^2 - \frac{1}{4} \left( \frac{F_{\text{msc}}}{2} \right)^3 + \dots$$

is also of  $\Theta(1)$  order. Hence, unless the success rate requirement  $F_{ps}$  is unrealistically close to 100%, relation (14) implies that  $\ell$  and  $t$  are of similar order.

## 4 Online Complexity

Having secured full knowledge concerning the success rate of the fuzzy rainbow tradeoff, we next discuss the online execution complexities. Our interest lies with the average case complexity, rather than the worst case complexity.

We first write the probability for each pass of the online phase to be executed.

**Lemma 2.** *For any number of colors  $s$  of interest, the probability for the online chains that start from the  $i$ -th colors of the fuzzy rainbow matrices to be generated, i.e., the probability for the DP sub-matrices  $DM_i$  within the fuzzy rainbow matrices to be searched for the correct answer to the inversion problem, is*

$$\left( \frac{2 + F_{\text{msc}} \frac{i}{s}}{2 + F_{\text{msc}}} \right)^{2 \frac{\ell}{t}}.$$

*Proof.* The online chains that start from the  $i$ -th color of any fuzzy rainbow matrix will be generated if and only if the correct answer to the inversion target does not belong to the DP sub-matrices  $DM_{i+1}, \dots, DM_s$  contained in the  $\ell$  fuzzy rainbow matrices. Hence, the probability under consideration is

$$\begin{aligned} \prod_{k=i+1}^s \left( 1 - \frac{|DM_k|}{N} \right)^\ell &= \exp \left( - \frac{\ell}{N} \sum_{k=i+1}^s |DM_k| \right) \\ &= \exp \left( - \frac{\ell}{t} F_{\text{msc}} \sum_{k=i+1}^s \frac{|DM_k|}{mts} \right) = \left( \frac{2 + F_{\text{msc}} \frac{i}{s}}{2 + F_{\text{msc}}} \right)^{2 \frac{\ell}{t}}, \end{aligned}$$

where the final equality follows from (10), which hold true for all  $s$  values of interest.  $\square$

The expected cost of generating the online chains is a direct consequence of this lemma.

**Proposition 3.** *For any number of colors  $s$  of interest, the generation of the online chains during the online phase of a fuzzy rainbow tradeoff is expected to require*

$$t\ell \sum_{i=1}^s (s - i + 1) \left( \frac{2 + F_{\text{msc}} \frac{i}{s}}{2 + F_{\text{msc}}} \right)^{2 \frac{\ell}{t}}$$

*iterations of the one-way function.*

*Proof.* Each of the  $\ell$  online chains that start from the  $i$ -th color of each fuzzy rainbow matrix is expected to require  $(s - i + 1)t$  iterations of the one-way function. The probability for each of these iterations to be executed is given by Lemma 2. The claim is a simple combination of these two observations.  $\square$

Our next objective is to express the cost of dealing with alarms, which is the remaining component of the online time complexity. To compute the cost of resolving alarms associated with an online chain that starts from the  $i$ -th color, the merging of normal single colored DP chains needs to be considered first.

**Lemma 3.** *The probability for two randomly generated DP chains to merge into each other is  $\frac{t^2}{N}$ .*

*Proof.* Assuming  $t \ll \sqrt{N}$ , the probability for the first chain to become a DP chain of length  $i$  is  $(1 - \frac{1}{t})^{i-1} \frac{1}{t}$ . The probability for the second chain to merge into this chain at its  $j$ -th iteration is  $(1 - \frac{1}{t} - \frac{i+1}{N})^{j-1} \frac{i+1}{N}$ . Hence, the probability for two chains to merge can be expressed as

$$\sum_{i=1}^{\infty} (1 - \frac{1}{t})^{i-1} \frac{1}{t} \sum_{j=1}^{\infty} (1 - \frac{1}{t} - \frac{i+1}{N})^{j-1} \frac{i+1}{N}.$$

The two infinite sums here should be understood as expressing the summations up to a sufficiently large chain length bound, so that we have  $\frac{i+1}{N} \ll \frac{1}{t}$  and  $(1 - \frac{1}{t} - \frac{i+1}{N})^{j-1} \approx (1 - \frac{1}{t})^{j-1}$ . The above may now be approximated by

$$\frac{t^2}{N} \int_0^{\infty} \int_0^{\infty} e^{-u} e^{-v} u \, dv \, du = \frac{t^2}{N},$$

and this completes the proof.  $\square$

With the simplifying assumption that the two DP chains are of length  $t$ , the merge probability can be computed more simply as

$$1 - \left(1 - \frac{t}{N}\right)^t = \frac{t^2}{N} - \binom{t}{2} \left(\frac{t}{N}\right)^2 + \dots - (-1)^t \binom{t}{t} \left(\frac{t}{N}\right)^t \approx \frac{t^2}{N}, \quad (15)$$

which is in agreement with the lemma. This approach seems trivial enough to have been previously tried by many researchers. We had treated the chain lengths carefully in the proof, since merge probabilities are higher with longer chains, and it was unclear as to whether this fact could bring about a difference in the final expression for the merge probability, when averaged over all chain lengths.

The merge probability for single colored chains is now used to compute the cost of resolving alarms from the fuzzy rainbow chains.

**Lemma 4.** *Consider a single fuzzy rainbow pre-computation matrix and its associated  $s$  colors. Assume the generation of an online chain for this matrix that starts from the  $i$ -th color. The cost of resolving alarms that may be induced by possible merges of this online chain with the chains of the single fuzzy rainbow matrix is expected to be*

$$t \frac{F_{\text{msc}}}{s} \{i(s - i + 1) + 1\}$$

*iterations of the one-way function.*

*Proof.* The alarms need to be handled separately for each pre-computation chain that merges with the online chain. The resolving of an alarm associated with one pre-computation chain requires the same amount of work regardless of whether or not the pre-computation and online chains merge with other pre-computation chains. Hence, the total cost of resolving alarms is  $m$  times the cost associated with one pre-computation chain. Below, we will focus on the possible merge between the online chain and a single randomly generated pre-computation chain.

If the online chain that starts from the  $i$ -th color merges with a given pre-computation chain, the merge will be at precisely one of the colors  $i, i + 1, \dots, s$ . The case of possible merge at the  $i$ -th color will be treated separately from the possible merge at strictly later colors.

The probability for the  $i$ -th colored DP sub-chain of the pre-computation chain to be of length  $p$  is  $(1 - \frac{1}{t})^{p-1} \frac{1}{t}$ . The probability for the online chain to merge into this DP sub-chain of length  $p$  within its  $i$ -th color DP sub-chain is

$$\sum_{q=1}^{\infty} \left(1 - \frac{1}{t} - \frac{p+1}{N}\right)^{q-1} \frac{p+1}{N} = \frac{p+1}{N} \frac{1}{\frac{1}{t} + \frac{p+1}{N}} \approx \frac{t(p+1)}{N}.$$

To resolve the alarm from such a merge, one must expect to compute  $(i-1)t$  iterations of the one-way function to regenerate the pre-computation chain up to the start of the  $i$ -th colored sub-chain and then additionally compute  $p$  iterations to reach the end of the  $i$ -th colored sub-chain. The only exception is when the correct answer is found, but this is a single rare event among the many alarms, and can be ignored. Hence, the cost of resolving an alarm that may occur due to a possible merge at the  $i$ -th color is

$$\sum_{p=1}^{\infty} \left(1 - \frac{1}{t}\right)^{p-1} \frac{1}{t} \cdot \frac{t(p+1)}{N} \cdot \{(i-1)t + p\},$$

which may be approximated by

$$\frac{t^3}{N} \int_0^{\infty} e^{-u} u \{(i-1) + u\} du = (i+1) \frac{t^3}{N}.$$

For color indices  $j > i$ , we can infer from Lemma 3 that the merge of the two chains at the  $j$ -th color will occur with probability  $(1 - \frac{t^2}{N})^{j-i} \frac{t^2}{N}$ . The combined probability of merge at any one of the colors appearing strictly after the  $i$ -th color is

$$\sum_{j=i+1}^s \left(1 - \frac{t^2}{N}\right)^{j-i} \frac{t^2}{N} = \left(1 - \frac{t^2}{N}\right) \left\{1 - \left(1 - \frac{t^2}{N}\right)^{s-i}\right\} \approx (s-i) \frac{t^2}{N}.$$

The final approximation is true since  $\frac{t^2}{N} \ll 1$ , and the same result would have been obtained if we had simply treated the merge probability at each color to be  $\frac{t^2}{N}$ , regardless of  $j$ . Since any such merge will require just  $it$  iterations of the

one-way function to resolve, the sum of costs associated with possible merges at all colors appearing strictly after the  $i$ -th color is

$$(s - i) \frac{t^2}{\mathbf{N}} \cdot it.$$

The sum of the two computed costs

$$(i + 1) \frac{t^3}{\mathbf{N}} + i(s - i) \frac{t^3}{\mathbf{N}} = \{i(s - i + 1) + 1\} \frac{t^3}{\mathbf{N}}$$

is the cost expected from a single pre-computation chain, and  $m$  times this value is what is claimed.  $\square$

In the case of the DP tradeoff, the cost of resolving alarms can be reduced slightly [18] through the online chain record (OCR) technique [17, 24]. The method is to keep a full record of the online chain during its generation, so that any pre-computation chain regeneration can be stopped at the exact point of merge, rather than at the terminating DP. Some readers may have wondered why the OCR technique is not being applied to the fuzzy rainbow tradeoff. A careful reading of the above proof shows that, for an online chain that starts from the  $i$ -th color, the OCR technique can take effect only if the merge occurs within the  $i$ -th colored sub-chain. This observation indicates that the application of OCR technique to the fuzzy rainbow tradeoff will reduce the number of one-way function iterations, at the inconvenience of more frequent memory accesses, but the reduction will be too small to be of interest, unless a very small  $s$  is in use.

During the online phase, the generation of an online chain that starts from the  $i$ -th color, which the above lemma assumes, is done only if all previous shorter online chains have failed to return the correct answer. The following statement accounts for this in computing the cost of resolving alarms.

**Proposition 4.** *For any number of colors  $s$  of interest, the resolving of alarms during the online phase of a fuzzy rainbow tradeoff is expected to require*

$$t\ell \frac{\mathbf{F}_{\text{msc}}}{s} \sum_{i=1}^s \{i(s - i + 1) + 1\} \left( \frac{2 + \mathbf{F}_{\text{msc}} \frac{i}{s}}{2 + \mathbf{F}_{\text{msc}}} \right)^{2\frac{\ell}{i}}$$

*iterations of the one-way function.*

*Proof.* The probability for the online chains that start from the  $i$ -th colors of the pre-computation matrices to be generated is given by Lemma 2. The cost of alarm treatment expected from each of these online chains is stated by Lemma 4. It now suffices to multiply by  $\ell$  to account for the multiple online chains and sum the product of the mentioned probability and expected work over all color indices.  $\square$

The two components of the online time complexity for the fuzzy rainbow tradeoff have been obtained, and we are ready to state the tradeoff coefficient, which succinctly expresses the online efficiency of a tradeoff algorithm.

**Theorem 1.** For any number of colors  $s$  of interest, the time memory tradeoff curve for the non-perfect table fuzzy rainbow tradeoff is  $TM^2 = F_{tc,s}N^2$ , where the tradeoff coefficient is

$$F_{tc,s} = F_{msc}^2 \left(\frac{\ell}{t}\right)^3 \sum_{i=1}^s \left\{ \left(1 - \frac{i-1}{s}\right) \left(1 + F_{msc} \frac{i}{s}\right) + \frac{F_{msc}}{s^2} \right\} \left(\frac{2 + F_{msc} \frac{i}{s}}{2 + F_{msc}}\right)^{2\frac{\ell}{t}} \frac{1}{s}.$$

*Proof.* The storage complexity of the fuzzy rainbow tradeoff is  $M = m\ell$ , and the time complexity is the sum

$$T = t\ell \sum_{i=1}^s \left\{ (s-i+1) \left(F_{msc} \frac{i}{s} + 1\right) + \frac{F_{msc}}{s} \right\} \left(\frac{2 + F_{msc} \frac{i}{s}}{2 + F_{msc}}\right)^{2\frac{\ell}{t}}$$

of the two terms given by Proposition 3 and Proposition 4. The tradeoff curve is obtained by appropriately combining the two complexities  $M$  and  $T$ . Easy modifications of the formula are needed to arrive at the form of the tradeoff coefficient presented by this theorem.  $\square$

*Remark 3.* Note that the time complexity  $T$ , appearing in the above proof, can be bounded from below by

$$T \geq t\ell \sum_{i=1}^s (s-i+1) \left(\frac{2}{2 + F_{msc}}\right)^{2\frac{\ell}{t}} = t\ell \frac{s(s+1)}{2} \left(\frac{2}{2 + F_{msc}}\right)^{2\frac{\ell}{t}}$$

and bound from above by

$$T \leq t\ell \sum_{i=1}^s \left\{ (s-i+1)(F_{msc} + 1) + \frac{F_{msc}}{s} \right\} = t\ell \left\{ \frac{s(s+1)}{2} (F_{msc} + 1) + F_{msc} \right\}.$$

Since we know from Remark 2 that  $\ell = \Theta(t)$ , the online time complexity  $T$  of the fuzzy rainbow tradeoff must be of  $\Theta(t^2s^2)$  order. In fact, one can similarly verify from Proposition 3 and Proposition 4 that both the online chain creation and alarm resolving consumes  $\Theta(t^2s^2)$  iterations of the one-way function.

As the final result of this section, we state the number of table lookups expected during the online phase. The time required for each table lookup is very implementation dependent. Since, when the pre-computation tables reside in fast memory, the cost of table lookups could be negligible in comparison to the cost of one-way function computations, table lookups are mostly ignored in theoretic analyses of the tradeoff algorithms. The same approach will be taken by this paper and the result below will not be referred to in the rest of this paper. However, in practice, table lookups can become a bottleneck and affect the performance of the algorithms significantly.

**Proposition 5.** For any number of colors  $s$  of interest, the online phase of the fuzzy rainbow tradeoff is expected to call for

$$\ell \sum_{i=1}^s \left(\frac{2 + F_{msc} \frac{i}{s}}{2 + F_{msc}}\right)^{2\frac{\ell}{t}},$$

table lookups.

*Proof.* The probability for the online chains that start from the  $i$ -th colors of the pre-computation matrices to be generated is given by Lemma 2, and every such online chain generation will call for a single table lookup per pre-computation table. Hence, the expected number of lookups can be written as claimed.  $\square$

*Remark 4.* The table lookup count stated by this proposition is upper bounded by  $s\ell$  and lower bounded by  $s\ell\left(\frac{2}{2+F_{\text{msc}}}\right)^{2\frac{\ell}{t}}$ . Referring to Remark 2 one more, we can state that the number of table lookups made by the online phase of the fuzzy rainbow tradeoff is of  $\Theta(ts)$  order.

Later discussions in Section 8 show that  $ts$  for the fuzzy rainbow tradeoff corresponds naturally to  $t$  for the usual rainbow tradeoff, in a manner that is somewhat analogous to how  $mt$  for the classical Hellman tradeoff corresponds to  $m$  for the rainbow tradeoff. Since the usual rainbow tradeoff requires  $\Theta(t\ell) = \Theta(t)$  table lookups [19], the table lookup requirements of the fuzzy rainbow and original rainbow tradeoffs are comparable.

## 5 Storage Optimization

The storage complexity  $M$  appearing in the tradeoff curve of Theorem 1 refers to the total number of entries, i.e., starting and ending point pairs, that are written to the pre-computation tables. In practice, the physical storage size, which depends not only on the number of table entries, but also on how many bits of storage must be allocated to each table entry, will be more important.

Each randomly generated starting point requires  $\log N$  bits of storage to record. However, notice that, as long as we are treating the one-way function as a random function, any set of  $m$  distinct starting points is as good as a set of randomly generated starting points. Hence, one can utilize sequentially generated starting points [5, 11, 12] and record each starting point in  $\log m$  bits, which is usually much smaller than the original  $\log N$  bits.

The issue of recording the ending points effectively is more complicated. There are three major techniques that can be used with various tradeoff algorithms. Slightly more detail than what is explained below can be found in [19, 20].

The first of the three methods is the index file method [11], which is widely used even outside the tradeoff subject. Once a pre-computation table has been sorted according to the ending points, two consecutive ending points in the table are highly likely to share a small number of common significant bits. This predictability of the significant bits can be used to remove almost  $\log m$  bits per table entry, without any loss of information concerning the ending points, when the table contains  $m$  entries. A generalization of this storage technique is widely known by the name of hash tables.

The second method for reducing ending point storage size is applicable only when the ending points are DPs. One simply does not have to record any portion of the ending points that can be recovered from the distinguishing property [11, 25]. This allows removal of  $\log t$  bits from each ending point without any

information loss, when the distinguishing property is of  $\frac{1}{t}$  probability. Clearly, the fuzzy rainbow tradeoff allows application of this technique.

The final technique is to simply truncate the ending points to a certain length before recording them to storage [8, 11]. During the online phase, the terminating DP of an online chain is likewise truncated before being searched for in the pre-computation table. This reduces the storage requirement, but since partial matches of ending points will now be incorrectly announced as collisions, this will cause a new type of false alarms to appear and increase the cost of resolving alarms. In the remainder of this section we work to find the degree of truncation that restricts the side effects of ending point truncation to a negligible fraction of the online time complexity.

Let us assume a fixed truncation method for the ending points with a truncated match probability of  $\frac{1}{r}$ . That is, we assume that the truncated outcome of two independently and randomly chosen ending points, which are a priori DPs, will be identical with probability  $\frac{1}{r}$ . For example, the case of no truncation corresponds to  $\frac{1}{r} = \frac{t}{N}$ . In most cases, the truncated match probability of  $\frac{1}{r}$  can be obtained by retaining just  $\log r$  bits of each ending point, that are unrelated to the distinguishing property. Note that whether the part that can be recovered from the distinguishing property, which contains no entropy, is also retained, does not affect the truncated match probability.

The extra cost incurred by the truncation-related alarms is stated below.

**Proposition 6.** *Assume the use of the ending point truncation method with the truncated match probability set to  $\frac{1}{r}$ . Then, during the online phase of the fuzzy rainbow tradeoff, one can expect to observe*

$$t\ell \frac{m}{r} \sum_{i=1}^s i \left( \frac{2 + F_{\text{msc}} \frac{i}{s}}{2 + F_{\text{msc}}} \right)^{2\frac{\ell}{t}}$$

*extra invocations of the one-way function induced by truncation-related alarms, for any number of colors  $s$  of interest.*

*Proof.* As was argued during the proof of Lemma 4, it suffices to focus on the possible merges between a set of  $s$  online chains starting at different colors and a single pre-computation chain, and later account for multiple pre-computation chains.

We first need to separate the normal alarms from alarms caused by ending point truncations. Consider an online chain that starts from the  $i$ -th color. Through an argument similar to that appearing in the proof of Lemma 4, we can deduce from Lemma 3 that the probability for the online chain *not* to merge into any single fixed pre-computation is  $1 - (s - i + 1) \frac{t^2}{N}$ . Unless  $\frac{1}{r} \approx \frac{t}{N}$ , the probability for the non-merging two chains to bring about a truncated match is  $\frac{1}{r}$ . Hence, the probability for an online chain that starts from the  $i$ -th color to cause a truncation related alarm is

$$\left\{ 1 - (s - i + 1) \frac{t^2}{N} \right\} \frac{1}{r}.$$



Each of these pseudo-alarms will require  $it$  iterations of the one-way function to resolve. Taking the  $\ell m$  pre-computation chains into account and recalling Lemma 2, which gives the probability for an online chain that starts from the  $i$ -th color to be generated, the cost of dealing with truncation-related alarms can be written as

$$\ell m \sum_{i=1}^s it \cdot \left\{ 1 - (s-i+1) \frac{t^2}{N} \right\} \frac{1}{r} \cdot \left( \frac{2 + F_{\text{msc}} \frac{i}{s}}{2 + F_{\text{msc}}} \right)^{2\frac{\ell}{t}}.$$

It now suffices to observe that  $(s-i+1) \frac{t^2}{N} = O(\frac{1}{m})$  to realize that the claimed formula is an accurate approximation.  $\square$

The cost stated by this proposition is upper bounded by

$$t\ell \frac{m}{r} \sum_{i=1}^s i = t\ell \frac{m}{r} \frac{s(s+1)}{2}$$

and lower bounded by

$$t\ell \frac{m}{r} \sum_{i=1}^s i \left( 1 - \frac{t^2 s}{N} \right) \left( \frac{2}{2 + F_{\text{msc}}} \right)^{2\frac{\ell}{t}} \approx t\ell \frac{m}{r} \frac{s(s+1)}{2} \left( \frac{2}{2 + F_{\text{msc}}} \right)^{2\frac{\ell}{t}}.$$

Recalling Remark 2, given at the end of Section 3, we can state that the added cost of dealing with truncation-related alarms is of  $\Theta(t^2 s^2 \frac{m}{r})$  order. In comparison, Remark 3 states that the time complexity  $T$  is of  $\Theta(t^2 s^2)$  order.

The two time complexity orders imply that, if  $\frac{m}{r}$  is a sufficiently small fraction, then the added cost of treating truncation-related alarms will be insignificant in comparison to the time complexity  $T$  for the algorithm that does not employ truncation of ending points. In other words, the side effects of ending point truncation can be ignored if the truncated ending points contain slightly more than  $\log m$  bits of information.

Of course, if the truncated ending points still contain bits that can be recovered from the DP definition they may also be removed without any loss of information. Furthermore, even the remaining effective  $\log m$  bits of the ending points can mostly be removed through the index table method, without any loss of information.

In summary, storage of each starting point of the fuzzy rainbow tradeoff requires  $\log m$  bits and the storage of each ending point requires a very small number  $\varepsilon$  of bits. Each entry of the fuzzy rainbow tradeoff can be recorded in  $\log m + \varepsilon$  bits.

Now that we have seen the detailed effects of the ending point truncation method, we can present an overall interpretation of the inner workings that is easier to understand. The cost of resolving alarms is of  $\Theta(t^2 s^2)$  order (Remark 3) and each alarm induces  $\Theta(ts)$  iterations of the one-way function, on average. Hence, one is expected to encounter  $\Theta(ts)$  alarms during the online phase. Since this is also the approximate number of table lookups expected during the online

phase (Remark 4), one can conclude that each table lookup incurs  $\Theta(1)$  alarm, or merges between an online chain and a pre-computation chain, on average. Hence, as long as slightly more than  $\log m$  bits of each ending point are retained, so that the ending points within any single pre-computation table remain distinguishable from each other and also from the truncated online chain ending point, the number of pseudo-collisions will be kept at a small fraction of the  $\Theta(1)$  order true merges.

## 6 Experimental Results

Test results that support our theoretic findings are given in this section.

The one-way function used during all the tests was the key to ciphertext mapping, under a randomly generated fixed plaintext, of AES-128. Freshly generated random plaintexts were used each time we required a new random mapping for multiple independent tests. Truncations of 128-bit ciphertexts to 40 bits and zero-extensions of 40-bit strings to 128-bit keys were used to control the search space to a manageable size of  $N = 2^{40}$ . The parameter  $t$  was always taken to be an integer power of 2, and the distinguishing property was set to check whether  $\log t$  least significant bits were zero. XOR-ing by constants were used as the reduction functions, with the binary expression of  $i$  used as the  $i$ -th color constant.

Our first experiment verifies Lemma 1. This should give strength to the validity of the partial coverage rate formula (10). After fixing parameters  $m$ ,  $t$ ,  $s$ , and  $N$ , we began the matrix generation with  $m$  starting points. Pre-computation chains were initially generated only up to the first set of DPs, i.e., only the first DP sub-matrix  $DM_1$  was initially generated. After sorting these color boundary DPs, any duplicates were discarded, and the number of remaining set of distinct DPs was recorded. The second DP sub-matrix was then generated from the distinct set of DPs, and the number of second group of color boundary DPs was recorded. The process was continued for  $s$  colors.

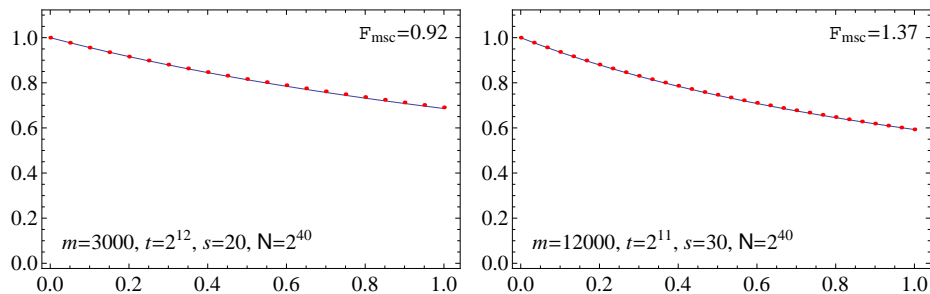
A small number of the chains did not reach a DP within our chain length bound of  $15t$ , at various colors, and were prematurely discarded. A total of ten fuzzy rainbow matrices were generated, and the number of  $i$ -th color boundary points was averaged separately for each  $i$ .

**Table 1.** Number of color boundary points  $\frac{m_i}{m}$  in a fuzzy rainbow matrix for a small  $s$ . ( $m = 2000$ ,  $t = 2^{13}$ ,  $s = 7$ ,  $N = 2^{40}$ )

$i$	0	1	2	3	4	5	6	7
test	1.0000	0.9457	0.8955	0.8494	0.8094	0.7743	0.7419	0.7119
Eq. (11)	1.0000	0.9454	0.8964	0.8521	0.8119	0.7752	0.7416	0.7108
Lemma 1	1.0000	0.9425	0.8912	0.8452	0.8038	0.7662	0.7320	0.7007

Test results for the small  $s = 7$  case is given in Table 1. It is clear that the experimental data is very close to the original theoretic values given by the

iterative formula (11). This justifies our treatment of each DP sub-matrix  $DM_i$  as a normal DP matrix that contains a predictable number of duplicate starting points or chains. The main target of verification, which is the closed-form formula for  $\frac{m_i}{m}$  given by Lemma 1, outputs numeric values that are slightly further away from the experimental data, but the error is by less than 2% at the worst.



**Fig. 2.** Number of color boundary points in a fuzzy rainbow matrix (*line*: theory; *dots*: test; *x*-axis:  $\frac{i}{s}$ ; *y*-axis:  $\frac{m_i}{m}$ )

The test results for more practical values of  $s$  are given in Figure 2. In order to present the larger data set for the larger  $s$  more effectively, we summarized the results as graphs. The lines represent our theory given by Lemma 1 and the dots correspond to the experimental data. Each dot gives the count of the  $i$ -th color boundary points, averaged over ten tests. It is clear that the test results match our theory very well, despite the small number of test repetitions. We may conclude that Lemma 1 predicts the number of  $i$ -th color boundary points quite accurately for  $s$  values of interest and reasonably accurately for even very small values of  $s$ .

Our second experiment is designed to verify our arguments concerning the cost of resolving alarms. There are two main components to this argument. The first component is the probability for the online chains that start from the  $i$ -th color to be generated. This is tightly connected to the partial coverage rate formula (10), which has already been tested indirectly through our first experiment.

The second major component of the alarm cost argument is a technical claim made during the proof of Lemma 4. It concerns the probability of merge between a pre-computation chain and an online chain that starts from the  $i$ -th color. Explicitly, we had stated the combined probability of such merges at any one of the colors appearing strictly after the  $i$ -th color as  $(s - i)\frac{t^2}{N}$ .

The experimental verification of this claim was carried out as follows. Multiple pre-computation chains were generated, and their color boundary DPs were recorded, rather than just their ending points. Since we were treating these chains as individual pre-computation chains, rather than as members of a pre-computation matrix, no sorting was done. After fixing a starting color index  $i$ ,

online chains were generated to the ending points. The first DP of the online chain, i.e., the DP that ends the  $i$ -th colored sub-chain, in addition to the terminating DP, were recorded. For each online chain, we did a linear search over the collection of pre-computation chains for matching ending points. Whenever a collision was found, we compared the first DP of the online chain against the corresponding color boundary DP of the colliding pre-computation chain to check whether the merge occur within the  $i$ -th color sub-chain or strictly after the  $i$ -th color, and occurrences of only the latter type of collisions were counted. Online chains that start at different color indices were tested for merges against a common large collection of pre-computation chains.

Since the matrix stopping rule plays no role in this experiment, we were free to use any large number of pre-computation chains, and test repetitions were not necessary. Two sets of tests, corresponding to different parameter choices, were executed.

**Table 2.** Probability of merge between an online chain that starts from the  $i$ -th color and a pre-computation chain. For each test setting, the number of merges at colors strictly after the  $i$ -th color are listed.

$t = 2^{12}, s = 20, N = 2^{40}, \# \text{ of pre-computation chains} = 500000$							
$i$		1	4	8	12	16	19
# of online chains		26315	31250	41666	62500	125000	500000
# of merges	test	3753142	3763624	3795469	3841206	3847142	3728423
	theory	3814583	3814697	3814636	3814697	3814697	3814697
test/theory		0.9839	0.9866	0.9950	1.0069	1.0085	0.9774

$t = 2^{11}, s = 30, N = 2^{40}, \# \text{ of pre-computation chains} = 500000$							
$i$		1	6	12	18	24	29
# of online chains		17241	20833	27777	41666	83333	500000
# of merges	test	966734	954600	948527	964926	979533	948478
	theory	953653	953659	953648	953659	953671	953674
test/theory		1.0137	1.0010	0.9946	1.0118	1.0271	0.9946

The experimental results are summarized in Table 2. The theoretic merge counts listed in the table were computed by multiplying the number of pre-computation chains and the number of online chains generated for the index  $i$  to the claimed probability  $(s - i) \frac{t^2}{N}$ . Larger number of chains were used when testing shorter online chains, since merges are seen less often with these chains, and a smaller number of merges would bring about unreliable data. The experimentally obtained merge counts for the two sets of tests are close to our theoretic predictions.

## 7 Number of Colors $s$

Before comparing the fuzzy rainbow tradeoff with the usual rainbow tradeoffs, we first need to discuss the effects of the parameter  $s$  on the performance of the fuzzy rainbow tradeoff. That is, we treat the fuzzy rainbow tradeoff as an infinite family of algorithms indexed by the positive integer  $s$ , and compare the performances of these multiple algorithms against each other.

### 7.1 The $F_{pc}$ versus $F_{tc}$ Curve

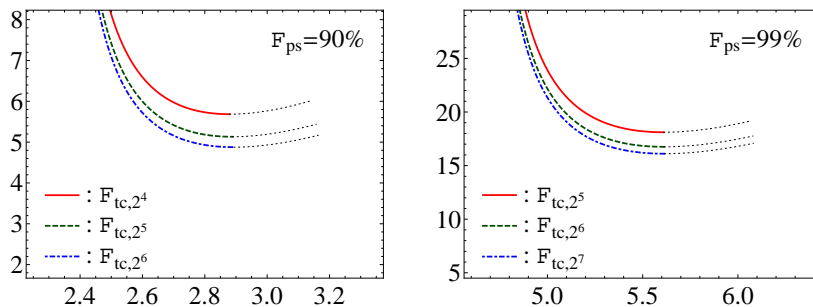
To carry out the performance comparisons as suggested by [19], we need to draw the  $F_{pc}$  versus  $F_{tc,s}$  curves for the fuzzy rainbow tradeoff, under various fixed  $F_{ps}$  and  $s$  values. The analyses given in the previous sections contain all the information required for this task, and let us briefly explain how to utilize this information to explicitly plot the curves.

Recall from Remark 1, given at the end of Section 3, that both the coverage rate  $F_{cr}$  and the ratio  $\frac{\ell}{t}$  may be seen as functions of the single variable  $F_{msc}$ , when parameters are restricted to those that achieve a fixed success rate. Hence, given any fixed  $s$ , we may view both the pre-computation coefficient

$$F_{pc} = \frac{\{-\ln(1 - F_{ps})\}}{F_{cr}} \quad (16)$$

and the tradeoff coefficient  $F_{tc,s}$  of Theorem 1 as functions of the single parameter  $F_{msc}$ , when under a fixed success rate requirement  $F_{ps}$ . Given any  $F_{ps}$  and  $s$ , the  $F_{pc}$  versus  $F_{tc,s}$  curve can be drawn as a curve parameterized by  $F_{msc}$ .

It will become evident in the next subsection that the  $s$  values of interest are in the range  $15 \sim 100$ . Hence, the summation appearing in the formula for  $F_{tc,s}$  does not bring about any practical difficulties in handling of the formulas, for example, in drawing the curves or finding the lowest point on each curve.



**Fig. 3.** The tradeoff coefficients  $F_{tc,s}$  in relation to their respective pre-computation costs, at small  $s$  ( $x$ -axis: pre-computation coefficient;  $y$ -axis: tradeoff coefficient).

Example curves are presented in Figure 3. In each box, the  $x$ -axis gives the pre-computation coefficient  $F_{pc}$  and the  $y$ -axis gives the tradeoff coefficients  $F_{tc,s}$ .

The lower parts in each box correspond to better online efficiency and parts closer to the left edge correspond to smaller pre-computation requirements. An implementer that wishes to utilize optimal online efficiency, at all costs, will choose to work with parameters corresponding to the lowest point of a curve, while an implementer with only modest pre-computation resources will have to be satisfied with a point that is situated higher but closer to the left edge. However, any set of parameters corresponding to dotted thin parts of the curves in Figure 3 will not be used by any reasonable implementer, since they correspond to worse online efficiency at larger pre-computation cost than the lowest point of each curve. These useless parts of the curves will not be plotted in all our later graphs.

It is evident that increasing the  $s$  value brings the  $F_{pc}$  versus  $F_{tc,s}$  curve closer to the bottom left corner, which might roughly be interpreted as being more desirable. However, as will be explained in the next subsection, this observation alone should not be used to draw any premature conclusions.

To compute a point on one of the curves of Figure 3, i.e., to position a single  $(F_{pc}, F_{tc})$ -pair, it suffices to fix  $F_{ps}$ ,  $s$ , and  $F_{msc}$  to specific values. Since there are four algorithm parameters, namely,  $m$ ,  $t$ ,  $s$ , and  $\ell$ , that can be varied in instantiating the fuzzy rainbow tradeoff, there still remains a single degree of freedom in the choice of parameters, even with the three restrictions. Specifically, one can verify that, given any  $F_{ps}$ ,  $s$ , and  $F_{msc}$ , and a  $(T, M)$ -pair satisfying  $TM^2 = F_{tc,s}N^2$ , where  $F_{tc,s}$  is computed from  $s$  and  $F_{msc}$  through Theorem 1, the parameters

$$m = \frac{F_{msc} F_{cr}^2 s}{\{\ln(1 - F_{ps})\}^2 N} \frac{M^2}{N} = \frac{F_{msc} F_{cr}^2 F_{tc,s} s N}{\{\ln(1 - F_{ps})\}^2 T}, \quad (17)$$

$$t = \frac{\{-\ln(1 - F_{ps})\} N}{F_{cr} s} \frac{N}{M} = \frac{\{-\ln(1 - F_{ps})\}}{F_{cr} \sqrt{F_{tc,s}} s} \sqrt{T}, \quad (18)$$

$$\ell = \frac{\{\ln(1 - F_{ps})\}^2 N}{F_{msc} F_{cr}^2 s} \frac{N}{M} = \frac{\{\ln(1 - F_{ps})\}^2}{F_{msc} F_{cr}^2 \sqrt{F_{tc,s}} s} \sqrt{T}, \quad (19)$$

together with the supplied  $s$ , will give an instantiation of the fuzzy rainbow tradeoff that corresponds to online time  $T$  and storage  $M$ , while satisfying the supplied restrictions on  $F_{ps}$  and  $F_{msc}$ .

In other words, the tradeoff between time  $T$  and storage  $M$  is still fully available even after one commits to using parameters corresponding to any specific point on a  $F_{pc}$  versus  $F_{tc}$  curve. An implementer that chooses a point on one of the curves is only choosing the appropriate balance between pre-computation cost and online efficiency, and is not relinquishing the ability to tradeoff  $T$  and  $M$  against each other. The only restriction the implementer is accepting by fixing the  $(F_{pc}, F_{tc})$ -pair to a specific  $(\alpha, \beta)$ -pair is that the pre-computation cost will be  $\alpha N$  and that the choice of online resources  $T$  and  $M$  will be constrained to the specific tradeoff relation  $TM^2 = \beta N^2$ .

## 7.2 Performance Comparisons at Different Number of Colors $s$

Let us explain how to compare the performances of the fuzzy rainbow tradeoffs running with different  $s$  values.

Consider a fuzzy rainbow tradeoff implementer that is working with a certain fixed number of colors  $s = s_1$ . Suppose that a set of parameters  $m = m_1$ ,  $t = t_1$ , and  $\ell = \ell_1$ , achieving all properties desired by the implementer, has been found. These parameters need not be optimal in any particular sense. We are only assuming that the desired success rate is met and that the balance between resource requirements, such as the pre-computation cost, physical storage size, and expected online time, is suitable for the intended purpose and environment. The implementer is willing to further tweak the parameters slightly, but prefers not to make large changes to  $\log m_1$ ,  $\log t_1$ , and  $\log \ell_1$ , that would destroy the favorable balance between pre-computation cost, storage size, and online time.

The implementer still wishes to explore the possibility of using a different  $s$  values, as long as the three resource requirements remain largely unchanged. Consider another  $s$  value  $s_2$  and the associated second set of parameters

$$m_2 = \frac{s_2}{s_1}m_1, \quad t_2 = \frac{s_1}{s_2}t_1, \quad \text{and} \quad \ell_2 = \frac{s_1}{s_2}\ell_1. \quad (20)$$

It may be easier to read the material that follows below with the simple example  $m_2 = 2m_1$ ,  $t_2 = \frac{1}{2}t_1$ ,  $s_2 = 2s_1$ , and  $\ell_2 = \frac{1}{2}\ell_1$ , in mind.

Let us explain that the new set of parameters will be acceptable for consideration by the above mentioned implementer. We can check that the pre-computation coefficients

$$F_{\text{pc}} = \frac{m_1 t_1 s_1 \ell_1}{N} = \frac{m_2 t_2 s_2 \ell_2}{N} \quad (21)$$

for the two parameter sets are identical, and

$$F_{\text{msc}} = \frac{m_1 t_1^2 s_1}{N} = \frac{m_2 t_2^2 s_2}{N} \quad (22)$$

implies that the coverage rates  $F_{\text{cr}}$  (Proposition 2) and success rates  $F_{\text{ps}}$  (Proposition 1) will also be identical.

As for the online time complexity  $T$ , since it is of  $\Theta(t^2 s^2)$  order (Remark 3), the observation  $t_1 s_1 = t_2 s_2$  implies that the online time complexities associated with the two sets of parameters will be similar.

It remains to consider the storage size required by the two parameter sets. The total number of pre-computation table entries  $M = m_1 \ell_1 = m_2 \ell_2$  for the two parameter sets are the same, and we had stated at the end of Section 5 that  $\log m + \varepsilon$  bits of storage are required per fuzzy rainbow table entry. With the new symbol  $m_0 = \frac{m_1}{s_1}$ , which allows us to write  $m_1 = m_0 s_1$  and  $m_2 = m_0 s_2$  in a more uniform manner, we can state the physical storage size called for by the two parameter sets as

$$(\log m_1 + \varepsilon)M = (\log m_0 + \varepsilon + \log s_1)M \quad (23)$$

and

$$(\log m_2 + \varepsilon)M = (\log m_0 + \varepsilon + \log s_2)M. \quad (24)$$

Here, we are assuming  $\varepsilon = \varepsilon_1 = \varepsilon_2$ , since the choice of  $\varepsilon$ , which corresponds to the ending point portion that remains after applications of the truncation and index file techniques, is somewhat independent of the choices made for other parameters. As an example, when  $s_2 = 2s_1$ , the physical storage sizes will be  $(\log m_1 + \varepsilon)M$  and  $(\log m_1 + \varepsilon + 1)M$ . Thus, we have confirmed that the physical storage requirements of the two sets of parameters are similar for any modest change in  $s$ .

Now that we have confirmed the two sets of parameters to be requiring similar resources, let us continue with the actual comparison of the algorithm performances corresponding to the two parameter sets. We have already confirmed that the probability of success and pre-computation cost are exactly matching for the two sets of parameters. Hence, it suffices to compare the online time and physical storage size requirements of the two options, which we denote by

$$T_1 = \mathbf{F}_{\text{tc},s_1} \frac{N^2}{M^2}, \quad M_1 = (\log m_0 + \varepsilon + \log s_1)M \quad (25)$$

and

$$T_2 = \mathbf{F}_{\text{tc},s_2} \frac{N^2}{M^2}, \quad M_2 = (\log m_0 + \varepsilon + \log s_2)M. \quad (26)$$

Note that the preferences between options (25) and (26) would be different for different implementers if, for example, we had  $T_1 > T_2$  and  $M_1 < M_2$ . In order to compare the two options in an objective manner, we employ the ability of the tradeoff algorithm to make tradeoffs between time and storage, even when  $\mathbf{F}_{\text{ps}}$ ,  $s$ , and  $\mathbf{F}_{\text{msc}}$  are fixed, as was discussed at the end of the previous subsection. Since the ratio of online time complexities is  $\frac{T_2}{T_1} = \frac{\mathbf{F}_{\text{tc},s_2}}{\mathbf{F}_{\text{tc},s_1}}$ , by slightly tweaking the second set of parameters to a third set of parameters  $m = m_3$ ,  $t = t_3$ , and  $\ell = \ell_3$ , we can design for online time and physical storage size complexities

$$T_3 = T_1, \quad M_3 = (\log m_0 + \varepsilon + \log s_2)M \left( \frac{\mathbf{F}_{\text{tc},s_2}}{\mathbf{F}_{\text{tc},s_1}} \right)^{\frac{1}{2}}, \quad (27)$$

while still using  $s = s_2$  and maintaining both the probability of success and pre-computation cost constant. One minor detail to note is that, the change from  $m_2$  to  $m_3$  necessitates a corresponding change to the  $(\log m_0 + \varepsilon + \log s_2)$  factor appearing above, but  $T_1 \approx T_2$  implies that the change to parameter  $m$  will be very small, so that the even smaller change to the logarithm scale factor will be ignorable.

The original set of parameters that uses  $s = s_1$  requires online resources stated by (25). In comparison, there is a set of parameters for  $s = s_2$  that achieves the same success rate, requires the same amount of pre-computation, and requires online resources stated by (27). Since we have  $T_1 = T_3$ , the comparison of the two fuzzy rainbow tradeoffs running with  $s = s_1$  and  $s = s_2$  can



be done by directly comparing  $M_1$  with  $M_3$ , or, equivalently, by comparing the *adjusted* tradeoff coefficients

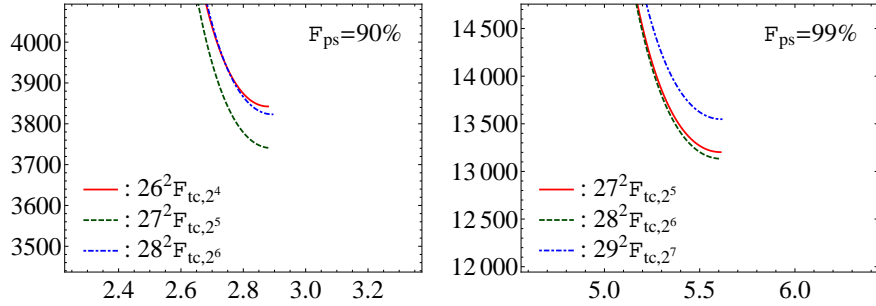
$$(\log m_0 + \varepsilon + \log s_1)^2 \mathbf{F}_{\text{tc},s_1} \quad \text{and} \quad (\log m_0 + \varepsilon + \log s_2)^2 \mathbf{F}_{\text{tc},s_2}, \quad (28)$$

against each other.

More generally, to find the optimal value of  $s$  and other parameters, the implementer can plot the  $\mathbf{F}_{\text{pc}}$  versus  $(\log m_0 + \varepsilon + \log s)^2 \mathbf{F}_{\text{tc},s}$  curves, for all the  $s$  values of interest, and choose a point on one of the curves that corresponds to the implementer's most favored balance of pre-computation cost and online efficiency.

### 7.3 Optimal Number of Colors $s$

Let us plot the curves suggested in the previous subsection for some specific situations. Suppose that a certain set of parameters, achieving an intended success rate of  $\mathbf{F}_{\text{ps}} = 90\%$  and appropriate for the resources available to a tradeoff implementer, is such that  $\log m + \varepsilon = 26$ , when  $s = 2^4$  is used. In the notation used in the previous subsection, this situation is expressed by  $\log m_0 + \varepsilon = 22$ .



**Fig. 4.** The adjusted tradeoff coefficients  $\{\log(m_0 s) + \varepsilon\}^2 \mathbf{F}_{\text{tc},s}$  in relation to pre-computation costs, when  $\log m_0 + \varepsilon = 22$  ( $x$ -axis: pre-computation coefficient;  $y$ -axis: adjusted tradeoff coefficient).

To find the optimal value of  $s$  for this situation, one must plot the  $\mathbf{F}_{\text{pc}}$  versus  $(22 + \log s)^2 \mathbf{F}_{\text{tc},s}$  curves for various  $s$  values. The left-hand side box of Figure 4 presents such curves for the  $s$  values of  $2^4$ ,  $2^5$ , and  $2^6$ , at  $\mathbf{F}_{\text{ps}} = 90\%$ . The switch from  $s = 2^4$  to  $s = 2^5$  moves the curve in the direction previously observed in Figure 3, but the transition from  $s = 2^5$  to  $s = 2^6$  results in a different behavior, that corresponds to a worsening of performance. The choice of  $s = 2^5$  is seen to be optimal, at least among the powers of 2, for this situation.

The optimal choice of  $s$  certainly would have been different if we had started from a different  $\log m_0 + \varepsilon$  value. The difference between the two boxes of Figure 4 indicates that the optimal choice of  $s$  also depends on the success rate requirement  $\mathbf{F}_{\text{ps}}$ .

We now wish to work with arbitrary integer values of  $s$  and explicitly list the optimal value of  $s$ , for a wide range of situations. The definition of  $s$  being optimal must first be made clearer. It can be observed from the curves of Figure 4 that a curve that is generally lower than another curve has a lower lowest point. This vague claim cannot be written as a precise statement, since two curves may intersect each other and both be lower than the other at different parts of the curves. Nevertheless, the example curves of Figure 4 show that we would lose very little by choosing the curve or  $s$  to use, based on the lowest point of the curves. That is, for each choice of  $F_{\text{ps}}$  and  $\log m_0 + \varepsilon$ , we define an  $s$  to be optimal, if it minimizes

$$\min_{F_{\text{msc}}} \left\{ \{\log(m_0 s) + \varepsilon\}^2 F_{\text{tc},s} \right\}, \quad (29)$$

i.e., the minimum value of the adjusted tradeoff coefficient.

**Table 3.** The optimal number of colors  $s$  at various success probabilities and  $\log m_0 + \varepsilon$ .

$\log m_0 + \varepsilon$	25%	50%	75%	90%	95%	99%	99.5%	99.9%
18	15	17	20	26	30	40	45	56
19	15	18	21	27	31	42	47	59
20	16	18	22	28	33	44	49	62
21	17	19	23	29	34	46	51	64
22	17	20	24	31	35	48	53	67
23	18	21	25	32	37	50	55	69
24	19	21	26	33	38	51	57	72
25	19	22	27	34	40	53	59	74
26	20	23	28	35	41	55	61	77
27	21	24	29	36	42	57	63	79
28	21	25	30	38	44	59	65	82
29	22	25	31	39	45	60	67	84
30	23	26	32	40	46	62	69	87
31	23	27	33	41	48	64	72	89
32	24	28	34	42	49	66	74	92
33	25	28	35	43	50	68	76	94
34	25	29	36	45	52	70	78	97
35	26	30	37	46	53	71	80	99

Table 3 lists the optimal number of colors  $s$  to be used, for a small number of fixed success rate requirements  $F_{\text{ps}}$  and a range of  $\log m_0 + \varepsilon$  values. Since even the raw tradeoff coefficient  $F_{\text{tc},s}$  does depend on  $s$ , the  $F_{\text{msc}}$  value giving the lowest point on each curve needs to be computed separately for each  $s$ , but can still be obtained easily enough through numeric computations tools.

According to Table 3, the use of  $s = 31$  is optimal for the  $F_{\text{ps}} = 90\%$  and  $\log m_0 + \varepsilon = 22$  situation. Our previous suggestion to use  $s = 2^5$ , that was made after consulting the left-hand box of Figure 4, was quite reasonable. The

table also states  $s = 48$  to be optimal for the  $F_{ps} = 99\%$  and  $\log m_0 + \varepsilon = 22$  situation. Our previous suggestion to use  $s = 2^6$  was somewhat large, but since  $2^5 < 48 < 2^6$  and the curves for  $s = 2^5$  and  $s = 2^6$  in the right-hand side box of Figure 4 are very close to each other, this is not surprising and we are not experiencing any contradiction.

The overall observation we can make is that small  $s$  values are optimal when under low success rate requirements and when the storage resources are small, and that large  $s$  values are optimal when working with the opposite environment.

## 8 Comparison of Tradeoff Algorithms

Let us follow the framework of [19] in comparing the fuzzy rainbow tradeoff algorithm against the usual rainbow tradeoff algorithm. That is, we present the pre-computation coefficient versus tradeoff coefficient curves for the non-perfect fuzzy rainbow, perfect rainbow, and non-perfect rainbow tradeoffs at several fixed success rate requirements. Since the tradeoff coefficient is a good measure of the resources required during the online phase, the curves present the range of options made available by each algorithm concerning the degree of online efficiency that can be achieved after the investment of certain amount of pre-computation effort. The perfect and non-perfect rainbow tradeoffs were chosen as the comparison targets, because the two were shown by recent works [19, 20] to be the most competitive algorithms among the five major tradeoff algorithms, under typical conditions.

Instructions for plotting the  $F_{pc}$  versus  $F_{tc,s}$  curves for the fuzzy rainbow tradeoff were given in Section 7.1, and the corresponding information for the comparison target algorithms can be found in [19, 20].

To compare the fuzzy rainbow tradeoff directly with the perfect and non-perfect rainbow tradeoffs, we need to find the appropriate adjustment factors to be multiplied to the tradeoff coefficients, and this starts with a discussion of the fuzzy rainbow tradeoff parameters  $m_F$ ,  $t_F$ ,  $\ell_F$ , and  $s$  that would make the resource requirements of the algorithm comparable to those of the perfect or non-perfect rainbow tradeoffs running under parameters  $m_R$ ,  $t_R$ , and  $\ell_R$ .

We had mentioned in Remark 3 that the online time for the fuzzy rainbow tradeoff is of  $\Theta(t_F^2 s^2)$  order and we know that the online time for the usual rainbow tradeoff is of  $\Theta(t_R^2)$  order. Equating the very rough time and storage complexities of the two algorithms and using the facts  $\ell_F \approx t_F$  (Remark 2) and  $\ell_R \approx 1$ , we see that one must require

$$t_F^2 s^2 \approx t_R^2 \quad \text{and} \quad m_F t_F \approx m_F \ell_F \approx m_R \ell_R \approx m_R. \quad (30)$$

These should be taken as extremely rough requirements, but the logarithm scale relations

$$\log t_F + \log s \approx \log t_R \quad \text{and} \quad \log m_F + \log t_F \approx \log m_R \quad (31)$$

are somewhat reasonably accurate requirements one should adhere to, if the two algorithms are to be using similar resources.

Recall from [19, 20] that each pre-computation table entry of both the perfect and non-perfect rainbow tradeoffs consumes  $\log m_R + \varepsilon_R$  bits of storage, where  $\varepsilon_R$  is a small positive integer. We have already seen in Section 5 that the fuzzy rainbow tradeoff similarly consumes  $\log m_F + \varepsilon_F$  bits of storage per table entry.

Our interest lies in the ratio of bits required per table entry, and the use of (31) implies

$$\frac{\log m_F + \varepsilon_F}{\log m_R + \varepsilon_R} \approx \frac{\log m_R - \log t_R + \log s + \varepsilon_F}{\log m_R + \varepsilon_R} \approx \frac{\frac{1}{3} \log N + \log s + \varepsilon_F}{\frac{2}{3} \log N + \varepsilon_R}, \quad (32)$$

where the second approximation is for the parameter set  $m_R = N^{\frac{2}{3}}$  and  $t_R = N^{\frac{1}{3}}$  that is typically considered during theoretic analyses of tradeoff algorithms. In the extreme, by ignoring the small integers  $\varepsilon_F$  and  $\varepsilon_R$ , and also assuming  $s$  to be small, one might argue that this ratio could be as small as  $\frac{1}{2}$ , at the theoretically typical parameters. However, this is a rather optimistic figure that is biased in favor of the fuzzy rainbow tradeoff.

Let us briefly work with some specific numbers. The first example we consider is the very large search space of  $\log N = 75$ , for which pre-computation could be barely within reach by very large organizations. We assume  $\varepsilon_R \approx \varepsilon_F \approx 8$  bits are used to record the ending point portions that remain after applications of the truncation and index file methods. When  $\log N = 75$ , the rainbow tradeoff parameter set that is typically considered during theoretic treatments of the tradeoff technique is

$$\log m_R = 50 \quad \text{and} \quad \log t_R = 25. \quad (33)$$

According to (31), the parameter set for the fuzzy rainbow tradeoff that calls for comparable resources would satisfy

$$\log m_F - \log s \approx \log m_R - \log t_R = 25. \quad (34)$$

That is, we must take  $\log m_0 \approx 25$ , in the notation of Section 7.2. The row labeled as  $\log m_0 + \varepsilon_F = 33$  in Table 3 state  $s = 68$  as the optimal choice, when  $F_{ps} = 99\%$  is required. The ratio of bits per table entry is

$$\frac{\log m_F + \varepsilon_F}{\log m_R + \varepsilon_R} \approx \frac{25 + \log 68 + 8}{50 + 8} \approx 0.673922. \quad (35)$$

Arguments similar to those made in Section 7.2 imply that, if one's favored balance of resources corresponds to rainbow tradeoff parameters of (33), one must compare the adjusted tradeoff coefficient  $0.67^2 F_{tc,68} = 0.45 F_{tc,68}$  against the rainbow tradeoff coefficients  $R_{tc}$  (non-perfect) and  $\bar{R}_{tc}$  (perfect). Similar treatment of other success rates can be done, and the bottom row of Table 4 lists the adjusted tradeoff coefficients for the fuzzy rainbow tradeoff that would be appropriate for comparisons against  $R_{tc}$  and  $\bar{R}_{tc}$ , when theoretically typical parameters for space size  $\log N = 75$  are considered.

**Table 4.** The adjusted tradeoff coefficients for the fuzzy rainbow tradeoff that are appropriate for direct comparison against the usual rainbow tradeoff coefficients, assuming the use of theoretically typical rainbow tradeoff parameters.

$\log N$	25%	50%	75%	90%	95%	99%
39	$0.54 F_{tc,17}$	$0.55 F_{tc,19}$	$0.56 F_{tc,23}$	$0.58 F_{tc,29}$	$0.59 F_{tc,34}$	$0.61 F_{tc,46}$
75	$0.42 F_{tc,25}$	$0.42 F_{tc,28}$	$0.43 F_{tc,35}$	$0.44 F_{tc,43}$	$0.44 F_{tc,50}$	$0.45 F_{tc,68}$

The second example we consider is at the other extreme, and is the small search space size of  $\log N = 39$ . Direct exhaustive search might even be reasonable for such small spaces. For this space size, the rainbow tradeoff parameters  $\log m_R = 26$  and  $\log t_R = 13$  are theoretically typical, and if we assume  $\varepsilon_R \approx \varepsilon_F \approx 8$ , as in the previous example, we must accept

$$\log m_0 + \varepsilon_F \approx \log m_R - \log t_R + \varepsilon_R = 26 - 13 + 8 = 21. \quad (36)$$

Table 3 shows that the use of  $s = 46$  is optimal for the 99% success rate, in which case, the ratio of bits per table entry becomes

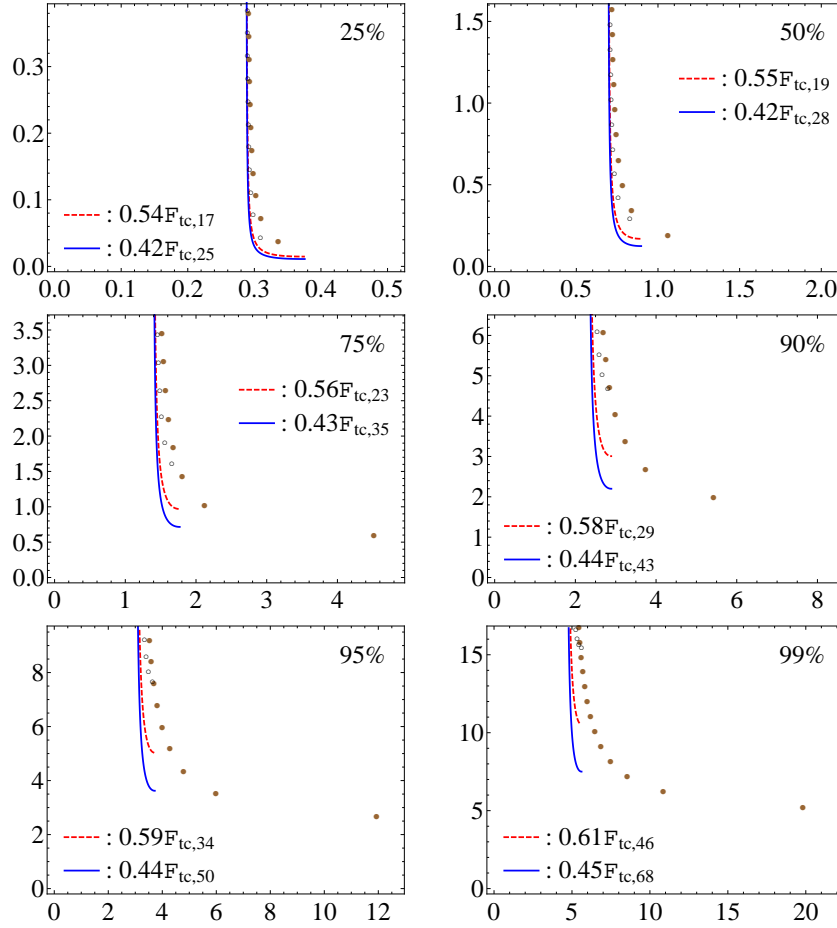
$$\frac{\log m_F + \varepsilon_F}{\log m_R + \varepsilon_R} \approx \frac{13 + \log 46 + 8}{26 + 8} \approx 0.780105. \quad (37)$$

A fair comparison would let  $0.78^2 F_{tc,46} = 0.61 F_{tc,46}$  compete against  $R_{tc}$  and  $\bar{R}_{tc}$ . Similar computations for other success rates can be done, and the outcomes are summarized in Table 4.

Different adjustment factors for  $F_{tc,s}$  will need to be used, depending on the success rate requirement and rough range of online resources that are appropriate for the situation in hand. However, we will somewhat arbitrarily choose to compare the two choices listed in Table 4, for each success rate, against  $R_{tc}$  and  $\bar{R}_{tc}$ . It seems reasonable to believe that our two choices represent the extreme situations that can be experienced during practical applications of the fuzzy rainbow tradeoff.

We clearly state that there could be situations that call for a tradeoff coefficient adjustment factor that is much larger than the ones we will be using, in which case, the conclusions made below could be completely different. The appropriate adjustment factor depends not only on the externally given implementation environment, but also on the taste of the implementer concerning the balance between online efficiency and pre-computation cost, so that the adjustment factor cannot be fixed in an objective manner. In any case, the discussions given above and to be given below can easily be adjusted to work for any specific situation.

The pre-computation coefficient versus (adjusted) tradeoff coefficient curves for the two usual rainbow tradeoffs and the fuzzy rainbow tradeoff are given in Figure 5. Each box presents data corresponding to the success rate requirement indicated at its upper right corner. The curves for the fuzzy rainbow tradeoffs are given as the solid and dashed lines. The data for the perfect rainbow tradeoff



**Fig. 5.** The rainbow tradeoff coefficients ( $\mathbb{R}_{tc}$ : empty circles;  $\bar{\mathbb{R}}_{tc}$ : filled dots) and the adjusted fuzzy rainbow tradeoff coefficients, in relation to their respective pre-computation costs, at various success rates ( $x$ -axis: pre-computation coefficient;  $y$ -axis: (adjusted) tradeoff coefficient).

(filled dots) and non-perfect rainbow tradeoff (empty circles) appear as discrete set of points, due to their use of small number of pre-computation tables. The curves for the fuzzy rainbow tradeoff have been terminated at their lowest points. Each box includes the lowest point for the two usual rainbow tradeoffs and no meaningful rainbow tradeoff point lies hidden beyond the right edge of each box.

In all the boxes the two curves for the fuzzy rainbow tradeoff are situated closer to the lower left corner than the data points for the two rainbow tradeoffs. Thus a very rough conclusion would be that the fuzzy rainbow tradeoff is better in performance than the perfect and non-perfect rainbow tradeoffs.

At the 75% and higher success rates, the lowest dot for the perfect rainbow curve is situated lower than the lowest point of the two fuzzy rainbow tradeoff curves. This shows that the perfect rainbow tradeoff is able to provide better online efficiency than the fuzzy rainbow tradeoff at moderate to high success rates. That is, no choice of fuzzy rainbow tradeoff parameters will make its online efficiency better than the optimal efficiency reachable with the perfect rainbow tradeoff. Hence, the perfect rainbow tradeoff can be advantageous over the fuzzy rainbow tradeoff when the success rate requirement is high and the online efficiency is important.

However, it must be understood that the higher online efficiency option of the perfect rainbow tradeoff can be utilized only if it is paid for with higher pre-computation cost. Since the pre-computation cost is the largest barrier in any large scale deployment of the tradeoff technique, the higher pre-computation cost cannot be ignored. At the high success rates, the decision as to whether the fuzzy rainbow or the perfect rainbow tradeoff is better will be different depending on how costly the additional pre-computation will be, relative to the value of better online efficiency, to the implementer.

At the low success rates 25% and 50%, the lowest point of the fuzzy rainbow curve is lower than the lowest point of the two original rainbow tradeoffs. For these low success rates, fuzzy rainbow tradeoff is always advantageous over the two original rainbow tradeoffs in terms of both the online efficiency and pre-computation cost.

At all success rates, for online efficiency levels that can be reached by both the usual rainbow and fuzzy rainbow tradeoffs, it is always the case that the fuzzy rainbow tradeoff can provide the common online efficiency at a lower pre-computation cost.

Finally, a pass through all six boxes, with focus on the empty circles, reveals that the performance of the non-perfect rainbow tradeoff is always inferior to that of the fuzzy rainbow tradeoff. Any degree of online efficiency that can be provided by the non-perfect rainbow tradeoff can always be obtained with the fuzzy rainbow tradeoff at even lower pre-computation cost.

## 9 Conclusion

The online execution behavior of the non-perfect table fuzzy rainbow tradeoff was analyzed in this work. The success rate, the accurate average case online exe-

cution time that accounts for false alarms, and the physical storage size required to hold the pre-computation tables have all been obtained.

The information obtained through our analyses was used to compare the fuzzy rainbow tradeoff against the original rainbow tradeoff algorithm, which is widely believed to be the best tradeoff algorithm. The tradeoff coefficient adjustment factor and the color count  $s$  per table had to be fixed to somewhat arbitrary values for the comparison. However, our choices were based on figures obtained from reasonable examples, and the ensuing conclusions should be valid for the most part of the practical parameter range. Furthermore, the process can be repeated easily for any other choices, should there be the need to work with a drastically different range of parameters.

We discovered that the fuzzy rainbow tradeoff is always advantageous over the non-perfect rainbow tradeoff. The fuzzy rainbow tradeoff also outperforms the perfect rainbow tradeoff at low success rate requirements. For high success rate requirements, the situation is less conclusive. It is possible for the perfect rainbow tradeoff to provide online efficiency that cannot be reached by the fuzzy rainbow tradeoff, but the advantage must be paid for with higher pre-computation cost. For efficiency levels that are reachable by both algorithms, the fuzzy rainbow tradeoff required less pre-computation.

It remains to analyze the perfect table version of the fuzzy rainbow tradeoff. The good performance of the non-perfect table fuzzy rainbow tradeoff witnessed through this work is an optimistic sign. On the other hand, the relatively poor performance of the perfect table DP tradeoff [20] could be interpreted as a negative indication.

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<sup>2</sup> On p.100, credit is given to Rivest for suggesting to apply the notion of distinguished points to the classical Hellman tradeoff.