# Modular Hardware Architecture for Somewhat Homomorphic Function Evaluation 

Sujoy Sinha Roy ${ }^{1}$, Kimmo Järvinen ${ }^{1}$, Frederik Vercauteren ${ }^{1}$, Vassil Dimitrov ${ }^{2}$, and Ingrid Verbauwhede ${ }^{1}$<br>${ }^{1}$ KU Leuven ESAT/COSIC and iMinds<br>Kasteelpark Arenberg 10, Bus 2452, B-3001 Leuven-Heverlee, Belgium<br>firstname.lastname@esat.kuleuven.be<br>${ }^{2}$ The University of Calgary, Canada and Computer Modelling Group, Ltd. 2500 University Dr. NW, Calgary, AB, Canada, T2N 1N4


#### Abstract

We present a hardware architecture for all building blocks required in polynomial ring based fully homomorphic schemes and use it to instantiate the somewhat homomorphic encryption scheme YASHE. Our implementation is the first FPGA implementation that is designed for evaluating functions on homomorphically encrypted data (up to a certain multiplicative depth) and we illustrate this capability by evaluating the SIMON-64/128 block cipher in the encrypted domain. Our implementation provides a fast polynomial operations unit using CRT and NTT for multiplication combined with an optimized memory access scheme; a fast Barrett like polynomial reduction method; an efficient divide and round unit required in the multiplication of ciphertexts and an efficient CRT unit. These building blocks are integrated in an instruction-set coprocessor to execute YASHE, which can be controlled by a computer for evaluating arbitrary functions (up to the multiplicative depth 44 and 128 -bit security level). Our architecture was compiled for a single Virtex7 XC7V1140T FPGA, where it consumes $23 \%$ of registers, $53 \%$ of LUTs, $53 \%$ of DSP slices, and $38 \%$ of BlockRAM memory. The implementation evaluates SIMON-64/128 in approximately 171.3 s (at 143 MHz ) and it processes 2048 ciphertexts at once giving a relative time of only 83.6 ms per block. This is 24.5 times faster than the leading software implementation on a 4 -core Intel Core-i 7 processor running at 3.4 GHz .


Keywords. Fully homomorphic encryption, YASHE, FPGA, NTT, CRT

## 1 Introduction

The concept of fully homomorphic encryption (FHE) was introduced by Rivest, Adleman, and Dertouzos [34] already in 1978 and allows evaluating arbitrary functions on encrypted data. Constructing FHE schemes proved to be a difficult problem that remained unsolved until 2009 when Gentry [22] proposed

[^0]the first FHE scheme by using ideal lattices. Despite its groundbreaking nature, Gentry's proposal did not provide a practical solution because of its low performance. Since then, many researchers have followed the blueprints set out by Gentry's proposal with an objective to improve the performance of FHE [6, $7,14,17,20,24,25,32]$. Most schemes are either based on (ring) learning with errors ((R)LWE) or $N$-th degree truncated polynomial ring (NTRU) and thus manipulate elements in modular polynomial rings, or on the approximate greatest common divisor (GCD) problem which manipulates very large integers. In this paper, we focus on the former category. Although major advances have been made, we are still lacking FHE schemes with performance levels that would allow large-scale practical use. Software implementations still require minutes or hours to evaluate even rather simple functions. For instance, evaluating the lightweight block cipher SIMON-64/128 [4] requires 4193s (an hour and 10 minutes) on a 4 -core Intel Core-i7 processor [29]. Note that homomorphic evaluation of a block cipher decryption is required to reduce the network communication to the data size following the proposal in [32]: data is encrypted with a block cipher by the user and then the server decrypts the ciphertext by evaluating the block cipher homomorphically by using a homomorhic encryption of the key. If FHE could achieve performance levels that would permit large-scale practical use, it would have a drastic effect on cloud computing: users could outsource computations to the cloud without the need to trust service providers and their mechanisms for protecting users' data from outsiders.

Application-specific integrated circuits (ASIC) and field-programmable gate arrays (FPGA) have been successfully used for accelerating performance-critical computations in cryptology (see, e.g, [28]). Hence, it is somewhat surprising that, so far, mainly standard software implementations of FHE have been published, because hardware acceleration could bring FHE significantly closer to practical feasibility. Only few publications have reported results on (hardware) acceleration of FHE and most are dealing with manipulation of very large integers. Wang et al. [38] implemented primitives for the Gentry-Halevi (GH) FHE scheme [23] using Graphics Processing Unit (GPU) and observed speedups up to 7.68. They focused particularly on the multi-million-bit modular multiplication by using Strassen multiplication and Barrett reduction. Wang and Huang [39, 40] later showed that this multiplication can be further accelerated by a factor of approximately two together with significant reductions in power consumption by using FPGA and ASIC. Doröz et al. [18] presented a million-bit multiplier for the GH scheme on ASIC. They reported that the performance remains roughly the same as on Intel Xeon CPU, but with a significantly smaller area than the CPU. Moore et al. [31] studied the use of hardwired multipliers inside FPGAs for accelerating large integer multiplication. The same researchers later presented the first implementation of the full FHE encryption in [10]. They reported a speedup factor of 44 compared to a corresponding software implementation. Cousins et al. [15, 16] drafted an architecture of an FPGA accelerator for FHE using Simulink extension to Matlab but they did not provide any implementation results for their architecture. To conclude, only few works are available on hardware accelera-
tion of FHE schemes. So far, no results are available on hardware acceleration of function evaluation on homomorphically encrypted data, although this is the most crucial part of FHE schemes in application scenarios.

We present the first efficient FPGA implementation of the building blocks required in modular polynomial ring based fully homomorphic schemes such as those built on RLWE [8] or NTRU [30]. These building blocks are sufficiently generic to allow implementation of such FHE schemes, and to illustrate this, we integrate these building blocks into a coprocessor architecture that can evaluate functions encrypted with the FHE scheme called Yet Another Somewhat Homomorphic Encryption (YASHE) [6]. To the best of our knowledge, it is the first FPGA implementation that supports function evaluation of homomorphically encrypted data. We use several standard optimization techniques such as the Chinese remainder theorem (CRT) representation, the number theoretic transformation (NTT) and fast modular polynomial reduction, but introduce several optimizations specific for the FPGA platform such as a specific memory access scheme for the NTT. We compile the architecture for Xilinx Virtex-7 XC7V1140T FPGA. We show that a single FPGA achieves speedups up to factor 26.6 in executing SIMON-64/128 compared to a corresponding software implementation running on a 4 -core Intel Core i7 processor from [29].

The paper is structured as follows. Section 2 describes the mathematical objects underlying FHE and recaps the YASHE scheme. Section 3 contains a high level description of known optimization techniques to speed-up computations in modular polynomial rings and describes how we represent polynomials using CRT in order to parallelize computations. We present our hardware architecture for the primitives of YASHE in Section 4. We provide implementation results on a Xilinx Virtex-7 FPGA and compare them to existing software results in Section 5. We end with conclusions and future work in Section 6.

## 2 System Setup

### 2.1 Modular Polynomial Rings

The FHE schemes based on RLWE [8] or NTRU [30] compute in modular polynomial rings of the form $R=\mathbb{Z}[x] /(f(x))$ where $f(x)$ is a monic irreducible polynomial of degree $n$. A very popular choice is to take $f(x)=x^{n}+1$ with $n=2^{k}$, since this is compatible with a $2 n$-degree NTT and reduction modulo $f(x)$ comes for free due to the NTT. However, we put no restriction on $f(x)$, which allows us to deal with any cyclotomic polynomial $\Phi_{d}(x)$ and thus to utilize single instruction multiple data (SIMD) operations $[36,37]$.

For an integer $q$, we denote by $R_{q}=R / q R$, i.e. the polynomial ring where the coefficients are reduced modulo $q$. The plaintext space in FHE schemes typically will be $R_{2}$, and if one wants to utilize SIMD operations the polynomial $f(x)$ should be chosen such that $f(x) \bmod 2$ splits into many different irreducible factors, each factor corresponding to "one slot" in the SIMD representation. It is easy to see that this excludes the most popular choice $x^{n}+1$ with $n=2^{k}$, since
it results in only one irreducible factor modulo 2 . In most polynomial ring based FHE schemes, a ciphertext consists of one or two elements in $R_{q}$. However, not all operations take place in the ring $R_{q}$; sometimes (see below for an illustration with YASHE) one is required to temporarily work in $R$ itself before mapping down into $R_{q}$ again using (typically) a divide and round operation.

### 2.2 YASHE

The YASHE scheme was introduced by Bos et al. in [6] in 2013. The scheme works in the ring $R=\mathbb{Z}[x] /(f(x))$, with $f(x)=\Phi_{d}(x)$ the $d$-th cyclotomic polynomial. The plaintext space is chosen as $R_{t}$ for some small $t$ (typically $t=2$ ) and a ciphertext consists of only one element in the ring $R_{q}$ for a large integer $q$. The main security parameters of the scheme are the degree of $f(x)$ and the size of $q$. We note that $q$ is not required to be a prime and can be chosen as a product of small primes to speed-up computations (see Section 3). To define the YASHE scheme we also require two probability distributions defined on $R$, namely $\chi_{\text {key }}$ and $\chi_{\text {err }}$. In practice one often takes $\chi_{\text {err }}$ to be a discrete Gaussian distribution, whereas $\chi_{\text {key }}$ can be simply sampling each coefficient from a narrow set like $\{-1,0,1\}$. Given an element $a \in R_{q}$ and a base $w$, we can write $a$ in base $w$ by splicing each of its coefficients, i.e. write $a=\sum_{i=0}^{u} a_{i} w^{i}$ with each $a_{i} \in R$ and coefficients in $(-w / 2, w / 2\rfloor$ and $u=\left\lfloor\log _{w}(q)\right\rfloor$. Decomposing an element $a \in R_{q}$ into its base $w$ components $\left(a_{i}\right)_{i=0}^{u}$ is denoted by $\operatorname{WordDecomp}_{w, q}(a)$. For an element $a \in R_{q}$, we define PowersOf ${ }_{w, q}(a)=\left(a w^{i}\right)_{i=0}^{u}$, the vector that consists of the element $a$ scaled by the different powers of $w$. Both operations can be used to provide an alternative description of multiplication in $R_{q}$, namely:

$$
\left\langle\operatorname{WordDecomp}_{w, q}(a), \text { PowersOf }_{w, q}(b)\right\rangle=a \cdot b \bmod q .
$$

The advantage of the above expression is that the first vector contains small elements, which limits error expansion in the homomorphic multiplication.

An FHE scheme is an augemented encryption scheme that defines two additional operations on ciphertexts, YASHE.Add and YASHE.Mult that result in a ciphertext encrypting the sum (respectively the product) of the underlying plaintexts. The YASHE scheme is then defined as follows (full details can be found in the original paper [6]).

- YASHE.ParamsGen $(\lambda)$ : For security parameter $\lambda$, choose a polynomial $\Phi_{d}(x)$, moduli $q$ and $t$ and distributions $\chi_{\text {err }}$ and $\chi_{\text {key }}$ attaining security level $\lambda$. Also choose base $w$ and return the system parameters ( $\left.\Phi_{d}(x), q, t, \chi_{\text {err }}, \chi_{\text {key }}, w\right)$.
- YASHE.KeyGen $\left(\Phi_{d}(x), q, t, \chi_{e r r}, \chi_{k e y}, w\right)$ : Sample $f^{\prime}, g \leftarrow \chi_{\text {key }}$ and set $f=$ $\left(t f^{\prime}+1\right) \in R_{q}$. If $f$ is not invertible in $R_{q}$ choose a new $f^{\prime}$. Define $h=$ $t g f^{-1} \in R_{q}$. Sample two vectors $\mathbf{e}, \mathbf{s}$ of $u+1$ elements from $\chi_{\text {err }}$ and compute $\gamma=$ PowersOf $_{w, q}(f)+\mathbf{e}+h \mathbf{s} \in R_{q}^{u+1}$ and output $(p k, s k, e v k)=(h, f, \gamma)$.
- YASHE.Encrypt $(h, m)$ : To encrypt a message $m \in R_{t}$ sample $s, e \leftarrow \chi_{\text {err }}$ and output the ciphertext $c=\Delta \cdot m+e+s h \in R_{q}$ with $\Delta=\lfloor q / t\rfloor$.
- YASHE.Decrypt $(f, c)$ : Recover $m$ as $m=\left\lfloor\frac{t}{q} \cdot[f \cdot c]_{q}\right\rceil \in R_{t}$ with $[\cdot]_{q}$ reduction in the interval ( $-q / 2, q / 2$ ].

```
Input: Polynomial \(a(x) \in \mathbb{Z}_{q}[\mathbf{x}]\) of degree \(N-1\) and \(N\)-th primitive root \(\omega_{N} \in \mathbb{Z}_{q}\) of unity
Output: Polynomial \(A(x) \in \mathbb{Z}_{q}[\mathbf{x}]=\operatorname{NTT}(a)\)
begin
    \(A \leftarrow\) BitReverse \((a)\);
    for \(m=2\) to \(N\) by \(m=2 m\) do
        \(\omega_{m} \leftarrow \omega_{N}^{N / m} ;\)
        \(\omega \leftarrow 1\);
        for \(j=0\) to \(m / 2-1\) do
            for \(k=0\) to \(N-1\) by \(m\) do
                \(t \leftarrow \omega \cdot A[k+j+m / 2] ;\)
                \(u \leftarrow A[k+j] ;\)
                \(A[k+j] \leftarrow u+t ;\)
                \(A[k+j+m / 2] \leftarrow u-t ;\)
            \(\omega \leftarrow \omega \cdot \omega_{m} ;\)
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Algorithm 1: Iterative NTT [13]

- YASHE.Add $\left(c_{1}, c_{2}\right)$ : Return $c_{1}+c_{2} \in R_{q}$.
- YASHE.KeySwitch $(c, e v k):$ Return $\left\langle\operatorname{WordDecomp}_{w, q}(c), e v k\right\rangle \in R_{q}$
- YASHE.Mult $\left(c_{1}, c_{2}, e v k\right)$ : Return $c=$ YASHE.KeySwitch $\left(c^{\prime}, e v k\right)$ with $c^{\prime}=$ $\left\lfloor\frac{t}{q} c_{1} c_{2}\right\rceil \in R_{q}$.

YASHE Paramater Set: We use the parameter set Set-III from [29] that supports homomorphic evaluations of SIMON-64/128; in particular $d=65535$ (and thus the degree of $f(x)$ is $\left.32768=2^{15}\right), \log _{2}(q)=1228$ and $\chi_{\text {err }}$ a discrete Gaussian distribution with parameter $\sigma=8$. The paper [29] claims that this set has security level 128 -bits, but this is an underestimate due to a small error in the security derivation. We chose SIMON because it has a smaller multiplicative depth (e.g. AES), and because it offers direct comparability to the existing software implementation [29].

## 3 High Level Optimizations

To efficiently implement YASHE we have to analyze the two main operations in detail, namely homomorphic addition and homomorphic multiplication. Homomorphic addition is easy to deal with since this simply corresponds to polynomial addition in $R_{q}$. Homomorphic multiplication is much more involved and is the main focus of this paper. As can be seen from the definition of YASHE.Mult in Section 2.2, to multiply two ciphertexts $c_{1}$ and $c_{2}$ one first needs to compute $c_{1} \cdot c_{2}$ over the integers, then scale by $t / q$ and round, before mapping back into the ring $R_{q}$. The fact that one first has to compute the result over the integers (to allow for the scaling and rounding) has a major influence on how elements of $R_{q}$ are represented and on how the multiplication has to be computed.

First we will consider polynomial multiplication in $R_{q}$ where the modulus $f(x)$ is an arbitrary polynomial of degree $n$. Since each element in $R_{q}$ therefore can be represented as a polynomial of degree $n-1$, the resulting product will have degree $2 n-2$. As such we choose the smallest $N=2^{k}>2 n-2$, and compute the product of the two polynomials in the ring $\mathbb{Z}_{q}[x] /\left(x^{N}-1\right)$ by using
the $N$-fold NTT (see Alg. 1). The NTT requires the $N$-th roots of unity to exist in $\mathbb{Z}_{q}$, so we either choose $q$ a prime with $q \equiv 1 \bmod N$ or $q$ a product of small primes $q_{i}$ with each $q_{i} \equiv 1 \bmod N$. It is the latter choice that will be used throughout this paper.

The product of two elements $a, b \in R_{q}$ is then computed in two steps: firstly, the product modulo $x^{N}-1$ (note that there will be no reduction, since the degree of the product is small enough) is computed using two NTT's, $N$ pointwise multiplications modulo $q$ and then finally, one inverse NTT. To recover the result in $R_{q}$, we need a reduction modulo $f(x)$. For general $f(x)$ this reduction does not come for free (unlike the choice $f(x)=x^{n}+1$ ) and for the parameters used in the YASHE scheme the polynomial $f(x)$ is in fact quite dense (although almost all coefficients are $\pm 1$ ). We have to consider general $f(x)$ because the most obvious choice $f(x)=x^{n}+1$ does not allow SIMD operations, since $f(x) \bmod 2$ has only one irreducible factor. The polynomial $\Phi_{d}(x)$ from the YASHE parameter set splits modulo 2 in 2048 different irreducible polynomials, which implies that we can work on 2048 bits in parallel using the SIMD method first outlined in [36].

To speed-up the reduction modulo $f(x)$ we rely on a polynomial version of Barrett reduction [21], where one precomputes the inverse of $x^{n} f(1 / x) \bmod -$ ulo $x^{n}$. The quotient and remainder can then be recovered at the cost of two polynomial multiplications.

Note that the multiplication of $c_{1}$ and $c_{2}$ in YASHE.Mult is performed over integers. To get the benefit of NTT based polynomial multiplication, we perform this multiplication in a ring $R_{Q}$ where $Q$ is a sufficiently large modulus of size $\sim 2 \log q$ such that the coefficients of the result polynomial are in $\mathbb{Z}$.

CRT Representation of Polynomials: In the cryptosystems based on the RLWE problem, computations are performed on the polynomials of a ring $R_{q}$. The reported FPGA-based architectures [3, 33, 35] of such cryptosystems use BRAM slices to store the polynomials and use arithmetic components made up of DSP multipliers and LUTs. The biggest challenge while designing a homomorphic processor is the complexity of computation. During a homomorphic operation, computations are performed on polynomials of degree $2^{15}$ or $2^{16}$ and coefficients of size $\sim 1,200$ or $\sim 2,500$ bits. If we use a bit-parallel coefficient multiplier, then a $2,500 \times 2,500$-bit multiplier will not only result in an enormous area, but will also result in a very low operating frequency. On the other side, a word-serial multiplier is too slow for homomorphic computations.

To tackle the problem of long integer arithmetic, we take inspiration from the application of the CRT in the RSA cryptosystems. We choose the moduli $q$ and $Q$ as products of many small prime moduli $q_{i}$, such that $q=\prod_{0}^{l-1} q_{i}$ and $Q=\prod_{0}^{L-1} q_{i}$, where $l<L$. We map any long integer operation modulo $q$ or $Q$ into small computations moduli $q_{i}$, and apply CRT whenever a reverse mapping is required. We use the term small residue to represent coefficients modulo $q_{i}$ and the term large residue to represent coefficients modulo $q$ or $Q$.

Parallel Processing: Beside making the long integer operations easy, such small-residue representation of the coefficients have a tremendous effect on the computation time. Since the computations in the small-residue representations are independent of each other, we can exploit this parallelism and speedup the computations using several parallel cores.

The size of the moduli $q_{i}$ is an important design decision and depends on the underlying platform. We use the largest Xilinx Virtex-7 FPGA XC7VX1140T to implement our homomorphic processor and tune the design decisions accordingly. The FPGA has $3,36025 \times 18$-bit DSP multipliers [1]. One could implement a slightly larger multiplier by combining DSP multipliers with LUTs. For the set of moduli, we choose in total 84 primes (hence $l=41$ and $L=84$ ) of size 30 bits, (the primes from 1008795649 onwards) satisfying $q_{i} \equiv 1 \bmod N$. The reasons for selecting only 30 -bit of primes are: 1) there are sufficiently many primes of size 30 -bit to compose 1,228 -bit $q$ and 2,517 -bit $Q, 2$ ) the data-paths for performing computations modulo $q_{i}$ become symmetric, and 3 ) the basic computation blocks, such as adders and multipliers of size 30-bit can be implemented efficiently using the available DSP slices and a few LUTs.

## 4 Architecture

We propose an architecture (Fig. 1) to perform the operations in the YASHE scheme. The central part of the architecture is an FPGA based accelerator that works as a coprocessor of a computer and executes the computationally intensive operations. We call this coprocessor the HE-coprocessor. The HE-coprocessor supports the following operations: NTT of a polynomial, coefficient wise addi-


Fig. 1. Overview of the HE Architecture
tion/subtraction/multiplication of two polynomials, computation of the residues using the CRT, computation of the coefficients modulo $Q$ from the residues, and the scaling of the coefficients. The external memory in this architecture is implemented using high-speed RAMs and is used to store the polynomials during a homomorphic computation. The computer in Fig. 1 works in master-mode and instructs the HE-coprocessor and the controller of the external memory. Since the execution of the homomorphic scheme is controlled by a software program in the computer, a level of flexibility to implement other homomorphic schemes based on a similar set of elementary operations is offered.

The HE-coprocessor comprises of three main components: the polynomial arithmetic unit (PAU), the CRT unit (CRTU), and the division and rounding unit (DRU). We do not implement the discrete Gaussian sampling in the HEcoprocessor as sampling is required only during an encryption, which is a less frequent operation. Since the samples from a narrow discrete Gaussian distribution can be generated very efficiently using lookup tables in software [11], we use the master-computer (Fig. 1) for this purpose.

### 4.1 Polynomial Arithmetic Unit

To exploit the parallelism provided by the small-residue representation of the polynomials, the PAU has $h$ parallel processors to perform computations on $h$ residue polynomials simultaneously. We call this horizontal parallelism. Since the targeted FPGA does not provide sufficient resources to process all the smallresidue polynomials in parallel, we design the processors in a generic way such that a processor can be time-shared by a group of $\lceil L / h\rceil$ prime moduli. To add an additional degree of acceleration, we add $v$ parallel cores in each processor. We call this vertical parallelism. The cores in a processor are connected to a group of BRAMs through a switching matrix.

Optimization in the Routing: During an NTT computation (Alg. 1), coefficients are fetched from the memory and then butterfly operations are performed on the coefficients. Let us assume that a residue polynomial of $N=2^{16}$ coefficients is stored in $b$ BRAMs and then processed using $v$ butterfly cores. If $v$ is a divisor of $b$, then we can split the NTT computation in equal parts among the $v$ parallel butterfly cores. However there are two main technical issues related to the memory access that would affect the performance of the NTT computation. The first one is: all the parallel cores read and write simultaneously in the memory blocks. Since a simple dual port BRAM has one port for reading and one port for writing, it can support only one read and write in a clock cycle. Hence a memory block can be read (or written) by one butterfly core in a cycle and thus address generation by the parallel butterfly cores should be free from conflicts. The second issue is related to the routing complexity. Since a residue polynomial is stored in many BRAMs, access of data from a BRAM that is very far from a butterfly core will result in a very long routing distance. Now in Alg. 1 we see that the maximum difference between the indexes of the two coefficients is $N / 2$.

In the FPGA, fetching data from memory locations at a relative distance of $2^{15}$ will result in a long routing, and thus could drastically reduce the frequency.

To address these two technical challenges, we have developed a memory access scheme by analysing the address generation during different iterations of the loops in the NTT (Alg. 1) We segment the set of $b$ BRAMs into $b / v$ groups. The read ports of a group are accessed by only one butterfly core. This dedicated read prevents any sort of conflict during the memory read operations. Moreover, in the FPGA the group of BRAMs can be placed close to the corresponding butterfly core and thus the routing complexity can be reduced.

We describe the proposed memory access scheme during an execution of the NTT by parallel cores in Alg. 2. The module butterfly-core performs butterfly operations on two coefficent pairs following the optimization technique in [35]. In the algorithm the $v$ parallel butterfly cores of a processor are indexed by $c$ where $c \in[0, v-1]$. During the $m$-th loop of a NTT, the twiddle factor in the $c$-th core is initialized to a constant value $\omega_{m, c}$. In the hardware, these constants are stored in a ROM. The counter $I_{\text {twiddle }}$ denotes the interval between two consecutive calculations of the twiddle factors. Whenever the number of butterfly operations $\left(N_{\text {butterfly }}\right)$ becomes a multiple of $I_{\text {twiddle }}$, a new twiddle factor is computed. The $c$-th butterfly core reads the $c$-th group of BRAMs MEMORY ${ }_{c}$ using two addresses address $_{1}$ and address $_{2}$. The addresses are computed from the counters: base, increment, and offset, that represent the starting memory address, the increment value, and the difference between address ${ }_{1}$ and address ${ }_{2}$ respectively. A butterfly core outputs the two addresses and the four coefficients $s_{1, c}, s_{2, c}, s_{3, c}, s_{4, c}$. These output signals from the parallel butterfly cores are collected by a set of parallel modules memory-write that are responsible for writing the groups of BRAMs. The input coefficients that will be read by the adjacent butterfly core in the next iteration of the $m$-th loop, are selected for the writing operation in $M E M O R Y_{c}$ by the $c$-th memory-write module. The top module Parallel-NTT instantiates $v$ butterfly cores and memory write blocks. These instances run in parallel and exchange signals.

Internal Architecture of the PAU: In Fig. 2 we show the internal architecture of the vertical cores that we use inside the horizontal processors in Fig. 1. We follow the pipelined RLWE encryption architecture presented in Fig. 2 of [35] and design our cores to support additional computations required in the YASHE scheme. We design the cores in a more generic way such that a single core can perform computations with respect to several moduli.

The input register bank in Fig. 2 contains registers to store data from the BRAMs and data from the CRTUs. In addition, the register bank also contains shift registers to delay the input coefficients in a pipeline during a NTT computation (see [35] for more details). The register bank has several ports to provide data to several other components present in the core. We use the common name $D_{\text {regbank }}$ to represent all data-outputs from the register bank. The small ROM block in Fig. 2 contains the twiddle factors and the value of $N^{-1}$ to support the computation of NTT and INTT. Though the figure shows only one such

```
/* This module computes butterfly operations
module butterfly-core(input \(c\); output \(m\), address \({ }_{1}\), address \({ }_{2}, s_{1, c}, s_{2, c}, s_{3, c}, s_{4, c}\) )
begin
    \(\left(I_{\text {twiddle }}\right.\), offset \() \leftarrow(N / 2,1)\)
    for \(m=0\) to \(\log N-1\) do
        \(\omega_{m} \leftarrow 2^{m}\)-th primitiveroot(1)
        \(N_{\text {butterfly }} \leftarrow 0 \quad / *\) Counts the number of butterfly operation in a \(m\)-loop */
        \(\omega \leftarrow \omega_{m, c} \quad / *\) Initialization to a power of \(\omega_{m}\) for a core-index \(c * /\)
        for base \(=0\) to base \(<\) offset do
            increment \(\leftarrow 0\)
                while base + offset + increment \(<\frac{N}{2 v}\) do
                        (address \({ }_{1}\), address \(\left.{ }_{2}\right) \leftarrow\) (base + increment, base + offset + increment \()\)
                        \(\left.\left(t_{1}, u_{1}\right) \leftarrow M E M O R Y_{c}[\text { address }]_{1}\right] \quad / *\) Read from \(c\)-th group of RAMs */
                    \(\left(t_{2}, u_{2}\right) \leftarrow M E M O R Y_{c}\left[a^{2} d\right.\) ress \(\left._{2}\right]\)
                    if \(m<\log N-1\) then
                                    \(\left(t_{1}, t_{2}\right) \leftarrow\left(\omega \cdot t_{1}, \omega \cdot t_{2}\right)\)
                                    \(\left(s_{1, c}, s_{2, c}, s_{3, c}, s_{4, c}\right) \leftarrow\left(u_{1}+t_{1}, u_{1}-t_{1}, u_{2}+t_{2}, u_{2}-t_{2}\right)\)
                                    \(N_{\text {butterfly }} \leftarrow N_{\text {butterfly }}+2\)
                                    increment \(=\) increment \(+2 \cdot\) offset
                                    if \(N_{\text {butterfly }} \equiv I_{\text {twiddle }}\) then \(\omega \leftarrow \omega \cdot \omega_{m}^{v / 2}\)
                    else
                    \(t_{1} \leftarrow \omega \cdot t_{1} ; \omega \leftarrow \omega \cdot \omega_{m}^{v / 2}\)
                            \(t_{2} \leftarrow \omega \cdot t_{2} ; \omega \leftarrow \omega \cdot \omega_{m}^{v / 2}\)
                            \(\left(s_{1, c}, s_{2, c}, s_{3, c}, s_{4, c}\right) \stackrel{\leftarrow}{\leftarrow}\left(u_{1}+t_{1}, u_{1}-t_{1}, u_{2}+t_{2}, u_{2}-t_{2}\right)\)
                            \(N_{\text {butterfly }} \leftarrow N_{\text {butterfly }}+2\)
                    increment \(=\) increment \(+2 \cdot\) offset
            \(I_{\text {twiddle }} \leftarrow I_{\text {twiddle }} / 2\)
            if offset \(<v / 2\) then offset \(\leftarrow 2\). offset
/* This module writes the coefficients computed by two butterfly-cores */
module memory-write(input \(c, m\), address \(_{1}\), address \(s_{2}, s_{1,0}, \ldots s_{4, v-1}\) )
begin
    if \(2^{m}<\frac{v}{2}\) then \(\operatorname{gap} \leftarrow 2^{m}\)
    else \(g a p \leftarrow \frac{v}{2}\)
                            /* This represents the index gap between the two cores */
    if \(c<v / 2\) then
            \(M E M O R Y_{c}\left[\right.\) address \(\left._{1}\right] \leftarrow\left(s_{2, c}, s_{1, c}\right)\)
            \(M E M O R Y_{c}\left[\right.\) address \(\left._{2}\right] \leftarrow\left(s_{2, c+g a p}, s_{1, c+g a p}\right)\)
    else
            \(\operatorname{MEMORY}_{c}\left[\right.\) address \(\left._{1}\right] \leftarrow\left(s_{4, c}, s_{3, c}\right)\)
            \(M E M O R Y_{c}\left[\right.\) address \(\left._{2}\right] \leftarrow\left(s_{4, c+g a p}, s_{3, c+g a p}\right)\)
/* This is the top module that executes butterfly-core in parallel */
module Parallel-NTT()
begin
    butterfly-core bc \(c_{0}\left(0, m\right.\), address \(s_{1}\), address \(\left._{2}, s_{1,0}, s_{2,0}, s_{3,0}, s_{4,0}\right)\)
    memory-write \(m_{0}\left(0, m\right.\), address \(_{1}\), address \(\left.{ }_{2}, s_{1,0}, \ldots s_{4, v-1}\right)\)
    butterfly-core \(^{\text {bu }} c_{v-1}\left(v-1, m\right.\), address \(_{1}\), address \(\left._{2}, s_{1, v-1}, s_{2, v-1}, s_{3, v-1}, s_{4, v-1}\right)\)
    memory-write \(m_{v-1}\left(v-1, m\right.\), address \(_{1}\), address \(\left.s_{2}, s_{1,0}, \ldots s_{4, v-1}\right)\)
```

Algorithm 2: Routing Efficient Parallel NTT using $v$ cores

ROM block, there are actually $\left\lceil\frac{L}{h}\right\rceil$ such ROM blocks, since a core is shared by $\left\lceil\frac{L}{h}\right\rceil$ primes. The integer multiplier (shown as a circle in Fig. 2) is a $30 \times 30$-bit multiplier. We maintain a balance between area and speed by combining two DSP multipliers and additional LUT based small multipliers to form this multiplier. After an integer multiplication, the result is reduced using the Barrett reduction circuit shown in Fig. 2. We use the Barrett reduction technique due to
two reasons. The first reason is that the primes used in this implementation are not of pseudo-Mersenne type which support fast modular reduction technique [26]. The second reason is that the cores are shared by several prime moduli, and hence, a generic reduction circuit is more preferable than several dedicated reduction circuits. The Barrett reduction circuit is bit parallel to process the outputs from the bit-parallel multiplier in a flow. The reduction consists of three $31 \times 31$-bit multipliers and additional adders and subtractors. The multipliers are implemented by combining two DSP multipliers with additional LUTs. Thus in total, the Barrett reduction block consumes six DSP multipliers. Beside performing the modular reduction operations, the multipliers present in the Barrett reduction circuit can be reused to perform $30 \times 59$-bit multiplications during the CRT computations. The adder/subtracter and the subtracter circuits after the Barrett reduction block in Fig. 2 are used to compute the butterfly operations during a NTT computation and to perform coefficient-wise additions and subtractions of polynomials. Finally, the results of a computation are stored in the output register bank and then the registers are written back in the memory. To achieve high operating frequency, we follow the pipelining technique from [35] and put pipeline registers in the data paths of the computation circuits. In Fig. 2, the pipeline registers are shown as magenta colored lines.

### 4.2 CRT Unit

We accelerate polynomial arithmetic by representing the polynomials of $R_{q}$ as smaller residue polynomials moduli $q_{j}, j \in[0, l-1]$. However, this representation also has the following overhead:

- The multiplication of the input polynomials $c_{1}$ and $c_{2}$ in YASHE.Mult is performed in the larger ring $R_{Q}$ (see Section 2.2). Since $c_{1}$ and $c_{2}$ are in $R_{q}$, we need to first lift the polynomials from $R_{q}$ to $R_{Q}$. This lifting operation essentially computes the residue polynomials moduli $q_{j}, j \in[l, L-1]$ from the residue polynomials moduli $q_{i}, i \in[0, l-1]$ by applying the CRT. We call this operation the small-CRT.


Fig. 2. Architecture for the Vertical Cores

- After the multiplication of $c_{1}$ and $c_{2}$, the result is a set of residue polynomials moduli $q_{j}, j \in[0, L-1]$. The scaling operation in YASHE.Mult requires the coefficients of the result in the form of modulo $Q$. Hence, we apply the CRT to get back the coefficients modulo $Q$ from the small residue polynomials moduli $q_{j}, j \in[0, L-1]$. We call this operation the large-CRT.

Architecture for the Large-CRT Unit: We compute simultaneous solution with respect to the large modulus $Q$ from the residues $[q]_{q_{i}}$ for $i \in[0, L-1]$.

$$
\begin{equation*}
[a]_{Q}=\left[\sum[a]_{q_{i}} \cdot\left(\frac{Q}{q_{i}}\right) \cdot\left[\left(\frac{Q}{q_{i}}\right)^{-1}\right]_{q_{i}}\right]_{Q}=\left[\sum[a]_{q_{i}} \cdot b_{i}\right]_{Q} \tag{1}
\end{equation*}
$$

Our large-CRT architecture is shown in the right half of Fig. 3. The constant values $b_{i}$ are stored in a ROM and then multiplied word-serially with the coefficients from the BRAMs. We set the word size of the ROMs to 59 bits in order to reuse the $31 \times 59$-bit multipliers of the Barrett reduction circuits (Fig. 2) for the 30 -by- 59 bit multiplications. The computation is distributed among the vertical cores of a processor. In our HE-coprocessor, there are 16 vertical cores in a processor. These cores are divided into two CRT groups: Core-0 to Core-7 form the first group, whereas Core-8 to Core-15 form the second group. Each group computes one large-CRT in parallel. Since there are $84 b_{i}$ constants (Equation 1), each core in a group computes multiplications with a maximum of 11 $b_{i}$ constants in parallel and in pipeline. The results of the multiplications are accumulated in the accumulation registers. The partially accumulated results from the cores are added together as follows: the register $\operatorname{acc}_{0}$ is added with $a c c_{1}$ and the result is stored in $a c c_{1}$. Then $a c c_{1}$ is added with $a c c_{2}$ and finally $a c c_{2}$ is added with $a c c_{3}$. In parallel, $a c c_{7}$ down to $a c c_{4}$ are added together and the result is stored in $a c c_{4}$. Finally $a c c_{4}$ is added with $a c c_{3}$ and the result is stored in $a c c_{3}$. This final result is then stored in a small distributed RAM (not shown in the figure) which is read by the DRU. Similar computations are performed in the group consisting of Core-8 to Core-15.

Architecture for the Small-CRT Unit: During a small-CRT computation we first compute the sum of products using the following equation for $i \in[0, l-1]$.

$$
\begin{equation*}
a=\sum[a]_{q_{i}} \cdot\left(\frac{q}{q_{i}}\right) \cdot\left[\left(\frac{q}{q_{i}}\right)^{-1}\right]_{q_{i}}=\sum[a]_{q_{i}} \cdot b_{i} \tag{2}
\end{equation*}
$$

This computation is similar to the sum calculation in the large-CRT, but the number of operands is less (maximum of 6 per core) and the size of $b_{i}$ are small. We use a similar computation strategy as described in the large-CRT unit. After the computation of $a$ we compute $\left[a^{\prime}\right]_{q_{j}}$ for $j \in[l, L-1]$ using the following equation.

$$
\begin{equation*}
\left[a^{\prime}\right]_{q_{j}}=\left[\sum[a]_{q_{i}} \cdot\left[b_{i}\right]_{q_{j}}\right]_{q_{j}} \tag{3}
\end{equation*}
$$

Here $\left[b_{i}\right]_{q_{j}}$ are 30 -bit integers. The architecture for this computation is shown in the left half of Fig. 3. For the modular multiplications we use the modular


Fig. 3. Architecture for the Small and Large CRT. The computation blocks are aligned along a horizontal processor. Exchange of data between the cores occur during a LargeCRT computation.
multiplier that is present inside the vertical cores present of a processor in our HE-coprocessor. The cores in the two CRT groups compute in parallel and in pipeline. Each core computes a maximum of 6 modular multiplications (since there are $43 q_{j}$ modulus and 8 cores in a CRT group). The accumulation of the partially computed results from one core to the next core is performed in the same way as described in the large-CRT unit. Finally, we compute the residues $[a]_{q_{j}}$ for $j \in[l, L-1]$ using the following equation:

$$
\begin{equation*}
[a]_{q_{j}}=\left[\left[a^{\prime}\right]_{q_{j}}-[\lfloor a / q\rfloor]_{q_{j}} \cdot[q]_{q_{j}}\right]_{q_{j}} \tag{4}
\end{equation*}
$$

This computation involves a division of $a$ by $q$ which is performed using the division unit in parallel to the computation of (3). The division architecture is described in the next section.

### 4.3 Division and Rounding Unit

The DRU computes $\lfloor t c / q\rceil$ where $t=2, c$ is a coefficient from the Large-CRTU, and $\lfloor\cdot\rceil$ denotes rounding towards the nearest integer. The division is carried out by precomputing the reciprocal $r=2 / q$ and then computing $r \times c$. The DRU outputs 59 -bit words that can be directly reduced modulo the 30 -bit $q_{i}$ using the existing Barrett reduction circuitries in the PAU that operate on inputs of


Fig. 4. The Division and Rounding Unit (DRU)
size $<q_{i}^{2}$. The word size of the DRU was selected to be 118 bits $(2 \times 59)$ as a compromise between area and latency.

To round a division of two $k$-bit integers correctly to $k$-bits, the quotient must be computed correctly to $2 k+1$ bits [27, Theorem 5.2]. In our case, the computation of $\lfloor t c / q\rceil$ requires a division of a $k_{1}$-bit dividend by a $k_{2}$-bit divisor. The precision that we will need in this case to guarantee correct rounding, based on the above, is $k_{1}+k_{2}+1$ bits. The divisor $q$ is a 1228 -bit constant integer and the dividend $c$ is an at most 2492-bit integer ${ }^{1}$, which gives a bound of 3721 bits. Hence, the reciprocal $r$ is computed up to a precision of 32118 -bit words, of which 22 words are nonzero.

Figure 4 shows the architecture of the DRU. The multiplication $r \times c$ is computed by using a $118 \times 118$-bit multiplier that computes $22^{2}=484$ partial multiplications. This multiplier performs a 118-bit Karatsuba multiplication by using three $59 \times 59$-bit multipliers generated with the Xilinx IP Core tool (which supports only up to 64 -bit multipliers). The 59 -bit multipliers each require 16 DSP blocks giving the total number of 48 DSP blocks. In order to achieve a high clock frequency, the 118 -bit multiplier utilizes a 23 -stage pipeline, of which 18 stages are in the 59-bit multipliers (the optimal number according to the tool).

The partial products from the 118-bit multiplier are accumulated into a 241bit $(2 \times 118+5)$ register using the Comba algorithm [12]. These additions are computed in a 4 -stage pipeline with three 59 -bit adders and one 64 -bit adder,

[^1]Table 1. The area results on Xilinx Virtex-7 XCV1140TFLG1930-2 FPGA

| Resource | Used | Avail. Percentage |  |
| :--- | ---: | ---: | ---: |
| Slice Registers | 323,120 | $1,424,000$ | $22.6 \%$ |
| Slice LUTs | 377,368 | 712,000 | $53 \%$ |
| BlockRAM | 640 BRAM36, 144 BRAM18 | 1,880 | $37.8 \%$ |
| DSP48 | 1,792 | 3,360 | $53 \%$ |

which are all implemented with LUTs. Whenever all partial products of an output word have been computed, the register is shifted to the right by 118 bits and the overflowing bits are given at the output of the DRU. Once the computation proceeds to the first word after the fractional point, then the msb of the fractional part is added to the register in order to perform the rounding. The DRU has a constant latency of 687 clock cycles per coefficient.

The DRU is reused for computing $\lfloor c / q\rfloor$ during the small-CRT. The computation proceeds analogously to the above. The differences are that the reciprocal is now $r=1 / q$ and it needs to be computed only to a precision of 2493 bits (12 nonzero words) because $c$ can be only 36 bits longer than $q$. The computation has a latency of 246 clock cycles per division.

## 5 Results

The HE-coprocessor proposed in Sect. 4 was described using mixed Verilog and VHDL. We compiled the processor for Xilinx Virtex-7 XC7V1140T-2, the largest device of the Virtex-7 FPGA family, by using the Xilinx ISE 13.4 Design Suite. We set the optimization goal in the ISE tool to speed. All results reported in the section have been obtained after place-and-route analysis.

The HE-coprocessor has $h=8$ horizontal processors, each having $v=16$ parallel vertical cores for performing polynomial arithmetic, two small-CRT computation groups, two large-CRT computation groups and two DRUs. The area counts of our HE-coprocessor are shown in Table 1. As seen from the table, our HE-coprocessor consumes nearly $50 \%$ of the computational elements (LUTs and DSP multipliers) available in the FPGA. To know the maximum number of processors that we can implement in a single FPGA, we performed a design exploration using the Xilinx PlanAhead tool. This tool allows the designer to manually place different components in the FPGA. The Virtex-7 XCV1140 FPGA consists of four super large logic regions (SLRs). From the design exploration we have found that we can put two processors in one SLR. If we put three processors in one SLR (occupies around $70 \%$ of the SLR-area), then the Xilinx tool reports congestion of routing channels and the place-and-route analysis fails. From this design exploration we conclude that we can implement two processors per SLR, and hence eight processors in one Virtex-7 XCV1140 FPGA.

Table 2 gives the latencies of different operations supported by our HEcoprocessor. The operating frequency of our HE-coprocessor is 143 MHz after

Table 2. Latencies and timings at 143 MHz after place-and-route

| Operation | Clocks | Time | Rel. time $^{\dagger}$ |
| :--- | ---: | ---: | ---: |
| NTT | 47,795 | 0.334 ms | $0.163 \mu \mathrm{~s}$ |
| INTT | 51,909 | 0.363 ms | $0.177 \mu \mathrm{~s}$ |
| Poly-add/sub/mult | 4,096 | 0.029 ms | $0.014 \mu \mathrm{~s}$ |
| Small-CRT | 821,248 | 5.743 ms | $2.804 \mu \mathrm{~s}$ |
| Large-CRT | $2,752,512$ | 19.248 ms | $9.398 \mu \mathrm{~s}$ |
| Divide-and-round | $2,813,952$ | 19.678 ms | $9.559 \mu \mathrm{~s}$ |
| YASHE.Add | 24,576 | 0.172 ms | $0.083 \mu \mathrm{~s}$ |
| YASHE.Mult $^{\star}$ | $17,399,987121.678 \mathrm{~ms}$ | $59.413 \mu \mathrm{~s}$ |  |
| SIMON-32/64 | $8,908,793,344$ | 62.299 s | 30.419 ms |
| SIMON-64/128 | $24,499,181,696$ | 171.323 s | 83.653 ms |

$\dagger$ Time per slot in SIMD operations (in total 2048 slots)

* Excluding interfacing with the computer and the external memory
place-and-route analysis. NTT and INTT computations are performed on polynomials of $N=2^{16}$ coefficients. To save memory requirement, we compute the twiddle factors on the fly at the cost of $N$ integer multiplications. One NTT computation using $v=16$ cores requires $\left(N+\frac{N}{2} \log _{2}(N)\right) / 16$, i.e. 36,864 multiplications. However the computation of the twiddle factors in the pipelined data path of the PAU (Fig. 2) has data dependencies and thus causes bubbles in the pipeline. Following [35], we use a small register-file that stores four consecutive twiddle factors, and reduce the cycles spent in the pipeline bubbles to around 10,000 . In the case of an INTT computation, the additional cycles are spent during scaling operation by $N^{-1}$. Cycle count per coefficient for the smallCRT is 401. Since there are two CRT groups per processor and there are total eight processors in our HE-coprocessor, for a polynomial with $2^{15}=32,768$ coefficient, the total cost of small-CRT is 821,248 cycles. Similarly, the costs of large-CRT and the division-and-rounding are 672 and 687 cycles per coefficient respectively. However, the cycles spent for the large-CRT operations are not a part of the actual cost, as the large-CRT operation runs in parallel with the division-and-rounding operations during a homomorphic multiplication. The division-and-rounding operations are computed $2^{16}$ times using 16 DRUs (two from each horizontal processor) at the cost of $2,813,952$ cycles.

Table 2 includes estimates for the latencies of YASHE.Add and YASHE.Mult as well as the evaluations of SIMON-32/64 and SIMON-64/128. The YASHE.Mult computes small-CRT, polynomial multiplication, scaling and YASHE.KeySwitch operations. The cycle count for YASHE.Mult is derived as follows. First the input polynomials $c_{1}$ and $c_{2}$ are lifted from $R_{q}$ to $R_{Q}$ using small-CRTs of the two polynomials; then a polynomial multiplication (including Barrett polynomial reduction) is performed using 4 NTTs, 3 INTTs, 3 Poly-mul and 1 Polysub. Since there are 84 moduli, we compute these operations in 11 batches using $h=8$ processors. After the polynomial multiplication, a scaling operation
by $t / q$ is performed to compute $c^{\prime}$. The YASHE.KeySwitch operation, which is $\left\langle\right.$ WordDecomp $\left._{w, q}\left(c^{\prime}\right), e v k\right\rangle$, uses NTT of the fixed evk (22 polynomials) and decomposes $c^{\prime}$ into 22 polynomials. First 22 NTTs and then 22 coefficient-wise multiplications, followed by 21 coefficient-wise additions are performed. Finally one INTT is computed and the result is reduced using Barrett reduction (2 NTTs, 2 INTTs, 2 coefficient-wise multiplications, and 1 coefficient-wise subtraction). All these computations are performed in six batches. Estimates for SIMON consider only YASHE.Mult, which dominate the costs of function evaluations. SIMON-32/64 and SIMON-64/128 require 512 ( 32 rounds with 16 ANDs) and 1,408 ( 44 rounds with 32 ANDs) YASHE.Mult, respectively. In addition to the latencies and timings for a single execution of the operations, we also provide the relative timings which represent the timings per slot (in total 2048 slots).

Lepoint and Naehrig [29] presented C++ implementations for homomorphic evaluations of SIMON-32/64 and SIMON $64 / 128$ with YASHE running on a 4 core Intel Core i7-2600 at 3.4 GHz . They reported computation times of 1029 s $(17.2 \mathrm{~min})$ and $4193 \mathrm{~s}(69.9 \mathrm{~min})$ for SIMON-32/64 and SIMON-64/128 using all 4 cores, respectively. The implementations included 1800 and 2048 slots and, hence, the relative times per slot were 0.57 s and 2.04 s , respectively. With one core, they achieved 16500 s ( 275 min ) for SIMON-64/128. The homomorphic evaluation of SIMON-64/128 on our FPGA implementation takes $171.3 \mathrm{~s}(2.85$ $\min )$ and it also allows 2048 slots giving a relative time of only 83.6 ms per slot. Hence, our single FPGA implementation offers a speedup of up to 24.5 (or 96.32) times compared to the 4 -core (or 1-core) software implementation.

## 6 Conclusions and Future Work

We showed that modern high-end FPGAs (such as Virtex-7) have sufficient logic, hardwired multipliers, and internal memory resources for efficient computation of primitives required for evaluating functions on FHE encrypted data. Despite this, memory requirements and the speed of memory access is critical. Only ciphertexts that are currently being processed fit into the internal memory of the FPGA and other ciphertexts must be stored in external memory. Interface with the external memory may become a bottleneck unless it is done with special care. Sufficiently fast memory access can be achieved by using high bandwidth memory and/or parallel memory chips. Many FPGAs include dedicated transceivers for fast interfacing that could be used for fast data access in FHE computations. Moreover, most of the memory access can be performed in parallel with computation using a ping-pong scheme of two sets of BRAMs in the FPGA. The FPGA and the master-computer operate on these two sets alternatively between two consecutive instructions: when the FPGA operates on the first set, the master-computer operates on the second, and vice versa.

We presented a single-FPGA design of homomorphic evaluation with YASHE. An obvious way to improve the performance would be to use a multi-FPGA design (a cluster). We see four parallelization approaches. The first and simplest option is to instantiate parallel FPGAs so that each of them computes different
homomorphic evaluations independently of each other. This approach improves throughput, but the latency of an individual evaluation remains the same. The second approach is to divide independent homomorphic operations inside a single homomorphic evaluation to parallel FPGAs. Thanks to the numerous independent computations included, e.g., in homomorphic evaluations of block ciphers, this approach is likely to improve both throughput and latency. While this is conceptually a simple approach, it may still face difficulties because data needs to be transferred between multiple FPGAs. The third option is to divide different parts of a homomorphic multiplication to different FPGAs and perform them in a pipelined fashion in order to increase throughput. The fourth option is to mix the other three options and it may lead to good tradeoffs that avoid the disadvantages of the other options. The techniques represented in this paper can be extrapolated to support these options.

The SIMD approach achieves high throughput, but it has been argued that low latency can be more important in practice [29]. The leading software implementation [29] requires as much as 200 s for a single slot evaluation of SIMON32/64 with YASHE. Our FPGA-based implementation achieves smaller latencies even for SIMON-64/128 with an implementation that allows 2048 slots. Reducing the number of slots to one would allow more efficient parameters (see Sect. 2). We plan to investigate such schemes in the future.

We evaluated the performance of our architecture for YASHE by providing performance values for SIMON in order to provide straightforward comparisons to the leading software implementation from [29]. However, SIMON is not necessarily an optimal cipher for FHE purposes. For instance, the low-latency Prince cipher [5] may lead to better performance [19]. FHE-friendly symmetric encryption that is designed to minimize the multiplicative size and depth can offer significant improvements over SIMON (and Prince) [2,9]. Our architecture is able to evaluate arbitrary functions (up to a certain multiplicative depth) and, hence, these options will be studied in the future. Performance can be further increased by tuning the parameters of the architecture for these specific functions. Such changes can be easily done because our architecture is highly flexible.

We presented the first FPGA implementation for function evaluation on homomorphically encrypted data. Although it already achieves competitive performance compared to leading software implementations, we see several ways to optimize the architecture and these issues will be explored further in the future. For instance, we can increase throughput of NTT by precomputing certain values. We used Barrett reduction for the primes but choosing 'nice' primes and optimizing reduction circuitries by hand could offer speedups. However, in that case the performance would be bounded by the worst prime and finding suitably many 'nice' primes may be challenging. The architecture uses simple data-flow and pipelining in order to keep high clock frequency, but it results in pipeline bubbles that increase the latencies of operations. A more elaborated data-flow could allow removing the pipeline bubbles and reducing the latencies. More research is required also in balancing the pipelines so that even higher clock frequencies can be achieved for the architecture. The architecture utilizes
parallelism on various levels and degrees of parallelism in different parts of the architecture should be fine-tuned to achieve optimal resource utilization and performance. Our source code is highly flexible and significant parts of it were generated with scripts. This allows us to perform parameter space explorations that will enable us to find more optimal parameters for the architecture.

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[^1]:    ${ }^{1}$ The dividend $c$ is a sum of $2^{16}$ integers, each in $\left[0,(q-1)^{2}\right]$ (2455-bit integers). Further growth by 14 bits is introduced by the polynomial modular reduction and 7 bits by the large-CRT computation.

