# Cryptanalysis of indistinguishability obfuscation using GGH13 without ideals 

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#### Abstract

Recently, Albrecht, Davidson, Larraia, and Pellet-Mary constructed a variant of the GGH13 without ideals and presented the distinguishing attacks in simplified branching program and obfuscation security models. However, it is not clear whether a variant of the CGH annihilation attack can be used to break an IO candidate using this new variant. This paper adaptively extends the CGH attack into the branch program obfuscator based on GGH13 without ideals. To achieve this goal, we introduce approximate eigenvalue of matrix and build a relationship between the determinant and the rank of a matrix with perturbation. Our result shows that the structural vulnerability of GGH13 encodings are beyond the presence of ideal.


Keywords: Cryptanalysis, obfuscation, multilinear maps, approximate eigenvalue

## 1 Introduction

Program obfuscation in cryptography makes programs unintelligible and keeps their functionality. All known construction of IO obfuscators [19,6,8,4,21,27,21] are based on the three candidate (resp. GGH13, CLT13 and GGH15) of graded encoding scheme (GES) [18,14,20,15,22]. Unfortunately, these GES have been proven to be vulnerable to zero attacks [18,12,9,5,23,16,13], attacks on the overstretched NTRU [1,11,24], and annihilation attacks [26,10].

To immune the above attacks, Garg et al. [21] constructed a provably secure obfuscation in a weak multilinear map model, whose aim is to prevent the annihilation attack. However, Chen, Gentry and Halevi (CGH) [10] showed that their immunization can not thwart the annihilation attack if the branch program obfuscator is input partionable. In fact, there does not exist the inputpartition problem for the constructions in $[21,17]$ since they respectively are used the dual-input introduced by [6] and stamping functions that can prevent any input partition [17]. On the other hand, Albrecht, Davidson, Larraia, and PelletMary (ADLP) [2] investigated a structural vulnerability of the GGH13 encoding scheme. They constructed a variant of the GGH13 without ideals and presented the distinguishing attacks in simplified branching program and obfuscation security models. However, it is not clear whether a variant of the CGH attack can be used to break an IO candidate using this new variant.

### 1.1 Our work

Our main contribution is to adaptively extend the CGH attack into the branch program obfuscator based on GGH13 without ideals. The framework of our attack directly follows that of the CGH attack. The core step in the CGH attack is to solve a basis of ideal, but we cannot perform this step since there are no ideal in the ADLP variant. Moreover, we cannot also find some exact ratios of the bundling scalars and distinguish the rank of a matrix because of the noise. In order to implement the attack, we solve some approximate ratios of the bundling scalars and build a relationship between the determinant and the rank of a matrix with noise. So, our result shows that the structural vulnerability of GGH13 encodings are beyond the presence of ideal.

Our second contribution is to introduce the approximate eigenvalues of matrix to solve the approximate ratios of the bundling scalars. In the variant of GGH13 without ideals [2], the multiplicative bundling scalars appear as an approximation factor. So, when solving the ratios of these bundling scalars in the variant IO, the diagonal matrix of the elements obtained from zero-testing has noisy. Consequently we can not directly apply the characteristic polynomial of matrix to get the ratios of the bundling scalars, and also can no longer compute their exact ratios. However, we observe that these matrices are diagonal dominated matrix with noise and their inverses are also diagonal dominated matrix with noise.

Our final contribution is to estimate the determinant of matrix with noise. Since in the IO using GGH13 without ideals each term of the matrices has noise, as a result these matrices are all full rank. So, we can no longer use the rank of matrix to distinguish two equivalent branch program obfuscators. But we observe that the magnitude of the noise of these matrices are "small" relative to the main component of matrix, consequently the determinant of matrix is also "small" if the matrix generated by these main components of the original matrix is not full rank. To this end, we build the relationship between the determinant and the rank of matrix.

Although in this paper the results on matrix apply only to the attack for the IO using GGH13 without ideals, we think that the applications of these matrix properties in other respects should also be possible.

Organization. In Section 2 we first recall some preliminaries. Then in Section 3 we give branch program using GGH13 without ideals. Finally in Section 4 and 5 , we respectively provide some matrix properties and describe cryptanalysis of IO based on GGH13 without ideals.

## 2 Preliminaries

### 2.1 Notations

Let $\mathbb{Z}, \mathbb{Q}, \mathbb{R}$ denote the ring of integers, the field of rational numbers, and the field of real numbers. Let $n$ be a positive integer and power of 2 . Notation $[n]$ denotes the set $\{1,2, \ldots, n\}$. Let $R=\mathbb{Z}[x] /\left\langle x^{n}+1\right\rangle, R_{q}=\mathbb{Z}_{q}[x] /\left\langle x^{n}+1\right\rangle$,
and $\mathbb{K}=\mathbb{Q}[x] /\left\langle x^{n}+1\right\rangle$. Vectors are denoted in bold lowercase (e.g. a), and matrices in bold uppercase (e.g. A). We denote by $a[j]$ the $j$-th entry of a vector a, and $A[i, j]$ the element of the $i$-th row and $j$-th column of $\mathbf{A}$. We denote by $\|\mathbf{a}\|_{2}($ abbreviated as $\|\mathbf{a}\|)$ the Euclidian norm of $\mathbf{a}$. For $\mathbf{A} \in R^{d \times d}$, we define $\|\mathbf{A}\|=\max \{\|A[i, j]\|, i, j \in[d]\}$, where $\|A[i, j]\|$ is the Euclidian norm corresponding to the coefficient vector of $A[i, j]$. Throughout this paper we will abuse notations on $R$ and $\mathbb{K}$, both as an element and as a norm, depending on the context.

Let $[a]_{q}$ denote the absolute minimum residual system, namely $[a]_{q}=a \bmod q \in$ $(-q / 2, q / 2]$. Similarly, for $\mathbf{a} \in \mathbb{Z}^{n}$ (or $a \in R$ ), $[\mathbf{a}]_{q}$ denotes each entry (or each coefficient) $a[j] \in(-q / 2, q / 2]$ of a (or $a)$.

Given $\mathbf{c} \in \mathbb{R}^{n}, \sigma>0$, the Gaussian distribution of a lattice $L$ is defined as $D_{L, \sigma, \mathbf{c}}=\rho_{\sigma, \mathbf{c}}(\mathbf{x}) / \rho_{\sigma, \mathbf{c}}(L)$ for $\mathbf{x} \in L$, where $\left.\rho_{\sigma, \mathbf{c}}(\mathbf{x})=\exp \left(-\pi\|\mathbf{x}-\mathbf{c}\|^{2} / \sigma^{2}\right)\right)$, $\rho_{\sigma, \mathbf{c}}(L)=\sum_{\mathbf{x} \in L} \rho_{\sigma, \mathbf{c}}(\mathbf{x})$. In the following, we will write $D_{L, \sigma, \mathbf{0}}$ as $D_{L, \sigma}$. We denote a Gaussian sample as $x \leftarrow D_{L, \sigma}$ (or $d \leftarrow D_{I, \sigma}$ ) over the lattice $L$ (or ideal lattice $I$ ).

An element $a \in R$ is called $\eta$-bounded if $\|a\|_{\infty} \leq \eta$. Moreover, it is easy to verify that for any $\eta$-bounded elements $a_{1}, \cdots a_{k} \in R$, the element $a=\prod_{i=1}^{k} a_{i}$ is $\left(n^{k-1} \eta\right)$-bounded. By the work of [25], the element $x \leftarrow D_{\mathbb{Z}^{n}, \sigma, \mathrm{c}}$ is $\sigma \sqrt{n}$-bounded with overwhelming probability. Therefore, we define the truncated Gaussian distribution $\bar{D}_{\mathbb{Z}^{n}, \sigma, \mathbf{c}}$ by sampling elements from $D_{\mathbb{Z}^{n}, \sigma, \mathbf{c}}$ and repeating any samples that are not $\sigma \sqrt{n}$-bounded.

### 2.2 Branching programs

Let $\lambda$ be the security parameter, $\kappa=\kappa(\lambda), l=l(\lambda)$ and $d=d(\lambda)$. Let inp : $[\kappa] \rightarrow[l]^{d}$ be some fixed 'input' function. All current obfuscators only consider branching programs with $d=1$ or $d=2[19,6]$.

Definition 2.1. A matrix branching program BP of length $\kappa$, input length $l$ and arity $d$ is defined as follows:

$$
\mathrm{BP}:=\left(\kappa, l, d, \operatorname{inp},\left\{\mathbf{A}_{k, x_{\operatorname{inp}(k)}}\right\}_{k \in[\kappa], \operatorname{inp}(k) \in\{0,1\}^{d}}\right),
$$

where $\mathbf{A}_{k, x_{\operatorname{inp}(k)}} \in\{0,1\}^{w \times w}$ and $|\operatorname{inp}(k)|=d$.
The branching program is associated with the function $f_{\mathrm{BP}}:\{0,1\}^{l} \rightarrow\{0,1\}$, defined as

$$
f_{\mathrm{BP}}(x)= \begin{cases}0, & \text { if } \prod_{k=1}^{\kappa} \mathbf{A}_{x_{k, \operatorname{inp}(k)}}=\mathbf{I} \\ 1, & \text { if } \prod_{k=1}^{k} \mathbf{A}_{x_{k, \operatorname{inp}(k)}} \neq \mathbf{I} .\end{cases}
$$

A branching program BP is input partionable if its input bits can be partitioned into two or more independent subsets. We need the following observation in [10].

Lemma 2.2 [10]. Let BP be an input-partitioned branching program, $[\kappa]=$ $X \| Y$. If $x, x^{\prime} \in\{0,1\}^{l}$ are two zeros of $f_{\mathrm{BP}}$ that differ only in bits that are
mapped to steps in $X$. Then the product of the matrices corresponding to $X$ generates the same result in the evaluation of BP on $x$ and $x^{\prime}$, namely $\prod_{k \in X} \mathbf{A}_{k, x_{\operatorname{inp}(k)}}=\prod_{k \in X} \mathbf{A}_{k, x_{\operatorname{inp}(k)}^{\prime}}$.

Similarly, if $x, x^{\prime} \in\{0,1\}^{l}$ are two zeros of $f_{\mathrm{BP}}$ that differ only in bits that are mapped to steps in $Y$, then $\prod_{k \in Y} \mathbf{A}_{k, x_{\operatorname{inp}(k)}}=\prod_{k \in Y} \mathbf{A}_{k, x_{\operatorname{inp}(k)}^{\prime}}$.

### 2.3 GGH13 without ideals

GGH13 overview. The encoding space of GGH13 is $R_{q}=R / q R$ where $q$ is some big integer, and its plaintext space $R_{g}=R / g R$ such that $g$ is a small element in $R$ and is kept secret. A GGH13 encoding takes the form $y=(e+r g) / z$ $\bmod q$, where $z$ is a random secret element in $R_{q}, e$ is the plaintext element and $r$ is some small random element.

The denominators $z$ enable the levels of the GGH13 scheme. In this paper, we only consider the asymmetric case of GGH13, that uses many different denominators $z_{i}$. We say the encoding $y$ is encoded at level $S_{i}$ if the denominator of $y$ is $z_{i}$. It is easy to see that additions and multiplications of encodings can be carried out if they satisfy some level restriction. Namely, adding encodings indexed at the same level $S_{i}$ generates an encoding at the level $S_{i}$, and multiplying two encodings, indexed at the level $S_{i}, S_{j}$ respectively, generates an encoding at level $S_{i} \cup S_{j}$.

The GGH13 scheme also provides a public zero-testing parameter $p_{z t}=$ $h \cdot \prod_{i=1}^{\kappa} z_{i} / g$, where $h \in R$ such that $\|h\| \ll q$. Given a top-level encoding $u$ indexed at level $[\kappa]$, one can determine whether $u$ encodes zero or not by computing $p_{z t} \cdot u$ and checking if the result is small.

However, a simplified candidate IO over GGH13 exists the annihilation attack introduced by Miles, Sahai and Zhandry [26]. That is, their work constructs two program that are functionally equivalent, and show how to efficiently distinguish between the obfuscator of these two programs by heuristically computing a basis of $\langle g\rangle$. Moreover, Chen, Gentry and Halevi [10] extend the annihilation attack in [26] to break the GGHRSW obfuscator over GGH13 when the branching program has input partitioning. These works are the first to construct a basis for the secret element $\langle g\rangle$.
GGH13 without ideals We describe a variant of GGH13 without ideals in [?]. Let $\chi=\bar{D}_{\mathbb{Z}^{n}, \sigma}$ be the error distribution. Let $e \in R$ be some non-zero element with small coefficients, $r \leftarrow \chi$. We sample $z_{i}$ uniformly from $R_{q}$ for $1 \leq i \leq \kappa$, and sample $\beta_{i}$ such that $\sqrt[\kappa+1]{q}<\left\|\beta_{i}\right\|_{\infty}<\sqrt[\kappa]{q}$.

An encoding of $e$ indexed at level $S_{i}$ takes the form $y=\left(e+r / \beta_{i}\right) / z_{i} \bmod q$, where $z_{i}, \beta_{i}$ enables the level structure. Obviously, the encodings also supports addition and multiplication operation. For addition, let $y_{1}, y_{2}$ be two encodings indexed at same level $S \subset[\kappa]$, then their sum results in the encoding $y=y_{1}+y_{2}$ at the level $S$. For multiplication, given two encodings $y_{1}, y_{2}$ at level $S_{1}, S_{2} \subset[\kappa]$ respectively, their product generates $y=y_{1} \cdot y_{2}$ at the level $S_{1} \cup S_{2}$.

In this variant, the zero-test parameter is defined as $p_{z t}=\prod_{i=1}^{\kappa} \beta_{i} z_{i}$. Similarly, given a top-level encoding $u$ at level $[\kappa$ ], one can determine whether $u$ encodes zero or not by computing $\delta=p_{z t} \cdot u$ and checking if the result $\delta$ is small.

## 3 BP Obfuscator using GGH13 without Ideals

Let $\mathrm{BP}:=\left(\kappa, l, d, \mathrm{inp},\left\{\mathbf{A}_{k, b}\right\}_{k \in[\kappa], b \in\{0,1\}}\right)$ be the branching program to be obfuscated, where directly using $d=1$ for notational simplicity. We obfuscate BP by GGHRSW [19] using instantiation of GGH13 without ideals as follows:

Step 1: Dummy branch. We introduce a "dummy branching program":

$$
\mathrm{BP}^{\prime}:=\left(\kappa, l, d, \mathrm{inp},\left\{\mathbf{A}_{k, b}^{\prime}\right\}_{k \in[\kappa], b \in\{0,1\}}\right),
$$

where every $\mathbf{A}_{k, b}^{\prime}=\mathbf{I}$ is the identity matrix in $\{0,1\}^{w \times w}$.
Step 2: Random diagonal entries and bookends. Let $s=2 m+w$, where $m=l+3$ in the original GGHRSW scheme.

For $k \in[k]$, we extend $w \times w$-dimensional matrices into $s \times s$-dimensional matrices

$$
\widehat{\mathbf{A}}_{k, b}=\left(\begin{array}{cc}
\mathbf{E}_{k, b} & 0 \\
0 & \mathbf{A}_{k, b}
\end{array}\right), \quad \widehat{\mathbf{A}}_{k, b}^{\prime}=\left(\begin{array}{cc}
\mathbf{E}_{k, b}^{\prime} & 0 \\
0 & \mathbf{A}_{k, b}^{\prime}
\end{array}\right),
$$

where the diagonal matrices $\mathbf{E}_{k, b}, \mathbf{E}_{k, b}^{\prime} \in R_{\sigma}^{2 m \times 2 m}$ are chosen uniformly at random from the plaintext space.

We also choose four "bookend" vectors as follows:

$$
\begin{aligned}
& \left\{\begin{array}{l}
\widehat{\mathbf{A}}_{0}=\left(0^{m}, \mathbf{e}_{0}, \mathbf{s}\right), \\
\widehat{\mathbf{A}}_{0}^{\prime}=\left(0^{m}, \mathbf{e}_{0}^{\prime}, \mathbf{s}^{\prime}\right),
\end{array}\right. \\
& \left\{\begin{array}{l}
\widehat{\mathbf{A}}_{\kappa+1}=\left(\mathbf{e}_{\kappa+1}, \mathbf{0}^{m}, \mathbf{t}\right)^{T}, \\
\widehat{\mathbf{A}}_{\kappa+1}^{\prime}=\left(\mathbf{e}_{\kappa+1}^{\prime}, \mathbf{0}^{m}, \mathbf{t}^{\prime}\right)^{T},
\end{array}\right.
\end{aligned}
$$

where $\mathbf{e}_{0}, \mathbf{e}_{0}^{\prime}, \mathbf{e}_{\kappa+1}, \mathbf{e}_{\kappa+1}^{\prime} \in R_{\sigma}^{m}$, and $\mathbf{s}, \mathbf{s}^{\prime}, \mathbf{t}, \mathbf{t}^{\prime} \in R_{\sigma}^{w}$ such that $\mathbf{s} \cdot \mathbf{t}^{T}=\mathbf{s}^{\prime} \cdot \mathbf{t}^{\prime T}$.
Step 3: Kilian randomization and bundling scalars. We first sample random scalars $\left\{\epsilon_{0}, \epsilon_{0}^{\prime}, \epsilon_{\kappa+1}, \epsilon_{\kappa+1}^{\prime}, \epsilon_{k, b}, \epsilon_{k, b}^{\prime} \leftarrow R_{\sigma}: k \in[\kappa], b \in\{0,1\}\right\}$ such that

$$
\begin{aligned}
\alpha_{j, b} & =\prod_{\mathrm{inp}(k)=j} \epsilon_{k, b}=\prod_{\mathrm{inp}(k)=j} \epsilon_{k, b}^{\prime} \\
\alpha_{0} & =\epsilon_{0} \epsilon_{\kappa+1}=\epsilon_{0}^{\prime} \epsilon_{\kappa+1}^{\prime}
\end{aligned}
$$

We then choose randomly unimodular matrices $\mathbf{P}_{0}, \mathbf{P}_{0}^{\prime}, \mathbf{P}_{k}, \mathbf{P}_{k}^{\prime} \in R_{q}^{s \times s}, k \in$ [ $\kappa$ ].

Finally we generate randomized matrices as follows:

$$
\begin{array}{lll}
\widetilde{\mathbf{A}}_{0}=\epsilon_{0} \widehat{\mathbf{A}}_{0} \mathbf{P}_{0}, & \widetilde{\mathbf{A}}_{k, b}=\epsilon_{k, b} \mathbf{P}_{k-1}^{-1} \widehat{\mathbf{A}}_{k, b} \mathbf{P}_{k}, & \widetilde{\mathbf{A}}_{\kappa+1}=\epsilon_{\kappa+1} \mathbf{P}_{\kappa}^{-1} \widehat{\mathbf{A}}_{\kappa+1} \\
\widetilde{\mathbf{A}}_{0}^{\prime}=\epsilon_{0}^{\prime} \widehat{\mathbf{A}}_{0}^{\prime} \mathbf{P}_{0}^{\prime}, & \widetilde{\mathbf{A}}_{k, b}^{\prime}=\epsilon_{k, b}^{\prime} \mathbf{P}_{k-1}^{\prime-1} \widehat{\mathbf{A}}_{k, b}^{\prime} \mathbf{P}_{k}^{\prime}, & \widetilde{\mathbf{A}}_{\kappa+1}^{\prime}=\epsilon_{\kappa+1}^{\prime} \mathbf{P}_{\kappa}^{\prime-1} \widehat{\mathbf{A}}_{\kappa+1}^{\prime}
\end{array}
$$

where $k \in[\kappa], b \in\{0,1\}$
Step 4: Encoding using GGH13 without ideals. For $k=0, \cdots, \kappa+1$, we sample uniformly invertible random elements $z_{k}, z_{k}^{\prime} \in R_{q}$, and $\beta_{k} \in R$ such that $\sqrt[\kappa+3]{q}<\left\|\beta_{k}\right\|<\sqrt[\kappa+2]{q}$. We then choose at random vectors $\mathbf{R}_{0}, \mathbf{R}_{0}^{\prime}, \mathbf{R}_{\kappa+1}, \mathbf{R}_{\kappa+1}^{\prime} \in$ $R_{\sigma}^{s}$, and matrices $\mathbf{R}_{k, b}, \mathbf{R}_{k, b}^{\prime} \in R_{\sigma}^{s \times s}$, and set

$$
\begin{aligned}
& \left\{\begin{array}{l}
\overline{\mathbf{A}}_{0}=\left(\widetilde{\mathbf{A}}_{0}+\mathbf{R}_{0} / \beta_{0}\right) / z_{0} \\
\overline{\mathbf{A}}_{0}^{\prime}=\left(\widetilde{\mathbf{A}}_{0}^{\prime}+\mathbf{R}_{0}^{\prime} / \beta_{0}\right) / z_{0}^{\prime}
\end{array},\right. \\
& \left\{\begin{array}{l}
\overline{\mathbf{A}}_{k, b}=\left(\widetilde{\mathbf{A}}_{k, b}+\mathbf{R}_{k, b} / \beta_{k}\right) / z_{k} \\
\overline{\mathbf{A}}_{k, b}^{\prime}=\left(\widetilde{\mathbf{A}}_{k, b}^{\prime}+\mathbf{R}_{k, b}^{\prime} / \beta_{k}\right) / z_{k}^{\prime}
\end{array}, k \in[\kappa], b \in\{0,1\},\right. \\
& \left\{\begin{array}{l}
\overline{\mathbf{A}}_{\kappa+1}=\left(\widetilde{\mathbf{A}}_{\kappa+1}+\mathbf{R}_{\kappa+1} / \beta_{\kappa+1}\right) / z_{\kappa+1} \cdot p_{z t} \\
\overline{\mathbf{A}}_{\kappa+1}^{\prime}=\left(\widetilde{\mathbf{A}}_{\kappa+1}^{\prime}+\mathbf{R}_{\kappa+1}^{\prime} / \beta_{\kappa+1}\right) / z_{\kappa+1}^{\prime} \cdot p_{z t}^{\prime}
\end{array}\right.
\end{aligned}
$$

where $p_{z t}=\prod_{k=0}^{\kappa+1} \beta_{k} z_{k}$, and $p_{z t}^{\prime}=\prod_{k=0}^{\kappa+1} \beta_{k} z_{k}^{\prime}$.
Step 5: Output the obfuscation of BP. The obfuscation $\overline{\mathrm{BP}}$ consists of the following matrices and vectors:

$$
\left\{\begin{array}{l}
\left\{\overline{\mathbf{A}}_{0},\left\{\overline{\mathbf{A}}_{k, b}\right\}_{k \in[\kappa], b \in\{0,1\}}, \overline{\mathbf{A}}_{\kappa+1}\right\}, \\
\left\{\overline{\mathbf{A}}_{0}^{\prime},\left\{\overline{\mathbf{A}}_{k, b}^{\prime}\right\}_{k \in[\kappa], b \in\{0,1\}}, \overline{\mathbf{A}}_{\kappa+1}^{\prime}\right\} .
\end{array}\right.
$$

Remark 1. (1) We can take $z_{k}=z_{k}^{\prime}$ for all $k$ and hence $p_{z t}=p_{z t}^{\prime}$.
(2) To perform Kilian randomization, we use the unimodular matrices $\mathbf{P}_{k}, \mathbf{P}_{k}^{\prime}$. Because $\left\|\mathbf{P}_{k}^{-1} \bmod \beta_{k}\right\| \approx \beta_{k}$ for $k \in[\kappa]$ when choosing randomly $\mathbf{P}_{k}$. That is, by a change of variable transformation we cannot rewrite the encodings as

$$
\overline{\mathbf{A}}_{k, b}=\left(\epsilon_{k, b} \mathbf{P}_{k-1}^{-1} \widehat{\mathbf{A}}_{k, b} \mathbf{P}_{k}+\mathbf{R}_{k, b} / \beta_{k}\right) / z_{k}=\left(\epsilon_{k, b} \mathbf{P}_{k-1}^{-1}\left(\widehat{\mathbf{A}}_{k, b}+\mathbf{R}_{k, b}^{\prime} / \beta_{k}\right) \mathbf{P}_{k}\right) / z_{k}
$$

In this case, $\left\|\mathbf{R}_{k, b}^{\prime}\right\| \approx \beta_{k}$. This point is different from the GGH13 encoding since $g$ is small and hence so $\left\|\mathbf{P}_{k}^{-1} \bmod g\right\|$.
(3) Alternatively, for choosing randomly $\mathbf{P}_{k}$ we can also use its adjugate matrix $\operatorname{adj}\left(\mathbf{P}_{k}\right)$ instead of $\mathbf{P}_{k}^{-1}$.

Evaluation. Given the obfuscation $\overline{\mathrm{BP}}$ and an arbitrary input $\mathbf{x} \in\{0,1\}^{l}$, we compute an honest evaluation as follows:

$$
\begin{aligned}
\delta & =\overline{\mathbf{A}}_{0} \cdot \prod_{k=1}^{\kappa} \overline{\mathbf{A}}_{k, x_{\operatorname{inp}(k)}} \cdot \overline{\mathbf{A}}_{\kappa+1} \\
& =\left(\beta_{0} \widetilde{\mathbf{A}}_{0}+\mathbf{R}_{0}\right) \cdot \prod_{k=1}^{\kappa}\left(\beta_{k} \widetilde{\mathbf{A}}_{k, x_{\operatorname{inp}(k)}}+\mathbf{R}_{k, x_{\operatorname{inp}(k)}}\right) \cdot\left(\beta_{\kappa+1} \widetilde{\mathbf{A}}_{\kappa+1}+\mathbf{R}_{\kappa+1}\right), \\
& =\alpha \beta \cdot \mathbf{s} \prod_{k=1}^{\kappa} \mathbf{A}_{k, x_{i n p(k)}} \mathbf{t}^{T}+o(\beta) \\
\delta^{\prime} & =\overline{\mathbf{A}}_{0}^{\prime} \cdot \prod_{k=1}^{\kappa} \overline{\mathbf{A}}_{k, x_{\operatorname{inp}(k)}^{\prime}}^{\prime} \cdot \overline{\mathbf{A}}_{\kappa+1}^{\prime} \\
& =\left(\beta_{0} \widetilde{\mathbf{A}}_{0}^{\prime}+\mathbf{R}_{0}^{\prime}\right) \cdot \prod_{k=1}^{\kappa}\left(\beta_{k} \widetilde{\mathbf{A}}_{k, x_{\operatorname{inp}(k)}^{\prime}}^{\prime}+\mathbf{R}_{k, x_{\operatorname{inp}(k)}^{\prime}}^{\prime}\right) \cdot\left(\beta_{\kappa+1} \widetilde{\mathbf{A}}_{\kappa+1}^{\prime}+\mathbf{R}_{\kappa+1}^{\prime}\right), \\
& =\alpha \beta \cdot \mathbf{s}^{\prime} \mathbf{t}^{\prime T}+o(\beta)
\end{aligned}
$$

where $\alpha=\prod_{j=1}^{l} \alpha_{j, x_{j}}$ and $\beta=\prod_{j=0}^{\kappa+1} \beta_{j}$.
If $\prod_{k=1}^{\kappa} \mathbf{A}_{k, x_{i n p(k)}}=\mathbf{I}$, then $\left\|\delta-\delta^{\prime}\right\|<q^{\frac{\kappa+1}{\kappa+2}}$ and $\overline{\mathrm{BP}}(\mathbf{x})=1$. Otherwise, $\overline{\mathrm{BP}}(\mathrm{x})=0$.

## 4 Matrix Properties

In this section, we give some matrix properties. Let $\gamma, \delta$ be positive numbers such that $\delta / \gamma=\operatorname{negl}(\lambda)$. For simplicity, we denote $R_{\mathbf{A}}[i]=\sum_{j \neq i}|A[i, j]|$ in the following. Similarly, we write $R_{\mathbf{A}}[i]=\sum_{j \neq i}\left\|\mathbf{A}_{i, j}\right\|$ when $\mathbf{A}_{i, j}$ are matrices.

A permutation $p=\left(p_{1}, p_{2}, \cdots, p_{n}\right)$ of the numbers $(1,2, \cdots, n)$ is any rearrangement. The parity of a permutation $p$ is the one of the number of interchanges to restore $p$ to natural order. Consequently, the sign of a permutation $p$ is defined to be the number

$$
\pi(p)= \begin{cases}+1 & \text { if the parity of } p \text { is even } \\ -1 & \text { if the parity of } p \text { is odd }\end{cases}
$$

Given a $n \times n$-dimensional matrix $\mathbf{A}=(A[i, j])$, the determinant of $A$ is defined to be the scalar

$$
\begin{equation*}
\operatorname{det}(\mathbf{A})=\sum_{p} \pi(p) \prod_{i=1}^{n} A\left[i, p_{i}\right] \tag{1}
\end{equation*}
$$

where the sum is taken over the $n$ ! permutations $p$ of $(1,2, \cdots, n)$.
Lemma 4.1 Determinant Inequality. Suppose that $\mathbf{A}$ is an $n \times n$-dimensional matrix over $\mathbb{Q}$ such that $\gamma \leq|A[i, j]| \leq c \gamma$ for $i, j \in[n]$, where $\gamma>2^{\lambda}$ and $c>1$. Then with overwhelming probability

$$
\gamma^{n} \leq|\operatorname{det}(\mathbf{A})| \leq n!(c \gamma)^{n}
$$

Proof. According to the definition of determinant (1),

$$
\begin{aligned}
|\operatorname{det}(\mathbf{A})| & =\left|\sum_{p} \pi(p) \prod_{i=1}^{n} A\left[i, p_{i}\right]\right| \\
& =\gamma^{n} \cdot\left|\sum_{p} \pi(p) \prod_{i=1}^{n} \frac{A\left[i, p_{i}\right]}{\gamma}\right| \\
& =\gamma^{n} \cdot\left|\sum_{p} \pi(p) A_{p}\right|
\end{aligned}
$$

where $A_{p}=\prod_{i=1}^{n} \frac{A\left[i, p_{i}\right]}{\gamma}$.

By $\gamma \leq|A[i, j]| \leq c \gamma$, we obtain $\left|\frac{A\left[i, p_{i}\right]}{\gamma}\right| \geq 1$ and $1 \leq\left|A_{p}\right| \leq c^{n}$. According to Chernoff-Hoefding inequality, $\left|\sum_{p} \pi(p) A_{p}\right| \geq 1$ with overwhelming probability.
On the other hand, $\left|\sum_{p} \pi(p) A_{p}\right| \leq \sum_{p}|\pi(p)| c^{n}=n!c^{n}$.
Definition 4.2 Matrix Decomposition ( $\mathrm{MD}_{\gamma, \delta}$ ). The decomposition $\mathbf{A}=\mathbf{A}_{1}+\mathbf{A}_{\delta}$ is called $\mathrm{MD}_{\gamma, \delta}$ if $\mathbf{A}_{1}, \mathbf{A}_{\delta}$ are satisfied

$$
\begin{aligned}
& \left|A_{1}[i, j]\right|=\Theta(\gamma), \text { for all } i, j \in[n] \\
& \left|A_{\delta}[i, j]\right|=O(\delta), \text { for all } i, j \in[n] .
\end{aligned}
$$

Lemma 4.3 Determinant Estimation I. Suppose that $\mathbf{A}=\mathbf{A}_{1}+\mathbf{A}_{\delta}$ is $\operatorname{MD}_{\gamma, \delta}$ and $\operatorname{rank}\left(\mathbf{A}_{1}\right)<n$. Then $|\operatorname{det}(\mathbf{A})| \leq O\left(n \cdot n!\cdot \delta \gamma^{n-1}\right)$. In particular, $|\operatorname{det}(\mathbf{A})|=O\left(\delta \gamma^{n-1}\right)$ when $n$ is constant.

Proof. By the definition of determinant (1),

$$
\operatorname{det}(\mathbf{A})=\sum_{p} \pi(p) \prod_{i=1}^{n} A\left[i, p_{i}\right]=\sum_{p} \pi(p) \prod_{i=1}^{n}\left(A_{1}\left[i, p_{i}\right]+A_{\delta}\left[i, p_{i}\right]\right)
$$

By $\operatorname{rank}\left(\mathbf{A}_{1}\right)<n$, $\operatorname{det}\left(\mathbf{A}_{1}\right)=0$. That is, $\sum_{p} \pi(p) \prod_{i=1}^{n} A_{1}\left[i, p_{i}\right]=0$.
We expand $\operatorname{det}(\mathbf{A})$ as follows:

$$
\begin{aligned}
\operatorname{det}(\mathbf{A}) & =\sum_{p} \pi(p) \prod_{i=1}^{n}\left(A_{1}\left[i, p_{i}\right]+A_{\delta}\left[i, p_{i}\right]\right) \\
& =\sum_{p} \pi(p)(\underbrace{\sum_{j=1}^{n} A_{\delta}\left[j, p_{j}\right] \prod_{i \neq j} A_{1}\left[i, p_{i}\right]}_{B_{p}}+o\left(B_{p}\right))
\end{aligned}
$$

So, $|\operatorname{det}(\mathbf{A})| \leq \sum_{p} \pi(p) \sum_{j=1}^{n} O\left(\left|A_{\delta}\left[j, p_{j}\right] \prod_{i \neq j} A_{1}\left[i, p_{i}\right]\right|\right) \leq O\left(n \cdot n!\cdot \delta \gamma^{n-1}\right)$.
Furthermore, $|\operatorname{det}(\mathbf{A})| \leq O\left(\delta \gamma^{n-1}\right)$ when $n$ is constant.
Remark 4.4. Lemma 4.1 and 4.3 are not contradictory. Because the matrix $\mathbf{A}$ in Lemma 4.1 is randomly sampled, whereas the matrix $\mathbf{A}$ in Lemma 4.3 has a special structure such that the rank of the dominant matrix in its matrix decomposition is less than $n$.

In Lemma 4.3, if we assume that the submatrix generated by the linearly independent vectors of $\mathbf{A}_{1}$ satisfies the condition of Lemma 4.1. Namely, the determinant of the square matrix obtained by this submatrix can be estimated by applying Lemma 4.1. Accordingly, we can further improve the results in Lemma 4.3. Note that the result of Lemma 4.5 is not used in this paper.

Lemma 4.5 Determinant Estimation II. Suppose that $\mathbf{A}=\mathbf{A}_{1}+\mathbf{A}_{\delta}$ is $\operatorname{MD}_{\gamma, \delta}$ and $\operatorname{rank}\left(\mathbf{A}_{1}\right)=k<n$. Then $|\operatorname{det}(\mathbf{A})| \leq n!\left(\gamma+\delta^{\prime}\right)^{k}\left(\delta^{\prime}\right)^{n-k}$, where
$\delta^{\prime}=n k!c^{k} \delta$ and c is a constant that depends on A. Furthermore, $|\operatorname{det}(\mathbf{A})| \leq$ $O\left(\delta^{n-k} \gamma^{k}\right)$ when $n$ is constant.

Proof. Assume that the first $k$ rows of $\mathbf{A}_{1}$ are linearly independent since $\operatorname{rank}\left(\mathbf{A}_{1}\right)=k$. So, the last $n-k$ rows of $\mathbf{A}_{1}$ are linearly dependent its first $k$ rows. That is, for $j \in\{k+1, \cdots, n\}, A_{1}[j, \cdot]=\sum_{i=1}^{k} y_{j}[i] A_{1}[i, \cdot]$.

For simplicity, we write this relationship as matrix-vector form

$$
A_{1}[j, \cdot]=\mathbf{y}_{j} \mathbf{A}_{1}^{\prime}=\mathbf{y}_{j}\left(\mathbf{B}_{1}, \mathbf{B}_{2}\right)
$$

where $\mathbf{A}_{1}^{\prime}=A_{1}[1 / / k]$, and $\mathbf{B}_{1}=A_{1}^{\prime}[1: k], \mathbf{B}_{2}=A_{1}^{\prime}[k+1: n]$.
Let $\mathbf{B}_{1, i}=\left(B_{1}[1 / / i-1] / / A_{1}[j, \cdot] / / B_{1}[i+1 / / k]\right)$ for $i \in[k]$. By Cramer's rule, we find $y_{j}[i]=\frac{\operatorname{det}\left(\mathbf{B}_{1, i}\right)}{\operatorname{det}\left(\mathbf{B}_{1}\right)}$.

We have $c_{1} \gamma \leq\left|A_{1}[i, j]\right| \leq c_{2} \gamma$ since $\left|A_{1}[i, j]\right|=\Theta(\gamma)$, and then using Lemma 4.1,

$$
\begin{aligned}
\left(c_{1} \gamma\right)^{k} & \leq\left|\operatorname{det}\left(\mathbf{B}_{1}\right)\right| \leq k!\left(c_{2} \gamma\right)^{k} \\
\left(c_{1} \gamma\right)^{k} & \leq\left|\operatorname{det}\left(\mathbf{B}_{1, i}\right)\right| \leq k!\left(c_{2} \gamma\right)^{k}
\end{aligned}
$$

Hence, for $j \in\{k+1, \cdots, n\}, i \in[k], \frac{1}{k!c^{k}}<y_{j}[i]<k!c^{k}$ where $c=c_{2} / c_{1}$.
Now, we set

$$
\begin{aligned}
\mathbf{Y} & =\left(\begin{array}{cccc}
y_{k+1}[1] & y_{k+1}[2] & \cdots & y_{k+1}[k] \\
y_{k+2}[1] & y_{k+2}[2] & \cdots & y_{k+2}[k] \\
\vdots & \vdots & \cdots & \vdots \\
y_{n}[1] & y_{n}[2] & \cdots & y_{n}[k]
\end{array}\right), \\
\mathbf{P} & =\left(\begin{array}{cc}
\mathbf{I}_{k} & \mathbf{0} \\
-\mathbf{Y} & \mathbf{I}_{n-k}
\end{array}\right) .
\end{aligned}
$$

Therefore,

$$
\mathbf{P A}=\mathbf{P} \mathbf{A}_{1}+\mathbf{P} \mathbf{A}_{\delta}=\binom{\mathbf{A}_{1}^{\prime}}{\mathbf{0}}+\mathbf{A}_{\delta^{\prime}}
$$

By $\mathbf{A}_{\delta^{\prime}}=\mathbf{P} \mathbf{A}_{\delta}$, we get $\left|A_{\delta^{\prime}}[i, j]\right|=\left|\sum_{k=1}^{n} P[i, k] A_{\delta}[k, j]\right| \leq n k!c^{k} \delta$ and then $\delta^{\prime}=n k!c^{k} \delta$.

By the definition of determinant (1),

$$
\begin{aligned}
\operatorname{det}(\mathbf{A}) & =\operatorname{det}(\mathbf{P A}) \\
& =\operatorname{det}\left(\binom{\mathbf{A}_{1}^{\prime}}{\mathbf{0}}+\mathbf{A}_{\delta^{\prime}}\right) \\
& =\sum_{p} \pi(p) \prod_{i=1}^{k}\left(A_{1}\left[i, p_{i}\right]+A_{\delta^{\prime}}\left[i, p_{i}\right]\right) \prod_{i=k+1}^{n} A_{\delta^{\prime}}\left[i, p_{i}\right]
\end{aligned}
$$

Since $\left|A_{1}\left[i, p_{i}\right]\right| \leq \gamma$ and $A_{\delta^{\prime}}\left[i, p_{i}\right] \leq \delta^{\prime}$, thus

$$
|\operatorname{det}(\mathbf{A})| \leq n!\left(\gamma+\delta^{\prime}\right)^{k}\left(\delta^{\prime}\right)^{n-k}
$$

Obviously, $|\operatorname{det}(\mathbf{A})| \leq O\left(\delta^{n-k} \gamma^{k}\right)$ when $n$ is constant.
Definition 4.6 Approximate Eigenvalue. Let $\mathbf{A}=\mathbf{A}_{1}+\mathbf{A}_{\delta}$ be a $(\gamma, \delta)$ matrix decomposition. The eigenvalues of $\mathbf{A}$ is defined as the approximate eigenvalues of $\mathbf{A}_{1}$.

Definition 4.7 Diagonally Dominant Matrix (DDM). An $n \times n$-dimensional matrix $A$ is diagonally dominant if for all $i \in[k]$,

$$
|A[i, i]| \geq R_{\mathbf{A}}[i] .
$$

If using a strict inequality ( $>$ ) instead $(\geq)$ in the definition 4.1 , then $A$ is called strict diagonally dominant matrix (SDDM).

Definition $4.8(\gamma, \delta)$-Diagonally Dominant Matrix ( $\mathbf{D D M}_{\gamma, \delta}$ ). A is a $(\gamma, \delta)$-diagonally dominant matrix if $\mathbf{A}$ is satisfied

$$
|A[i, j]|= \begin{cases}O(\gamma), & \text { if } i=j \\ O(\delta), & \text { if } i \neq j\end{cases}
$$

Lemma 4.9. Suppose that $\mathbf{A}$ is a $\mathrm{DDM}_{\gamma, \delta}$ matrix. Then $\mathbf{A}^{-1}$ is a $\mathrm{DDM}_{\gamma^{-1}, n \delta / \gamma^{-2}}$ matrix.

Proof. Since $\mathbf{A}$ is a $\mathrm{DDM}_{\gamma, \delta}$ matrix, we can write $\mathbf{A}=\mathbf{A}_{1}+\mathbf{A}_{\delta}$ such that

$$
\begin{aligned}
& \mathbf{A}_{1}=\operatorname{Diag}(A[1,1], \cdots, A[n, n]), \\
& \mathbf{A}_{\delta}= \begin{cases}0, & \text { if } i=j \\
A[i, j], & \text { if } i \neq j .\end{cases}
\end{aligned}
$$

So, $\mathbf{A}_{1}^{-1}=\operatorname{Diag}\left(A^{-1}[1,1], \cdots, A^{-1}[n, n]\right)$. Without loss of generality, assume $\gamma_{\max }^{-1}=\max _{i \in[n]}\left\{A^{-1}[i, i]\right\}=O\left(\gamma^{-1}\right)$.

By $\left\|\mathbf{A}_{1}^{-1} \mathbf{A}_{\delta}\right\| \leq\left\|\mathbf{A}_{1}^{-1}\right\|\left\|\mathbf{A}_{\delta}\right\| \leq O\left(n \gamma_{\max }^{-1} \delta\right)=O\left(n \gamma^{-1} \delta\right) \ll 1$, we have

$$
\begin{aligned}
\mathbf{A}^{-1} & =\left(\mathbf{A}_{1}+\mathbf{A}_{\delta}\right)^{-1} \\
& =\left(\mathbf{I}+\mathbf{A}_{1}^{-1} \mathbf{A}_{\delta}\right)^{-1} \mathbf{A}_{1}^{-1} \\
& =\left(\mathbf{I}-\mathbf{A}_{1}^{-1} \mathbf{A}_{\delta}+\left(\mathbf{A}_{1}^{-1} \mathbf{A}_{\delta}\right)^{2}-\cdots\right) \mathbf{A}_{1}^{-1} \\
& =\mathbf{A}_{1}^{-1}+\mathbf{A}_{\delta^{\prime}}
\end{aligned}
$$

where $\mathbf{A}_{\delta^{\prime}}=\left(-\mathbf{A}_{1}^{-1} \mathbf{A}_{\delta}+\left(\mathbf{A}_{1}^{-1} \mathbf{A}_{\delta}\right)^{2}-\cdots\right) \mathbf{A}_{1}^{-1}$.
Again,

$$
\begin{aligned}
\left\|\mathbf{A}_{\delta^{\prime}}\right\| & \left.\leq\left\|\mathbf{A}_{1}^{-1} \mathbf{A}_{\delta}\right\|+\left\|\left(\mathbf{A}_{1}^{-1} \mathbf{A}_{\delta}\right)^{2}\right\|-\cdots\right)\left\|\mathbf{A}_{1}^{-1}\right\| \\
& =\sum_{i=1}^{\infty}\left(O\left(n \gamma^{-1} \delta\right)\right)^{i} O\left(\gamma^{-1}\right) \\
& =\frac{O\left(n \gamma^{-1} \delta\right)}{1-O\left(n \gamma^{-1} \delta\right)} O\left(\gamma^{-1}\right) \\
& =O\left(n \delta \gamma^{-2}\right) .
\end{aligned}
$$

Consequently, $\left|\mathbf{A}_{\delta^{\prime}}[i, j]\right|=O\left(n \delta \gamma^{-2}\right)$ for all $i, j \in[n]$, and hence

$$
\left|\mathbf{A}^{-1}[i, j]\right|= \begin{cases}O\left(\gamma^{-1}\right), & \text { if } i=j \\ O\left(n \delta \gamma^{-2}\right), & \text { if } i \neq j\end{cases}
$$

Therefore $\mathbf{A}^{-1}$ is a $\mathrm{DDM}_{\gamma^{-1}, n \delta / \gamma^{-2}}$ matrix.
Remark 4.10. Although the results of all lemmas above are given on the rational number field $\mathbb{Q}$, these results can be directly extended to the field $\mathbb{K}=$ $\mathbb{Q}[x] /\langle f(x)\rangle$. Note that in this case we require to use the norm of the elements in $\mathbb{K}$, instead of absolute value over $\mathbb{Q}$.

## 5 Cryptanalysis

Since the ADLP variant no longer uses ideals, as a result we cannot obtain a basis of the ideal $\beta_{k}$ as that of the CGH attack. Moreover, we cannot also find some exact representatives of the bundling scalars. However, we can recover some approximate ratios of the bundling scalars using some matrix properties in the above section. Applying these approximate ratios, we can extend the CGH attack to the ADLP variant.

### 5.1 Branching program with input partitioning

We first adaptively recall the branching program with input partitioning in [10]. Let $X\|Y\| Z=[\kappa]$ be a 3 -partition of the branching program steps. For a 3partition input $u=x y z$, we use $\mathbf{S}_{x}$ (resp. $\mathbf{S}_{y}, \mathbf{S}_{z}$ ) to denote the plaintext product matrix of function branch in the $X($ resp. $Y, Z)$ interval, and $\mathbf{S}_{x}^{\prime}\left(\right.$ resp. $\left.\mathbf{S}_{y}^{\prime}, \mathbf{S}_{z}^{\prime}\right)$ the plaintext product matrix of dummy branch in the $X$ (resp. $Y, Z$ ) interval. That is, for the function branch we have

$$
\begin{aligned}
\mathbf{S}_{x} & =\widetilde{\mathbf{A}}_{0} \prod_{k \in X} \widetilde{\mathbf{A}}_{k, u_{\operatorname{inp}(k)}}=\alpha_{x} \widehat{\mathbf{A}}_{0} \times \prod_{k \in X} \widehat{\mathbf{A}}_{k, u_{\operatorname{inp}(k)}} \times \mathbf{P}_{y_{1}} \\
& =\alpha_{x} \widehat{\mathbf{A}}_{0} \times \widehat{\mathbf{A}}_{x} \times \mathbf{P}_{y_{1}} \\
\mathbf{S}_{y} & =\prod_{k \in Y} \widetilde{\mathbf{A}}_{k, u_{\operatorname{inp}(k)}}=\alpha_{y} \mathbf{P}_{y_{1}}^{-1} \times \prod_{k \in Y} \widehat{\mathbf{A}}_{k, u_{\operatorname{inp}(k)}} \times \mathbf{P}_{z_{1}} \\
& =\alpha_{y} \mathbf{P}_{y_{1}}^{-1} \times \widehat{\mathbf{A}}_{y} \times \mathbf{P}_{z_{1}} \\
\mathbf{S}_{z} & =\prod_{k \in Z} \widetilde{\mathbf{A}}_{k, u_{\operatorname{inp}(k)}} \times \widetilde{\mathbf{A}}_{\kappa+1}=\alpha_{z} \mathbf{P}_{z_{1}}^{-1} \times \prod_{k \in Z} \widehat{\mathbf{A}}_{k, u_{\mathrm{inp}(k)}} \times \widehat{\mathbf{A}}_{\kappa+1} \\
& =\alpha_{z} \mathbf{P}_{z_{1}}^{-1} \times \widehat{\mathbf{A}}_{z} \times \widehat{\mathbf{A}}_{\kappa+1}
\end{aligned}
$$

Similarly, for the dummy branch we have

$$
\begin{aligned}
\mathbf{S}_{x}^{\prime} & =\widetilde{\mathbf{A}}_{0}^{\prime} \prod_{k \in X} \widetilde{\mathbf{A}}_{k, u_{\operatorname{inp}(k)}^{\prime}}^{\prime}=\alpha_{x}^{\prime} \widehat{\mathbf{A}}_{0}^{\prime} \times \prod_{k \in X} \widehat{\mathbf{A}}_{k, u_{\operatorname{inp}(k)}^{\prime}}^{\prime} \times \mathbf{P}_{y_{1}}^{\prime} \\
& =\alpha_{x}^{\prime} \widehat{\mathbf{A}}_{0}^{\prime} \times \widehat{\mathbf{A}}_{x}^{\prime} \times \mathbf{P}_{y_{1}}^{\prime} \\
\mathbf{S}_{y}^{\prime} & =\prod_{k \in Y} \widetilde{\mathbf{A}}_{k, u_{i n p}(k)}^{\prime}=\alpha_{y}^{\prime} \mathbf{P}_{y_{1}}^{\prime-1} \times \prod_{k \in Y} \widehat{\mathbf{A}}_{k, u_{\operatorname{inp}(k)}^{\prime}}^{\prime} \times \mathbf{P}_{z_{1}}^{\prime} \\
& =\alpha_{y}^{\prime} \mathbf{P}_{y_{1}}^{\prime-1} \times \widehat{\mathbf{A}}_{y}^{\prime} \times \mathbf{P}_{z_{1}}^{\prime} \\
\mathbf{S}_{z}^{\prime} & =\prod_{k \in Z} \widetilde{\mathbf{A}}_{k, u_{i n p}(k)}^{\prime} \times \widetilde{\mathbf{A}}_{\kappa+1}^{\prime}=\alpha_{z}^{\prime} \mathbf{P}_{z_{1}}^{\prime-1} \times \prod_{k \in Z} \widehat{\mathbf{A}}_{k, u_{i n p}(k)}^{\prime} \times \widehat{\mathbf{A}}_{\kappa+1}^{\prime} \\
& =\alpha_{z}^{\prime} \mathbf{P}_{z_{1}}^{\prime-1} \times \widehat{\mathbf{A}}_{z}^{\prime} \times \widehat{\mathbf{A}}_{\kappa+1}^{\prime}
\end{aligned}
$$

where the scalars $\alpha_{x}, \alpha_{y}, \alpha_{z}$, etc are the product of all the $\epsilon_{k, b}$ in the corresponding branch, and $y_{1}=|X|$ and $z_{1}=|X||Y|$.

For these bundling scalars $\alpha_{x}, \alpha_{y}, \alpha_{z}$, etc, we require the following observation.

Lemma 5.1 (Lemma 2.3 [10]). Suppose that $u^{(i, j, t)}=x^{(i)} y^{(j)} z^{(t)}$ are some 3-partition inputs that are all zeros of the function. Then $\alpha_{x^{(1)}} / \alpha_{x^{\prime(1)}}=$ $\alpha_{x^{(2)}} / \alpha_{x^{\prime(2)}}=\cdots$, and similarly $\alpha_{y^{(1)}} / \alpha_{y^{\prime(1)}}=\alpha_{y^{(2)}} / \alpha_{y^{\prime(2)}}=\cdots$ and $\alpha_{z^{(1)}} / \alpha_{z^{\prime}(1)}=$ $\alpha_{z^{(2)}} / \alpha_{z^{\prime(2)}}=\cdots$.

### 5.2 Generating approximate ratios of the bundling scalars

Without loss of generality, we assume that the branching program is 3-partitioned. Let $u^{(i, b, j)}=x^{(i)} y^{(b)} z^{(j)}$ be a 3-partition input of the form $X\|Y\| Z$ that is an input of a zero of the function. Let $i, j$ range over $2 s$ inputs and for $b \in\{0,1\}$, we first obtain the matrices:

$$
\begin{aligned}
\mathbf{W}_{b}= & \mathbf{X} \mathbf{Y}_{b} \mathbf{Z} \\
= & \binom{\beta_{X} \mathbf{S}_{x^{(i)}}+\mathbf{R}_{x^{(i)}},-\beta_{X} \mathbf{S}_{x^{(i)}}^{\prime}+\mathbf{R}_{x^{(i)}}^{\prime}}{\cdots} \\
& \left(\begin{array}{cc}
\beta_{Y} \mathbf{S}_{y^{(b)}}+\mathbf{R}_{y^{(b)}}, & 0 \\
0 & \beta_{Y} \mathbf{S}_{y^{(b)}}^{\prime}+\mathbf{R}_{y^{(b)}}^{\prime}
\end{array}\right)\binom{\cdots, \beta_{Z} \mathbf{S}_{z^{(j)}}+\mathbf{R}_{z^{(j)}}, \cdots}{\beta_{Z} \mathbf{S}_{z^{(j)}}^{\prime}+\mathbf{R}_{z^{(j)}}^{\prime}},
\end{aligned}
$$

where $\mathbf{X}, \mathbf{Y}_{b}, \mathbf{Z} \in R^{2 s \times 2 s}$ are full rank with high probability, and $\beta_{X}$ (resp. $\beta_{Y}$ and $\beta_{Z}$ ) is $\prod_{k \in X} \beta_{k}$ (resp. $\prod_{k \in Y} \beta_{k}$ and $\prod_{k \in Z} \beta_{k}$ ).

Then we compute the characteristic polynomial of $\mathbf{W}_{1} \mathbf{W}_{0}^{-1}$ in $\mathbb{K}$ that is equal to the characteristic polynomial of $\mathbf{Y}_{1} \mathbf{Y}_{0}^{-1}$.

Now we analyze $\mathbf{Y}_{1} \mathbf{Y}_{0}^{-1}$ in $\mathbb{K}$ as follows:

$$
\mathbf{Y}_{1} \mathbf{Y}_{0}^{-1}=\left(\begin{array}{cc}
\beta_{Y} \mathbf{S}_{y^{(1)}}+\mathbf{R}_{y^{(1)}}, & 0 \\
0 & \beta_{Y} \mathbf{S}_{y^{(1)}}^{\prime}+\mathbf{R}_{y^{(1)}}^{\prime}
\end{array}\right)\left(\begin{array}{cc}
\beta_{Y} \mathbf{S}_{y^{(0)}}+\mathbf{R}_{y^{(0)}}, & 0 \\
0 & \beta_{Y} \mathbf{S}_{y^{(0)}}^{\prime}+\mathbf{R}_{y^{(0)}}^{\prime}
\end{array}\right)^{-1}
$$

According to the ADLP encoding, we get $\left\|\mathbf{R}_{y^{(1)}}\right\|=o\left(\beta_{Y}\right)$ and hence by Lemma 4.9 we compute for the function branching part of $\mathbf{Y}_{1} \mathbf{Y}_{0}^{-1}$

$$
\begin{aligned}
& \left(\beta_{Y} \mathbf{S}_{y^{(1)}}+\mathbf{R}_{y^{(1)}}\right)\left(\beta_{Y} \mathbf{S}_{y^{(0)}}+\mathbf{R}_{y^{(0)}}\right)^{-1} \\
= & \left(\beta_{Y} \alpha_{y^{(1)}} \mathbf{P}_{y_{1}}^{-1} \widehat{\mathbf{A}}_{y^{(1)}} \mathbf{P}_{z_{1}}+\mathbf{R}_{y^{(1)}}\right)\left(\beta_{Y} \alpha_{y^{(0)}} \mathbf{P}_{y_{1}}^{-1} \widehat{\mathbf{A}}_{y^{(0)}} \mathbf{P}_{z_{1}}+\mathbf{R}_{y^{(0)}}\right)^{-1} \\
= & \frac{\alpha_{y^{(1)}}}{\alpha_{y^{(0)}}} \mathbf{P}_{y_{1}}^{-1}\left(\widehat{\mathbf{A}}_{y^{(1)}} \widehat{\mathbf{A}}_{y^{(0)}}^{-1}\right) \mathbf{P}_{y_{1}}+O\left(\beta_{Y}^{-1}\right) \mathbf{R} \\
= & \frac{\alpha_{y^{(1)}}}{\alpha_{y^{(0)}}} \mathbf{P}_{y_{1}}^{-1}\left(\begin{array}{cc}
\mathbf{E}_{y^{(1)}} & 0 \\
0 & \mathbf{A}_{y^{(1)}}
\end{array}\right)\left(\begin{array}{cc}
\mathbf{E}_{y^{(0)}} & 0 \\
0 & \mathbf{A}_{y^{(0)}}
\end{array}\right)^{-1} \mathbf{P}_{y_{1}}+O\left(\beta_{Y}^{-1}\right) \mathbf{R} \\
= & \frac{\alpha_{y^{(1)}}}{\alpha_{y^{(0)}}} \mathbf{P}_{y_{1}}^{-1}\left(\begin{array}{cc}
\mathbf{E}_{y^{(1)}} \mathbf{E}_{y^{(0)}}^{-1} & 0 \\
0 & \mathbf{A}_{y^{(1)}} \mathbf{A}_{y^{(0)}}^{-1}
\end{array}\right) \mathbf{P}_{y_{1}}+O\left(\beta_{Y}^{-1}\right) \mathbf{R} \\
\approx & \frac{\alpha_{y^{(1)}}}{\alpha_{y^{(0)}}} \mathbf{P}_{y_{1}}^{-1}\left(\begin{array}{cc}
\mathbf{E}_{y^{(1)}} \mathbf{E}_{y^{(0)}}^{-1} & 0 \\
0 & \mathbf{A}_{y^{(1)}} \mathbf{A}_{y^{(0)}}^{-1}
\end{array}\right) \mathbf{P}_{y_{1}},
\end{aligned}
$$

where $\mathbf{R} \approx \alpha_{y^{(1)}} \mathbf{P}_{y_{1}}^{-1} \widehat{\mathbf{A}}_{y^{(1)}} \mathbf{P}_{z_{1}} \mathbf{R}_{y^{(0)}}+\alpha_{y^{(0)}} \mathbf{R}_{y^{(1)}} \mathbf{P}_{y_{1}}^{-1} \widehat{\mathbf{A}}_{y^{(0)}} \mathbf{P}_{z_{1}}+O\left(\beta_{Y}^{-1}\right) \mathbf{R}_{y^{(1)}} \mathbf{R}_{y^{(0)}}$.
By Lemma 2.2, $\mathbf{A}_{y^{(1)}} \mathbf{A}_{y^{(0)}}^{-1}=\mathbf{I}^{w \times w}$, hence $\frac{\alpha^{(1)}}{\alpha_{y^{(0)}}} \in \mathbb{K}$ is an approximate eigenvalue of the function branch part of multiplicity at least $w$. Likewise, $\frac{\alpha_{y}^{\prime}(1)}{\alpha_{y}^{\prime}(0)} \in$ $\mathbb{K}$ is an approximate eigenvalue of the dummy branch of multiplicity at least $w$. Again by Lemma 5.1, $\frac{\alpha_{y}(1)}{\alpha_{y}(0)}=\frac{\alpha_{y}^{\prime}(1)}{\alpha_{y}^{\prime}(0)}$, therefore $\frac{\alpha_{y(1)}}{\alpha_{y^{(0)}}}$ is the approximate eigenvalue of $\mathbf{Y}_{1} \mathbf{Y}_{0}^{-1}$ of multiplicity at least $2 w$.

Thus, we can find all roots of the characteristic polynomial of $\mathbf{W}_{1} \mathbf{W}_{0}^{-1}$ in $\mathbb{K}$ and consider at least $2 w$ approximately equal roots as the approximate value of $\frac{\alpha_{y(1)}}{\alpha_{y}(0)}$.

Remark 5.2. We observe that for two inputs $\mathbf{x}, \mathbf{x}^{\prime} \in\{0,1\}^{l}$ that differ only in $x_{i}=1$ and $x_{i}^{\prime}=0$, if the branching program evaluates to zero for them, that is $\delta_{x}=\alpha_{x} \beta \cdot \mathbf{s t}^{T}+o(\beta)$ and $\delta_{x^{\prime}}=\alpha_{x^{\prime}} \beta \cdot \mathbf{s t}^{T}+o(\beta)$, then $\frac{\alpha_{i, 1}}{\alpha_{i, 0}} \approx \frac{\delta_{x}}{\delta_{x^{\prime}}}$ since $\left\|\delta_{x}\right\|,\left\|\delta_{x^{\prime}}\right\|<q$. The advantage of this attack method is that it has no regard to the input-partition of the branch program. However, it is not difficult to avoid this attack by setting $\|\beta\| \geq q$.

### 5.3 Annihilation attack

Chen, Gentry and Halevi have extended the annihilation attack in [26] to break GGH13-based branching program obfuscators with the padded random diagonal entries by using the ratios of the bundling scalars. Here we will further extend the CGH attack to break the branching program obfuscators based on GGH13 without ideals by applying the approximate ratios of the bundling scalars.

To describe our attack, we also use the running example used by Chen, Gentry and Halevi.

Example 5.3 (Example 3.1 [10]). The two programs $B, B^{\prime}$ have the identity matrix for both 0 and 1 in all the steps except for the two steps $u, w$ that are a permutation matrix $P$ and its inverse $P^{-1}$ for $B^{\prime}$. Here we require the steps $u, v, w$ belong to the interval $Y$ such that $u<v<w$ and the input bit $j_{2}$ does not control any steps before $u$ or after $w$. The programs $B, B^{\prime}$ that compute the constant-zero function concretely define as follows:

| $B=$ | $0:$ | $\mathbf{I}$ | $\cdots$ | $\mathbf{I}$ | $\mathbf{I}$ | $\mathbf{I}$ | $\mathbf{I}$ | $\mathbf{I}$ | $\cdots$ | $\mathbf{I}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | $1:$ | $\mathbf{I}$ | $\cdots$ | $\mathbf{I}$ | $\mathbf{I}$ | $\mathbf{I}$ | $\mathbf{I}$ | $\mathbf{I}$ | $\cdots$ | $\mathbf{I}$ |
| $B^{\prime}=$ | $0:$ | $\mathbf{I}$ | $\cdots$ | $\mathbf{I}$ | $\mathbf{I}$ | $\mathbf{I}$ | $\mathbf{I}$ | $\mathbf{I}$ | $\cdots$ | $\mathbf{I}$ |
|  | $1:$ | $\mathbf{I}$ | $\cdots$ | $\mathbf{I}$ | $\mathbf{P}$ | $\mathbf{I}$ | $\mathbf{P}^{-1}$ | $\mathbf{I}$ | $\cdots$ | $\mathbf{I}$ |
| Steps | $0:$ |  | $X$ |  | $u$ | $v$ | $w$ |  | $Z$ |  |
| Input bits | $1:$ | $*$ | $\cdots$ | $*$ | $j_{1}$ | $j_{2}$ | $j_{1}$ | $*$ | $\cdots$ | $*$ |

In the above subsection, we can solve the approximate ratios $\alpha_{1} / \alpha_{0}$ and $\alpha_{1}^{\prime} / \alpha_{0}^{\prime}$. Since these ratios are approximate, consequently we cannot compute four scalars $v_{0}, v_{1}, \zeta_{00}, \zeta_{11} \in R$ as that in [10]. However, we here are working on $\mathbb{K}$, not $\bmod \langle g\rangle$ and hence we can take

$$
v_{0}=1, v_{1} \approx \alpha_{1}^{\prime} / \alpha_{0}^{\prime} \quad \text { and } \quad \zeta_{00}=1, \zeta_{11} \approx \alpha_{1} \alpha_{1}^{\prime} / \alpha_{0} \alpha_{0}^{\prime}
$$

We let $u_{\mu \nu}^{i, j}=x^{(i)} \mu \nu z^{(j)}$ an input for a zero of the function, where $x^{(i)}$ is the bits controlled in the step interval $X, \mu \nu$ the two distinguished bits controlled in the step interval $Y$, and $z^{(j)}$ the bits controlled in the step interval $Z$. We denote by $\operatorname{Eval}\left(u_{\mu \nu}^{i, j}\right)$ the value returned by evaluating the obfuscated branching program on the input $u_{\mu \nu}^{i, j}$ :

$$
\begin{aligned}
\operatorname{Eval}\left(u_{\mu \nu}^{i, j}\right) & =\overline{\mathbf{A}}_{0} \cdot \prod_{k=1}^{\kappa} \overline{\mathbf{A}}_{k, x_{\operatorname{inp}(k)}} \cdot \overline{\mathbf{A}}_{\kappa+1}-\overline{\mathbf{A}}_{0}^{\prime} \cdot \prod_{k=1}^{\kappa} \overline{\mathbf{A}}_{k, x_{\operatorname{inp}(k)}^{\prime}}^{\prime} \cdot \overline{\mathbf{A}}_{\kappa+1}^{\prime} \\
& =\left(\beta_{0} \widetilde{\mathbf{A}}_{0}+\mathbf{R}_{0}\right) \cdot \prod_{k=1}^{\kappa}\left(\beta_{k} \widetilde{\mathbf{A}}_{k, x_{\operatorname{inp}(k)}}+\mathbf{R}_{\left.k, x_{\operatorname{inp}(k)}\right)}\right) \cdot\left(\beta_{\kappa+1} \widetilde{\mathbf{A}}_{\kappa+1}+\mathbf{R}_{\kappa+1}\right) \\
& -\left(\beta_{0} \widetilde{\mathbf{A}}_{0}^{\prime}+\mathbf{R}_{0}^{\prime}\right) \cdot \prod_{k=1}^{\kappa}\left(\beta_{k} \widetilde{\mathbf{A}}_{k, x_{\operatorname{inp}(k)}^{\prime}}^{\prime}+\mathbf{R}_{k, x_{\operatorname{inp}(k)}}^{\prime}\right) \cdot\left(\beta_{\kappa+1} \widetilde{\mathbf{A}}_{\kappa+1}^{\prime}+\mathbf{R}_{\kappa+1}^{\prime}\right)
\end{aligned}
$$

To perform our attack, we choose many different inputs $u_{\mu \nu}^{i, j}$ that are all zeros of the function and for each $i, j$ we compute

$$
\begin{aligned}
A[i, j]= & \operatorname{Eval}\left(u_{11}^{i, j}\right) \cdot \zeta_{00} \cdot v_{1} v_{0}-\operatorname{Eval}\left(u_{10}^{i, j}\right) \cdot \zeta_{00} \cdot v_{1} v_{1} \\
& -\operatorname{Eval}\left(u_{01}^{i, j}\right) \cdot \zeta_{11} \cdot v_{0} v_{0}-\operatorname{Eval}\left(u_{00}^{i, j}\right) \cdot \zeta_{11} \cdot v_{0} v_{1},
\end{aligned}
$$

where all the computations are operated in $\mathbb{K}$.
In the following, we will first analyze the rank of the submatrix corresponding to the interval $Y$ in the matrix $\mathbf{A}$. Then we show that matrix $\mathbf{A}$ has non-full rank matrix decomposition for the program $B$. Finally, we describe a distinguishing attack between $B$ and $B^{\prime}$.

### 5.4 Analysis

### 5.4.1 The Matrix $D_{Y}$

Assume that the step interval $Y$ only includes the steps $u, v, w$ and $\mu \nu \in\{0,1\}^{2}$ are any two input bits corresponding to $Y$. For simplicity, let $\bar{\beta}=\max _{0 \leq k \leq \kappa+1}\left\{\beta_{k}\right\}$, which means $\bar{\beta}$ is the maximum norm element of $\beta_{k}$. Let $|Y|$ be the number of the elements of $Y$. We also denote by $\beta_{u v}=\beta_{u} \beta_{v}$, and similarly for $\beta_{u w}, \beta_{v w}$.

Then the matrix in the function branch of $Y$ has the form

$$
\begin{aligned}
& \mathbf{A}_{Y}= \prod_{k \in Y}\left(\beta_{k} \widetilde{\mathbf{A}}_{k, x_{\operatorname{inp}(k)}}+\mathbf{R}_{k, x_{\operatorname{inp}(k)}}\right) \\
&=\left(\beta_{u} \widetilde{\mathbf{A}}_{u, \mu}+\mathbf{R}_{u, \mu}\right)\left(\beta_{v} \widetilde{\mathbf{A}}_{v, \nu}+\mathbf{R}_{v, \nu}\right)\left(\beta_{w} \widetilde{\mathbf{A}}_{w, \mu}+\mathbf{R}_{w, \mu}\right) \\
&= \alpha_{\mu} \alpha_{\nu}^{\prime} \cdot \mathbf{P}_{u-1}^{-1} \cdot(\beta_{u} \widehat{\mathbf{A}}_{u, \mu}+\underbrace{\frac{1}{\epsilon_{u, \mu}} \mathbf{P}_{u-1} \mathbf{R}_{u, \mu} \mathbf{P}_{u}^{-1}}_{:=\widehat{\mathbf{R}}_{u, \mu}})(\beta_{v} \widehat{\mathbf{A}}_{v, \nu}+\underbrace{\frac{1}{\epsilon_{v, \nu}} \mathbf{P}_{u} \mathbf{R}_{v, \nu} \mathbf{P}_{v}^{-1}}_{:=\widehat{\mathbf{R}}_{v, \nu}}) \\
&(\beta_{w} \widehat{\mathbf{A}}_{w, \mu}+\underbrace{\frac{1}{\epsilon_{w, \mu}} \mathbf{P}_{v} \mathbf{R}_{w, \mu} \mathbf{P}_{w}^{-1}}_{:=\widehat{\mathbf{R}}_{w, \mu}}) \cdot \mathbf{P}_{w}^{-1} \\
&=\alpha_{\mu} \alpha_{\nu}^{\prime} \cdot \mathbf{P}_{u-1}^{-1} \cdot(\underbrace{\beta_{Y} \widehat{\mathbf{A}}_{u, \mu} \widehat{\mathbf{A}}_{v, \nu} \widehat{\mathbf{A}}_{w, \mu}}_{:=\mathbf{C}_{Y}^{\mu \nu}} \\
& \quad+(\underbrace{\beta_{u w} \widehat{\mathbf{A}}_{u, \mu} \widehat{\mathbf{R}}_{v, \nu} \widehat{\mathbf{A}}_{w, \mu}+\beta_{u v} \widehat{\mathbf{A}}_{u, \mu} \widehat{\mathbf{A}}_{v, \nu} \widehat{\mathbf{R}}_{w, \mu}+\beta_{v w} \widehat{\mathbf{R}}_{u, \mu} \widehat{\mathbf{A}}_{v, \nu} \widehat{\mathbf{A}}_{w, \mu}}_{Y}) \\
&\left.+O\left(\bar{\beta}^{|Y|-2}\right) \mathbf{E}_{Y}^{\mu \nu}\right) \cdot \mathbf{P}_{w} \\
&=\alpha_{\mu} \alpha_{\nu}^{\prime} \cdot \mathbf{P}_{u-1}^{-1} \cdot\left(\mathbf{C}_{Y}^{\mu \nu}+\mathbf{D}_{Y}^{\mu \nu}+O(\bar{\beta}) \mathbf{E}_{Y}^{\mu \nu}\right) \cdot \mathbf{P}_{w},
\end{aligned}
$$

where all the computations above are operated in $\mathbb{K}$.
By $\mathbf{D}_{Y}^{\mu \nu}$ we define

$$
\begin{aligned}
\mathbf{D}_{Y}= & \mathbf{D}_{Y}^{11}-\mathbf{D}_{Y}^{10}-\mathbf{D}_{Y}^{01}+\mathbf{D}_{Y}^{00} \\
= & \left(\beta_{u w} \widehat{\mathbf{A}}_{u, 1} \widehat{\mathbf{R}}_{v, 1} \widehat{\mathbf{A}}_{w, 1}+\beta_{u v} \widehat{\mathbf{A}}_{u, 1} \widehat{\mathbf{A}}_{v, 1} \widehat{\mathbf{R}}_{w, 1}+\beta_{v w} \widehat{\mathbf{R}}_{u, 1} \widehat{\mathbf{A}}_{v, 1} \widehat{\mathbf{A}}_{w, 1}\right) \\
& -\left(\beta_{u w} \widehat{\mathbf{A}}_{u, 1} \widehat{\mathbf{R}}_{v, 0} \widehat{\mathbf{A}}_{w, 1}+\beta_{u v} \widehat{\mathbf{A}}_{u, 1} \widehat{\mathbf{A}}_{v, 0} \widehat{\mathbf{R}}_{w, 1}+\beta_{v w} \widehat{\mathbf{R}}_{u, 1} \widehat{\mathbf{A}}_{v, 0} \widehat{\mathbf{A}}_{w, 1}\right) \\
& -\left(\beta_{u w} \widehat{\mathbf{A}}_{u, 0} \widehat{\mathbf{R}}_{v, 1} \widehat{\mathbf{A}}_{w, 0}+\beta_{u v} \widehat{\mathbf{A}}_{u, 0} \widehat{\mathbf{A}}_{v, 1} \widehat{\mathbf{R}}_{w, 0}+\beta_{v w} \widehat{\mathbf{R}}_{u, 0} \widehat{\mathbf{A}}_{v, 1} \widehat{\mathbf{A}}_{w, 0}\right) \\
& +\left(\beta_{u w} \widehat{\mathbf{A}}_{u, 0} \widehat{\mathbf{R}}_{v, 0} \widehat{\mathbf{A}}_{w, 0}+\beta_{u v} \widehat{\mathbf{A}}_{u, 0} \widehat{\mathbf{A}}_{v, 0} \widehat{\mathbf{R}}_{w, 0}+\beta_{v w} \widehat{\mathbf{R}}_{u, 0} \widehat{\mathbf{A}}_{v, 0} \widehat{\mathbf{A}}_{w, 0}\right) .
\end{aligned}
$$

Now it is completely analogous to the method in [10] to show $\mathbf{D}_{Y} \in\left(\begin{array}{cc}* & * \\ * & 0^{w \times w}\end{array}\right)$ when evaluating $B$, but not whp when evaluating $B^{\prime}$.

Similarly, we can define the matrix $\mathbf{D}_{Y}^{\prime}$ in the dummy branch for the step interval $Y$, and use the same method to prove $\mathbf{D}_{Y}^{\prime} \in\left(\begin{array}{cc}* & * \\ * 0^{w \times w}\end{array}\right)$ regardless of whether the branch program is $B$ or $B^{\prime}$.

### 5.4.2 The Matrix A

To analyze A, we let $X=\left\{x_{1}, x_{2}, \cdots, x_{x}\right\}, Y=\{u, v, w\}, Z=\left\{z_{1}, z_{2}, \cdots, z_{z}\right\}$, and $\alpha_{x}^{i}, \alpha^{\prime \prime}{ }_{x}$ (resp. $\alpha_{z}^{j}, \alpha^{\prime j}{ }_{z}$ ) be the product of the bundling scalars corresponding to $X$ (resp. $Z$ ). Moreover, we have $\alpha_{x}^{i} \alpha_{z}^{j}=\alpha^{\prime i}{ }_{x}^{\prime \prime}{ }_{z}^{j}$ by Lemma 5.1 and denote this product by $\alpha_{(i, j)}$. We also write $\beta_{X_{k}}=\beta_{X} / \beta_{k}$ and $\beta_{Z_{k}}=\beta_{Z} / \beta_{k}$.

Now we simplify $\operatorname{Eval}\left(u_{\mu \nu}^{i, j}\right)$ as follows:

$$
\begin{aligned}
& \operatorname{Eval}\left(u_{\mu \nu}^{i, j}\right) \\
& =\alpha_{(i, j)} \alpha_{\mu} \alpha_{\nu}^{\prime} \cdot((\underbrace{\beta_{0} \widehat{\mathbf{A}}_{0}}_{:=\mathbf{C}_{0}}+\widehat{\mathbf{R}}_{0})\left(\mathbf{C}_{X}^{i}+\mathbf{D}_{X}^{i}+O\left(\bar{\beta}^{|X|-2}\right) \mathbf{E}_{X}^{i}\right) \\
& \left(\mathbf{C}_{Y}^{\mu \nu}+\mathbf{D}_{Y}^{\mu \nu}+O\left(\bar{\beta}^{|Y|-2}\right) \mathbf{E}_{Y}^{\mu \nu}\right)\left(\mathbf{C}_{Z}^{j}+\mathbf{D}_{Z}^{j}+O\left(\bar{\beta}^{|Z|-2}\right) \mathbf{E}_{Z}^{j}\right)(\underbrace{\beta_{\kappa+1} \widehat{\mathbf{A}}_{\kappa+1}}_{:=\mathbf{C}_{\kappa+1}}+\widehat{\mathbf{R}}_{\kappa+1}) \\
& -(\underbrace{\beta_{0} \widehat{\mathbf{A}}_{0}^{\prime}}_{:=\mathbf{C}_{0}^{\prime}}+\widehat{\mathbf{R}}_{0}^{\prime})\left(\mathbf{C}^{\prime}{ }_{X}+\mathbf{D}_{X}^{\prime i}+O\left(\bar{\beta}^{|X|-2}\right) \mathbf{E}_{X}^{\prime i}\right)\left(\mathbf{C}_{Y}^{\prime \mu \nu}+\mathbf{D}_{Y}^{\prime \mu \nu}+O\left(\bar{\beta}^{|Y|-2}\right) \mathbf{E}_{Y}^{\prime \mu \nu}\right) \\
& \left(\mathbf{C}^{\prime j}{ }_{Z}+\mathbf{D}^{\prime j}{ }_{Z}+O\left(\bar{\beta}^{|Z|-2}\right) \mathbf{E}_{Z}^{\prime j}\right)(\underbrace{\beta_{\kappa+1} \widehat{\mathbf{A}}_{\kappa+1}^{\prime}}_{:=\mathbf{C}_{\kappa+1}^{\prime}}+\widehat{\mathbf{R}}_{\kappa+1}^{\prime})) \\
& =\alpha_{(i, j)} \alpha_{\mu} \alpha_{\nu}^{\prime} \cdot\left(\mathbf{C}_{0}\left(\mathbf{C}_{X}^{i}+\mathbf{D}_{X}^{i}\right)\left(\mathbf{C}_{Y}^{\mu \nu}+\mathbf{D}_{Y}^{\mu \nu}\right)\left(\mathbf{C}_{Z}^{j}+\mathbf{D}_{Z}^{j}\right) \mathbf{C}_{\kappa+1}\right. \\
& +\widehat{\mathbf{R}}_{0} \mathbf{C}_{X}^{i} \mathbf{C}_{Y}^{\mu \nu} \mathbf{C}_{Z}^{j} \mathbf{C}_{\kappa+1}+\mathbf{C}_{0} \mathbf{C}_{X}^{i} \mathbf{C}_{Y}^{\mu \nu} \mathbf{C}_{Z}^{j} \widehat{\mathbf{R}}_{\kappa+1} \\
& -\mathbf{C}_{0}^{\prime}\left(\mathbf{C}^{\prime \prime}{ }_{X}+\mathbf{D}_{X}^{\prime i}\right)\left(\mathbf{C}_{Y}^{\prime \mu \nu}+\mathbf{D}_{Y}^{\prime \mu \nu}\right)\left(\mathbf{C}_{Z}^{\prime j}+\mathbf{D}_{Z}^{\prime j}\right) \mathbf{C}_{\kappa+1}^{\prime} \\
& \left.-\widehat{\mathbf{R}}_{0}^{\prime} \mathbf{C}_{X}^{i} \mathbf{C}_{Y}^{\prime \mu \nu} \mathbf{C}_{Z}^{\prime j} \mathbf{C}_{\kappa+1}^{\prime}-\mathbf{C}_{0}^{\prime} \mathbf{C}_{X}^{\prime i} \mathbf{C}_{Y}^{\prime \mu \nu} \mathbf{C}_{Z}^{\prime j} \widehat{\mathbf{R}}_{\kappa+1}^{\prime}+O\left(\bar{\beta}^{\kappa}\right)\right) \\
& =\alpha_{(i, j)} \alpha_{\mu} \alpha_{\nu}^{\prime} \cdot\left(\mathbf{C}_{0}\left(\mathbf{C}_{X}^{i} \mathbf{C}_{Y}^{\mu \nu} \mathbf{D}_{Z}^{j}+\mathbf{C}_{X}^{i} \mathbf{D}_{Y}^{\mu \nu} \mathbf{C}_{Z}^{j}+\mathbf{D}_{X}^{i} \mathbf{C}_{Y}^{\mu \nu} \mathbf{C}_{Z}^{j}\right) \mathbf{C}_{\kappa+1}\right. \\
& +\widehat{\mathbf{R}}_{0} \mathbf{C}_{X}^{i} \mathbf{C}_{Y}^{\mu \nu} \mathbf{C}_{Z}^{j} \mathbf{C}_{\kappa+1}+\mathbf{C}_{0} \mathbf{C}_{X}^{i} \mathbf{C}_{Y}^{\mu \nu} \mathbf{C}_{Z}^{j} \widehat{\mathbf{R}}_{\kappa+1} \\
& -\mathbf{C}_{0}^{\prime}\left(\mathbf{C}^{\prime i}{ }_{X} \mathbf{C}_{Y}^{\prime \mu \nu} \mathbf{D}^{\prime j}+\mathbf{C}_{X}^{\prime i} \mathbf{D}_{Y}^{\prime \mu \nu} \mathbf{C}_{Z}^{j j}+\mathbf{D}_{X}^{\prime i} \mathbf{C}_{Y}^{\prime \mu \nu} \mathbf{C}_{Z}^{\prime j}\right) \mathbf{C}_{\kappa+1}^{\prime} \\
& \left.-\widehat{\mathbf{R}}_{0}^{\prime} \mathbf{C}_{X}^{\prime i} \mathbf{C}_{Y}^{\prime \mu \nu} \mathbf{C}_{Z}^{\prime j} \mathbf{C}_{\kappa+1}^{\prime}-\mathbf{C}_{0}^{\prime} \mathbf{C}_{X}^{\prime i} \mathbf{C}_{Y}^{\prime \mu \nu} \mathbf{C}_{Z}^{\prime j} \widehat{\mathbf{R}}_{\kappa+1}^{\prime}+O\left(\bar{\beta}^{\kappa}\right)\right)
\end{aligned}
$$

In the above simplification, except for the unspecified small noise matrix $\mathbf{E}_{X}^{i}, \mathbf{E}_{X}^{\prime i}, \mathbf{E}_{Z}^{j}, \mathbf{E}_{Z}^{\prime j}$, we also use the following notation

$$
\begin{array}{ll}
\mathbf{C}_{X}^{i}=\beta_{X} \cdot \prod_{k \in X} \widehat{\mathbf{A}}_{k, u_{\operatorname{inp}(k)}}, & \mathbf{C}_{X}^{\prime}=\beta_{X} \cdot \prod_{k \in X} \widehat{\mathbf{A}}_{k, u_{\operatorname{inp}(k)}^{\prime}}^{\prime} \\
\mathbf{C}_{Z}^{j}=\beta_{Z} \cdot \prod_{k \in Z} \widehat{\mathbf{A}}_{k, u_{\operatorname{inp}(k)}}, & \mathbf{C}_{Z}^{\prime j}=\beta_{Z} \cdot \prod_{k \in Z} \widehat{\mathbf{A}}_{k, u_{\operatorname{inp}(k)}^{\prime}}
\end{array}
$$

$$
\begin{aligned}
& \mathbf{D}_{X}^{i}=\sum_{k \in X} \beta_{X_{k}} \cdot \widehat{\mathbf{A}}_{x_{1}, u_{\operatorname{inp}\left(x_{1}\right)}} \cdots \widehat{\mathbf{A}}_{k-1, u_{\operatorname{inp}(k-1)}} \widehat{\mathbf{R}}_{k, u_{\operatorname{inp}(k)}} \widehat{\mathbf{A}}_{k+1, u_{\operatorname{inp}(k+1)}} \cdots \widehat{\mathbf{A}}_{x_{x}, u_{\operatorname{inp}\left(x_{x}\right)}} \\
& {\mathbf{D}^{\prime}}^{i}{ }_{X}=\sum_{k \in X} \beta_{X_{k}} \cdot \widehat{\mathbf{A}}_{x_{1}, u_{\operatorname{inp}\left(x_{1}\right)}^{\prime}}^{\prime} \cdots \widehat{\mathbf{A}}_{k-1, u_{\text {inp }(k-1)}}^{\prime} \widehat{\mathbf{R}}_{k, u_{\text {inp }}(k)}^{\prime} \widehat{\mathbf{A}}_{k+1, u_{\text {inp }(k+1)}}^{\prime} \cdots \widehat{\mathbf{A}}_{x_{x}, u_{\text {inp }\left(x_{x}\right)}}^{\prime} \\
& \mathbf{D}_{Z}^{j}=\sum_{k \in Z} \beta_{Z_{k}} \cdot \widehat{\mathbf{A}}_{z_{1}, u_{\operatorname{inp}\left(z_{1}\right)}} \cdots \widehat{\mathbf{A}}_{k-1, u_{\operatorname{inp}(k-1)}} \widehat{\mathbf{R}}_{k, u_{\operatorname{inp}(k)}} \widehat{\mathbf{A}}_{k+1, u_{\operatorname{inp}(k+1)}} \cdots \widehat{\mathbf{A}}_{z_{z}, u_{\operatorname{inp}}\left(z_{z}\right)} \\
& \mathbf{D}_{Z}^{\prime j}=\sum_{k \in Z} \beta_{Z_{k}} \cdot \widehat{\mathbf{A}}_{z_{1}, u_{\text {inp }}\left(z_{1}\right)}^{\prime} \cdots \widehat{\mathbf{A}}_{k-1, u_{\text {inp }(k-1)}}^{\prime} \widehat{\mathbf{R}}_{k, u_{\text {inp }(k)}^{\prime}}^{\prime} \widehat{\mathbf{A}}_{k+1, u_{\text {inp }}(k+1)}^{\prime} \cdots \widehat{\mathbf{A}}_{z_{z}, u_{\text {inp }}\left(z_{z}\right)}^{\prime} .
\end{aligned}
$$

To simplify $A[i, j]$, we further define

$$
\begin{aligned}
\mathbf{C}_{Y} & =\mathbf{C}_{Y}^{11}-\mathbf{C}_{Y}^{10}-\mathbf{C}_{Y}^{01}+\mathbf{C}_{Y}^{00}, \quad \mathbf{C}_{Y}^{\prime}=\mathbf{C}_{Y}^{\prime 11}-\mathbf{C}_{Y}^{\prime 10}-\mathbf{C}_{Y}^{\prime 01}+\mathbf{C}_{Y}^{\prime 00} \\
\mathbf{x}_{i} & =\mathbf{C}_{0} \mathbf{C}_{X}^{i}, \quad \mathbf{x}_{i}^{\prime}=\mathbf{C}_{0}^{\prime} \mathbf{C}_{X}^{i}, \quad \mathbf{z}_{j}=\mathbf{C}_{Z}^{j} \mathbf{C}_{\kappa+1}, \quad \mathbf{z}_{j}^{\prime}=\mathbf{C}_{Z}^{\prime j} \mathbf{C}_{\kappa+1}^{\prime} \\
\mathbf{e}_{i} & =\mathbf{C}_{0} \mathbf{D}_{X}^{i}, \quad \mathbf{e}_{i}^{\prime}={\mathbf{C}_{0}^{\prime} \mathbf{D}_{X}^{\prime}}^{i}, \quad \mathbf{f}_{j}=\mathbf{D}_{Z}^{j} \mathbf{C}_{\kappa+1}, \quad \mathbf{f}_{j}^{\prime}=\mathbf{D}_{Z}^{\prime j} \mathbf{C}_{\kappa+1}^{\prime} \\
\mathbf{r}_{i} & =\widehat{\mathbf{R}}_{0} \mathbf{C}_{X}^{i}, \quad \mathbf{r}_{i}^{\prime}=\widehat{\mathbf{R}}_{0}^{\prime} \mathbf{C}_{X}^{\prime i}, \quad \mathbf{w}_{j}=\mathbf{C}_{Z}^{j} \widehat{\mathbf{R}}_{\kappa+1}, \quad \mathbf{w}_{j}^{\prime}=\mathbf{C}_{Z}^{\prime j} \widehat{\mathbf{R}}_{\kappa+1}^{\prime}
\end{aligned}
$$

By the definition of bundling scalars and their approximate ratios that we solve in the above subsection, we have

$$
\alpha_{1} \alpha_{1}^{\prime} \cdot \zeta_{00} \cdot v_{1} v_{0} \approx \alpha_{1} \alpha_{0}^{\prime} \cdot \zeta_{00} \cdot v_{1} v_{1} \approx \alpha_{0} \alpha_{1}^{\prime} \cdot \zeta_{11} \cdot v_{0} v_{0} \approx \alpha_{0} \alpha_{0}^{\prime} \cdot \zeta_{11} \cdot v_{0} v_{1}
$$

where the approximate accuracy is $O\left(\bar{\beta}^{-1}\right)$.
Thus, we can incorporate these approximate scalars into the matrices corresponding to $x^{(i)}$ and $z^{(j)}$ respectively and can rewrite $A[i, j]$ as follows:

$$
\begin{aligned}
A[i, j]= & (\underbrace{\mathbf{x}_{i} \mathbf{C}_{Y} \mathbf{z}_{j}+\mathbf{x}_{i} \mathbf{D}_{Y} \mathbf{z}_{j}+\mathbf{e}_{i} \mathbf{C}_{Y} \mathbf{z}_{j}+\mathbf{r}_{i} \mathbf{C}_{Y} \mathbf{z}_{j}+\mathbf{x}_{i} \mathbf{C}_{Y} \mathbf{w}_{j}}_{:=F[i, j]}) \\
& -(\underbrace{\mathbf{x}_{i}^{\prime} \mathbf{C}_{Y}^{\prime} \mathbf{z}_{j}^{\prime}+\mathbf{x}_{i}^{\prime} \mathbf{D}_{Y}^{\prime} \mathbf{z}_{j}^{\prime}+\mathbf{e}_{i}^{\prime} \mathbf{C}_{Y}^{\prime} \mathbf{z}_{j}^{\prime}+\mathbf{x}_{i}^{\prime} \mathbf{C}_{Y}^{\prime} \mathbf{z}_{j}^{\prime}+\mathbf{x}_{i}^{\prime} \mathbf{C}_{Y}^{\prime} \mathbf{w}_{j}^{\prime}}_{:=F^{\prime}[i, j]})+O\left(\bar{\beta}^{\kappa}\right)
\end{aligned}
$$

In the following we first analyze the matrix $\mathbf{F}$ generated by the term $F[i, j]$ from the function branch with $i, j \in[\xi]$, where $\xi \geq 2 m+1$.

According to the construction structure of BP , for program $B$ the vectors $\mathbf{x}_{i}, \mathbf{x}_{i}^{\prime}, \mathbf{e}_{i}, \mathbf{e}_{i}^{\prime}=\left(0^{m} \$^{m} \$ w\right), \mathbf{z}_{j}, \mathbf{z}_{j}^{\prime}, \mathbf{f}_{j}, \mathbf{f}_{j}^{\prime}=\left(\$^{m} 0^{m} \$ w\right)^{T}$, and the matrices

$$
\mathbf{C}_{Y}, \mathbf{C}_{Y}^{\prime} \in\left(\begin{array}{ccc}
\$^{m \times m} & 0^{m \times m} & 0^{m \times w} \\
0^{m \times m} & \$^{m \times m} & 0^{m \times w} \\
0^{m \times m} & 0^{m \times m} & 0^{w \times w}
\end{array}\right), \quad \mathbf{D}_{Y}, \mathbf{D}_{Y}^{\prime} \in\left(\begin{array}{ccc}
\$^{m \times m} & \$^{m \times m} & \$^{m \times w} \\
\$^{m \times m} & \$^{m \times m} & \$^{m \times w} \\
\$^{m \times m} & \$^{m \times m} & 0^{w \times w}
\end{array}\right)
$$

Moreover, for the program $B^{\prime}$ everything else is the same except that $\mathbf{D}_{Y}$ is arbitrary by the analysis of $\mathbf{D}_{Y}$ in the previous subsection.

Thus for $B$ we can write $\mathbf{F}$ by the block form and simplify it to determine its rank as follows:

$$
\begin{aligned}
& \mathbf{F}=\mathbf{X} \mathbf{C}_{Y} \mathbf{Z}+\mathbf{X} \mathbf{D}_{Y} \mathbf{Z}+\mathbf{E C} \mathbf{C}_{Y} \mathbf{Z}+\mathbf{R C}_{Y} \mathbf{Z}+\mathbf{X} \mathbf{C}_{Y} \mathbf{W} \\
& =\left(\begin{array}{lll}
0 & \mathbf{X}_{2} & \mathbf{X}_{3}
\end{array}\right)\left(\begin{array}{ccc}
\mathbf{C}_{1,1} & 0 & 0 \\
0 & \mathbf{C}_{2,2} & 0 \\
0 & 0 & 0
\end{array}\right)\left(\begin{array}{c}
\mathbf{Z}_{1} \\
0 \\
\mathbf{Z}_{3}
\end{array}\right)+\left(\begin{array}{lll}
0 & \mathbf{X}_{2} & \mathbf{X}_{3}
\end{array}\right)\left(\begin{array}{lll}
\mathbf{D}_{1,1} & \mathbf{D}_{1,2} & \mathbf{D}_{1,3} \\
\mathbf{D}_{2,1} & \mathbf{D}_{2,2} & \mathbf{D}_{2,3} \\
\mathbf{D}_{3,1} & \mathbf{D}_{3,2} & 0
\end{array}\right)\left(\begin{array}{c}
\mathbf{Z}_{1} \\
0 \\
\mathbf{Z}_{3}
\end{array}\right) \\
& +\left(0 \mathbf{E}_{2} \mathbf{E}_{3}\right)\left(\begin{array}{ccc}
\mathbf{C}_{1,1} & 0 & 0 \\
0 & \mathbf{C}_{2,2} & 0 \\
0 & 0 & 0
\end{array}\right)\left(\begin{array}{c}
\mathbf{Z}_{1} \\
0 \\
\mathbf{Z}_{3}
\end{array}\right)+\left(\mathbf{R}_{1} \mathbf{R}_{2} \mathbf{R}_{3}\right)\left(\begin{array}{ccc}
\mathbf{C}_{1,1} & 0 & 0 \\
0 & \mathbf{C}_{2,2} & 0 \\
0 & 0 & 0
\end{array}\right)\left(\begin{array}{c}
\mathbf{Z}_{1} \\
0 \\
\mathbf{Z}_{3}
\end{array}\right) \\
& +\left(\begin{array}{lll}
0 & \mathbf{X}_{2} & \mathbf{X}_{3}
\end{array}\right)\left(\begin{array}{ccc}
\mathbf{C}_{1,1} & 0 & 0 \\
0 & \mathbf{C}_{2,2} & 0 \\
0 & 0 & 0
\end{array}\right)\left(\begin{array}{l}
\mathbf{W}_{1} \\
\mathbf{W}_{2} \\
\mathbf{W}_{3}
\end{array}\right) \\
& =\left(\mathbf{X}_{2} \mathbf{D}_{2,1}+\mathbf{X}_{3} \mathbf{D}_{3,1}+\mathbf{R}_{1} \mathbf{C}_{1,1}\right) \mathbf{Z}_{1}+\mathbf{X}_{2}\left(\mathbf{D}_{2,3} \mathbf{Z}_{3}+\mathbf{C}_{2,2} \mathbf{W}_{2}\right)
\end{aligned}
$$

Since the rank of $\mathbf{Z}_{1}$ and $\mathbf{X}_{2}$ is at most $m$, consequently the $\operatorname{rank}$ of $\mathbf{F}$ is at most $2 m$.

However, the rank of $\mathbf{F}$ for $B^{\prime}$ is at least $2 m+1$ with high probability. Since $\mathbf{D}_{3,3}$ is non-zero block matrix, as a result $\mathbf{F}$ with high probability can not be decomposed into the sum of two matrices with rank $m$.

Furthermore, the rank of $\mathbf{F}^{\prime}$ for $B$ and $B^{\prime}$ is at most $2 m$. The analysis of $\mathbf{F}^{\prime}$ is exactly similar to the analysis of $\mathbf{F}$ for $B$.

Theorem 5.4. Let $\xi=4 m+1, \gamma=\bar{\beta}^{\kappa+1}$ and $\delta=\bar{\beta}^{\kappa}$. Suppose there exist sufficiently many inputs $u_{\mu \nu}^{i, j}$ that are all the zero of the function. Then when $m$ is constant, with high probability we have

$$
\text { the program is } \begin{cases}B^{\prime} & \text { if } \operatorname{det}(\mathbf{A})=O\left(\gamma^{\xi}\right) \\ B & \text { if } \operatorname{det}(\mathbf{A})=O\left(\gamma^{\xi-1} \delta\right)\end{cases}
$$

When $m=\operatorname{poly}(\lambda)$, we heuristically have

$$
\text { the program is } \begin{cases}B^{\prime} & \text { if } \operatorname{det}(\mathbf{A})=O\left(\xi!\cdot \gamma^{\xi}\right) \\ B & \text { if } \operatorname{det}(\mathbf{A})=O\left(\xi!\cdot \xi \gamma^{\xi-1} \delta\right)\end{cases}
$$

Proof. According to the analysis of $\mathbf{A}$, for $B$ we have

$$
\mathbf{A}=\underbrace{\mathbf{F}-\mathbf{F}^{\prime}}_{:=\mathbf{A}_{1}}+\underbrace{O\left(\bar{\beta}^{\kappa}\right) \mathbf{E}}_{:=\mathbf{A}_{\delta}}
$$

Thus, for $B$ there exists a $(\gamma, \delta)$-matrix decomposition $\mathbf{A}=\mathbf{A}_{1}+\mathbf{A}_{\delta}$. Since for $B$ the rank of $\mathbf{A}_{1}$ is at most $4 m<\xi$, consequently for a constant $m$ we have $\operatorname{det}(\mathbf{A})=O\left(\gamma^{\xi-1} \delta\right)$ by Lemma 4.3.

However, for $B^{\prime}$ with high probability there is no such $(\gamma, \delta)$-matrix decomposition with a non-full rank $\mathbf{A}_{1}$. Therefore when $m$ is constant we get $\operatorname{det}(\mathbf{A})=O\left(\gamma^{\xi}\right)$ for $B^{\prime}$ by Lemma 4.1.

For $m=\operatorname{poly}(\lambda)$ we heuristically assume the determinant of $\mathbf{A}$ is equal to $O\left(\xi!\cdot \gamma^{\xi}\right)$ if $\mathbf{A}$ has no $(\gamma, \delta)$-matrix decomposition with a non-full rank. Note that our experiment supports this heuristic assumption.

Therefore for $B$ we have $\operatorname{det}(\mathbf{A})=O\left(\xi!\cdot \xi \gamma^{\xi-1} \delta\right)$ by Lemma 4.3, and for $B^{\prime}$ the result directly follows the heuristic assumption.

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