# Elliptic Curves in Generalized Huff's Model 

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#### Abstract

This paper introduces elliptic curves in generalized Huff's model. These curves endowed with addition are shown to be a group over a finite field. We present formulae for point addition and doubling point on the curves and evaluate computational cost of point addition and doubling point using projective, Jacobian and Lopez-Dahab coordinates. It is noted that the computational cost for point addition and doubling on the curves is lower on the projective coordinates than the other mentioned above coordinates.


Keywords: Doubling points, elliptic curves, groups, Huff's model, projective coordinates, scalar multiplication.

## 1 Introduction

Elliptic curves are algebraic curves and have been widely studied in number theory and cryptography $[22,19,7,18,21]$. The study of elliptic curves could be of a variety of areas : Algebra, Algebraic Geometry, Number Theory, Diophantine problems and so on. Lang [25] mentions in his book that

> "It is possible to write endlessly on elliptic curves. (This is not a treat.)"

In 1995, Andrew Wiles proved the Fermat's Last Theorem using proof of the modularity conjecture for semistable elliptic curves [32]. The use of elliptic curves have commercialized and are studied intensively for its application in cryptography $[16,8,9]$.

The plane curves of degree 3 are known as cubics and have the general form of

$$
A x^{3}+B x^{2} y+C x y^{2}+D y^{3}+E x^{2}+F x y+G y^{2}+H x+I y+J=0
$$

Elliptic curves are non-singular cubic curves and have points defined over a field $\mathbb{K}[15,31]$.

In mid-1980s, Koblitz and Miller independently proposed Elliptic Curve Cryptography (ECC) using Elliptic Curve Discrete Logarithmic Problem (ECDLP) [23, 27]. The ECC provides better security when compared to Diffie-Hellman (DH) key exchange and Rivest-Shamir-Adlemen (RSA) algorithm using substantially lower key sizes but the arithmetic underlying group is more tedious, which makes the study particularly interesting for systems with confined computing power and memory [24].

Some of the famous forms of elliptic curves existing in literature are Weierstrass cubics [15, 31], Hessian curves [6, 21], Jacobi quartics [7], Montgomery [28, 29], Edwards [4, 5, 13] and Huff's curve [19]. There has been a lot of development to these models of elliptic curves, for instance Joye et al. studied Huff's model for elliptic curves in 2010 [22]. In the same year, Wu and Feng also carried out a research on Huff's curves in [14]. An year later, Binary Huff's curves were investigated by Devigne and Joye [12]. In 2015, He et al. [18] studied generalized Huff's curves. The different families of Huff's elliptic curves studied over the past decade are listed below.

1. The curves over a field $\mathbb{K}, \operatorname{char}(\mathbb{K}) \neq 2$ by Joye et al. in [22] are of the form of:

$$
a x\left(y^{2}-1\right)=b y\left(x^{2}-1\right), \text { where } a^{2}-b^{2} \neq 0
$$

2. The generalized Huff's curves over a field $\mathbb{K}, \operatorname{char}(\mathbb{K}) \neq 2$ by Joye et al. in [22] are of the form of:

$$
a x\left(y^{2}-d\right)=b y\left(x^{2}-d\right), \text { where } a b d\left(a^{2}-b^{2}\right) \neq 0
$$

3. The generalized Huff's curves over a field $\mathbb{K}, \operatorname{char}(\mathbb{K}) \neq 2$ by Wu and Feng in [14] are of the form of:

$$
x\left(a y^{2}-1\right)=y\left(b x^{2}-d\right), \text { where } a b(a-b) \neq 0,
$$

4. The binary Huff curves over a field $\mathbb{K}, \operatorname{char}(\mathbb{K})=2$ by Joye et al. in [22] are of the form of:

$$
a x\left(y^{2}+y+1\right)=b y\left(x^{2}+x+1\right), \text { where } a b(a-b) \neq 0,
$$

5. The generalized binary Huff curves over a field $\mathbb{K}, \operatorname{char}(\mathbb{K})=2$ by Joye et al. in [22] are of the form of:

$$
a x\left(y^{2}+f y+1\right)=b y\left(x^{2}+f x+1\right), \text { where } a b f(a-b) \neq 0
$$

6. The generalized Huff's curves over a field $\mathbb{K}$, $\operatorname{char}(\mathbb{K}) \neq 2$ by Ciss and Sow in [10] are of the form of:

$$
a x\left(y^{2}-c\right)=b y\left(x^{2}-d\right), \text { where } a b c d\left(a^{2} c-b^{2} d\right) \neq 0 .
$$

We can also find similar progress of other elliptic curves. For instance, after the introduction of Edwards curve in [13] by Harold Edwards, it became an active area of research resulting in an extensive literature $[3,4,5,11,20,1,2]$.

In this paper, we propose a generalization of Huff's model of elliptic curves over a field $\mathbb{K}, \operatorname{char}(\mathbb{K}) \neq 2$ which are of the form $E(\mathbb{K}): a x\left(y^{2}+x y+f\right)=b y\left(x^{2}+x y+g\right)$, where $a, b, f, g \in \mathbb{K}$ and $a b f g(a-b) \neq 0$, and under appropriate addition operation shows that these curves satisfy axioms of an abelian group. Furthermore, we provide formulae for point addition and doubling point in affine, projective, Jacobian and Lopez-Dahab coordinates, including an estimate of number of points on $E$ over a field $\mathbb{K}$, and evaluate computational cost in the each coordinate systems.

The rest of the paper is organized as follows. In Section 2, we show that the proposed generalized Huffs model curves is a commutative group over a finite field and give formulae for point addition and doubling points for affine, projective, Jacobian, and Lopez-Dahab coordinates, including an estimate of number of points on $E(\mathbb{K})$. Furthermore, we give computational costs and a comparison for different projective coordinates. In Section 3, we discuss the elliptic curve discrete logarithmic problem on the curve $E(\mathbb{K})$. Finally, we conclude in the Section 4 with prospective of future study.

## 2 Generalized Huff's Model

Let $\mathbb{K}$ be a finite field of characteristic $\neq 2$. We define an elliptic curve, denote it by $E$ over $\mathbb{K}$ as $E(\mathbb{K}): a x\left(y^{2}+x y+f\right)=b y\left(x^{2}+x y+g\right)$, where $a, b, f, g \in \mathbb{K}$ and $\operatorname{abfg}(a-b) \neq 0$. The inflection point $(0,0,1)$ of $E(\mathbb{K})$ has the tangent line as $b g y=a f x$, that passes through the curve with the multiplicity of 3 , thus $O=(0,0,1)$ is the neutral point of $E(\mathbb{K})$. Furthermore, we denote group law as $\oplus$. The figure 2.1 shows that the line passing through the points $P$ and $Q$, and intersecting at third point $R$ on $E(\mathbb{K})$.


Figure 2.1: An example for the elliptic curve $E(\mathbb{K})$
Let $P=\left(X_{1}, Y_{1}, Z_{1}\right), Q=\left(X_{2}, Y_{2}, Z_{2}\right)$ and $R=\left(X_{3}, Y_{3}, Z_{3}\right)$ be three points on $E(\mathbb{K})$. Then, $P \oplus Q$ could be obtained by line connecting $R$ and $O$ that intersects at third point $\ominus R$ on $E(\mathbb{K})$ such that $P \oplus Q=\ominus R$ which implies that $P \oplus Q \oplus R=O$. In particular, the inverse of the point $P$ is $\ominus P=\left(X_{1}, Y_{1},-Z_{1}\right)$. It is clear that the curve $E(\mathbb{K})$ posses commutative law. We note that there are three points at infinity, namely $(1,0,0),(0,1,0)$ and $(a, b, 0)$ on $E(\mathbb{K})$, and the sum of any two points at infinity equals to the third point. For any point $\left(X_{1}, Y_{1}, Z_{1}\right)$, when $Z_{1} \neq 0$, for some real number $\alpha$ and $\gamma$ bounded by the field $\mathbb{K}$, we observe that

$$
\begin{aligned}
& (1: 0: 0) \oplus\left(X_{1}: Y_{1}: Z_{1}\right)=\left(\alpha Z_{1}^{2}:-X_{1} Y_{1}: X_{1} Z_{1}\right) \text { and } \\
& (0: 1: 0) \oplus\left(X_{1}: Y_{1}: Z_{1}\right)=\left(-X_{1} Y_{1}: \gamma Z_{1}^{2}: Y_{1} Z_{1}\right) .
\end{aligned}
$$

Furthermore, we note that

$$
\begin{gathered}
(a: b: 0) \oplus\left(X_{1}: Y_{1}: Z_{1}\right)=(0: 1: 0) \oplus\left(\alpha Z_{1}^{2}:-X_{1} Y_{1}: X_{1} Z_{1}\right), \\
\\
\text { therefore } \\
(a: b: 0) \oplus\left(X_{1}: Y_{1}: Z_{1}\right)=\left\{\begin{array}{ll}
(a: b: 0) \text { if }\left(X_{1}: Y_{1}: Z_{1}\right)= & (0: 0: 1) \\
\left(-\alpha y_{1} z_{1}:-\gamma X_{1} Z_{1}: X_{1} Y_{1}\right) & \text { otherwise }
\end{array} .\right.
\end{gathered}
$$

We have doubling point if $P=Q$, thus the line connecting $P$ and $Q$ is the tangent at the point $P$.

### 2.1 Affine formulae

In this Subsection, we provide formulae for the group law for the elliptic curve $E(\mathbb{K})$ : ax $\left(y^{2}+x y+f\right)=b y\left(x^{2}+x y+g\right)$, where $a, b, f, g \in \mathbb{K}$ and $\operatorname{abfg}(a-b) \neq 0$.

Let $P=\left(x_{1}, y_{1}\right), Q=\left(x_{2}, y_{2}\right)$ and $R=\left(x_{3}, y_{3}\right)$ be the three different points on $E(\mathbb{K})$ such that $R$ is obtained by connecting a line through $P$ and $Q$. Let the secant line joining $P$ and $Q$ have the slope defined as $\lambda=\frac{y_{2}-y_{1}}{x_{2}-x_{1}}$. Thus, $y=\lambda x+\beta$ is the equation of the secant line passing through the points $P, Q$ and $R$, where $\beta=y_{1}-\lambda x_{1}$. For the curve equation $a x\left(y^{2}+x y+f\right)=b y\left(x^{2}+x y+g\right)$, we can replace $y$ with $\lambda x+\beta$.

$$
\begin{aligned}
a x\left((\lambda x+\beta)^{2}+x(\lambda x+\beta)+f\right)= & b(\lambda x+\beta) \\
& \left(x^{2}+x(\lambda x+\beta)+g\right) \\
x\left(a f+a \beta^{2}\right)+x^{2}(a \beta+2 a \beta \lambda) & \\
+x^{3}\left(a \lambda+a \lambda^{2}\right)= & \left(b g \beta+x\left(b \beta^{2}+b g \lambda\right)\right. \\
& +x^{2}(b \beta+2 b \beta \lambda)+x^{3}\left(b \lambda+b \lambda^{2}\right)
\end{aligned}
$$

Let

$$
A=a \beta-b \beta+2 a \beta \lambda-2 b \beta \lambda
$$

and

$$
B=a \lambda-b \lambda+a \lambda^{2}-b \lambda^{2}
$$

then

$$
-b g \beta+x\left(a f+a \beta^{2}-b \beta^{2}-b g \lambda\right)+A x^{2}+B x^{3}=0 .
$$

We now note that

$$
\begin{gathered}
x_{1}+x_{2}+x_{3}=-\frac{A}{B} \\
-x_{3}=x_{1}+x_{2}+\frac{a \beta-b \beta+2 a \beta \lambda-2 b \beta \lambda}{a \lambda-b \lambda+a \lambda^{2}-b \lambda^{2}}
\end{gathered}
$$

substituting $\beta=y_{1}-\lambda x_{1}$ and $\lambda=\frac{y_{2}-y_{1}}{x_{2}-x_{1}}$.

$$
\begin{aligned}
x_{3} & =-\left(x_{1}+x_{2}+\frac{\left(x_{1}-x_{2}+2 y_{1}-2 y_{2}\right)\left(-x_{2} y_{1}+x_{1} y_{2}\right)}{\left(y_{1}-y_{2}\right)\left(x_{1}-x_{2}+y_{1}-y_{2}\right)}\right) \\
& =-x_{1}-x_{2}-\frac{\left(x_{1}-x_{2}+2 y_{1}-2 y_{2}\right)\left(-x_{2} y_{1}+x_{1} y_{2}\right)}{\left(y_{1}-y_{2}\right)\left(x_{1}-x_{2}+y_{1}-y_{2}\right)}
\end{aligned}
$$

which simplifies to

$$
\begin{equation*}
x_{3}=-\frac{\left(x_{1}-x_{2}\right)\left(y_{1}\left(x_{1}+y_{1}\right)-y_{2}\left(x_{2}+y_{2}\right)\right)}{\left(y_{1}-y_{2}\right)\left(x_{1}-x_{2}+y_{1}-y_{2}\right)} . \tag{2.1}
\end{equation*}
$$

We claim, by symmetry that

$$
\begin{equation*}
y_{3}=-\frac{\left(y_{1}-y_{2}\right)\left(x_{1}^{2}+x_{1} y_{1}-x_{2}\left(x_{2}+y_{2}\right)\right)}{\left(x_{1}-x_{2}\right)\left(x_{1}-x_{2}+y_{1}-y_{2}\right)} . \tag{2.2}
\end{equation*}
$$

Thus, this is an evidence that the curve $E(\mathbb{K})$ has three points $P=\left(x_{1}, y_{1}\right), Q=\left(x_{2}, y_{2}\right)$ and $R=\left(x_{3}, y_{3}\right)$. We observe that inverse of the point $R$ is $\ominus R=\left(-x_{3},-y_{3}\right)$. We note that the point $R=\left(x_{3}, y_{3}\right)$ is computed only when $x_{1} \neq x_{2}, y_{1} \neq y_{2}$ and $x_{1}-x_{2}+y_{1}-y_{2} \neq 0$ and the addition formula used in the affine coordinate system could not be employed for doubling points since $x_{1} \neq x_{2}$ and $y_{1} \neq y_{2}$.

We now show that the curve $E(\mathbb{K})$ holds associative law, that is $P \oplus(Q \oplus R)=(P \oplus Q) \oplus R$.
For $x$-coordinates, we have

$$
\begin{aligned}
P \oplus(Q \oplus R) & =x_{1}+\left[x_{2}-\frac{\left(x_{1}-x_{2}\right)\left(y_{1}\left(x_{1}+y_{1}\right)-y_{2}\left(x_{2}+y_{2}\right)\right)}{\left(y_{1}-y_{2}\right)\left(x_{1}-x_{2}+y_{1}-y_{2}\right)}\right] \\
& =x_{1}+ \\
& \left.=-\frac{x_{1}^{2} y_{1}-2 x_{1} x_{2} y_{1}+x_{2}^{2} y_{1}+x_{1} y_{1}^{2}-2 x_{2} y_{1}^{2}+2 x_{2} y_{1} y_{2}-x_{1} y_{2}^{2}}{\left(y_{1}-y_{2}\right)\left(-x_{1}+x_{2}-y_{1}+y_{2}\right)}\right] \\
& =\frac{\left(x_{1}-x_{2}+2 y_{1}-2 y_{2}\right)\left(-x_{2} y_{1}+x_{1} y_{2}\right)}{\left(y_{1}-y_{2}\right)\left(x_{1}-x_{2}+y_{1}-y_{2}\right)}
\end{aligned}
$$

and

$$
\begin{aligned}
(P \oplus Q) \oplus R & =\left(x_{1}+x_{2}\right)-\frac{\left(x_{1}-x_{2}\right)\left(y_{1}\left(x_{1}+y_{1}\right)-y_{2}\left(x_{2}+y_{2}\right)\right)}{\left(y_{1}-y_{2}\right)\left(x_{1}-x_{2}+y_{1}-y_{2}\right)} \\
& =x_{1}+x_{2}-\frac{\left(x_{1}-x_{2}\right)\left(y_{1}\left(x_{1}+y_{1}\right)-y_{2}\left(x_{2}+y_{2}\right)\right)}{\left(y_{1}-y_{2}\right)\left(x_{1}-x_{2}+y_{1}-y_{2}\right)} \\
& =-\frac{\left(x_{1}-x_{2}+2 y_{1}-2 y_{2}\right)\left(-x_{2} y_{1}+x_{1} y_{2}\right)}{\left(y_{1}-y_{2}\right)\left(x_{1}-x_{2}+y_{1}-y_{2}\right)} .
\end{aligned}
$$

For $y$-coordinates, we have

$$
\begin{aligned}
P+(Q+R)= & y_{1}+\left[y_{2}-\frac{\left(y_{1}-y_{2}\right)\left(x_{1}^{2}+x_{1} y_{1}-x_{2}\left(x_{2}+y_{2}\right)\right)}{\left(x_{1}-x_{2}\right)\left(x_{1}-x_{2}+y_{1}-y_{2}\right)}\right] \\
= & y_{1}+ \\
& \frac{x_{1}^{2} y_{1}-x_{2}^{2} y_{1}+x_{1} y_{1}^{2}-2 x_{1}^{2} y_{2}+2 x_{1} x_{2} y_{2}-2 x_{1} y_{1} y_{2}+x_{1} y_{2}^{2}}{\left(x_{1}-x_{2}\right)\left(-x_{1}+x_{2}-y_{1}+y_{2}\right)} \\
= & -\frac{\left(2 x_{1}-2 x_{2}+y_{1}-y_{2}\right)\left(x_{2} y_{1}-x_{1} y_{2}\right)}{\left(x_{1}-x_{2}\right)\left(x_{1}-x_{2}+y_{1}-y_{2}\right)}
\end{aligned}
$$

and

$$
\begin{aligned}
(P+Q)+R & =\left(y_{1}+y_{2}\right)-\frac{\left(y_{1}-y_{2}\right)\left(x_{1}^{2}+x_{1} y_{1}-x_{2}\left(x_{2}+y_{2}\right)\right)}{\left(x_{1}-x_{2}\right)\left(x_{1}-x_{2}+y_{1}-y_{2}\right)} \\
& =y_{1}+y_{2}-\frac{\left(y_{1}-y_{2}\right)\left(x_{1}^{2}+x_{1} y_{1}-x_{2}\left(x_{2}+y_{2}\right)\right)}{\left(x_{1}-x_{2}\right)\left(x_{1}-x_{2}+y_{1}-y_{2}\right)} \\
& =-\frac{\left(2 x_{1}-2 x_{2}+y_{1}-y_{2}\right)\left(x_{2} y_{1}-x_{1} y_{2}\right)}{\left(x_{1}-x_{2}\right)\left(x_{1}-x_{2}+y_{1}-y_{2}\right)} .
\end{aligned}
$$

Thus, we have $(P \oplus Q) \oplus R=P \oplus(Q \oplus R)$.
We now define a point of infinity on $E(\mathbb{K})$ as $O=(0,0)$. For the point $P=\left(x_{1}, y_{1}\right)$, we have $\ominus P=\left(-x_{1},-y_{1}\right)$. Thus, it follows that

$$
\begin{aligned}
x_{3} & =-\frac{\left(x_{1}-x_{2}\right)\left(y_{1}\left(x_{1}+y_{1}\right)-y_{2}\left(x_{2}+y_{2}\right)\right)}{\left(y_{1}-y_{2}\right)\left(x_{1}-x_{2}+y_{1}-y_{2}\right)} \\
& =-\frac{\left(x_{1}--x_{1}\right)\left(y_{1}\left(x_{1}+y_{1}\right)--y_{2}\left(-x_{2}-y_{2}\right)\right)}{\left(y_{1}--y_{2}\right)\left(x_{1}--x_{2}+y_{1}--y_{2}\right)} \\
& =-\frac{\left(x_{1}+x_{1}\right)\left(y_{1}\left(x_{1}+y_{1}\right)+y_{1}\left(-x_{1}-y_{1}\right)\right)}{\left(y_{1}--y_{1}\right)\left(x_{1}--x_{1}+y_{1}--y_{1}\right)} \\
& =-\frac{\left(2 x_{1}\right)(0)}{\left(2 y_{1}\right)\left(2 x_{1}+2 y_{1}\right)} \\
& =0
\end{aligned}
$$

and

$$
\begin{aligned}
y_{3} & =-\frac{\left(y_{1}-y_{2}\right)\left(x_{1}^{2}+x_{1} y_{1}-x_{2}\left(x_{2}+y_{2}\right)\right)}{\left(x_{1}-x_{2}\right)\left(x_{1}-x_{2}+y_{1}-y_{2}\right)} \\
& =-\frac{\left(y_{1}--y_{1}\right)\left(x_{1}^{2}+x_{1} y_{1}--x_{1}\left(-x_{1}-y_{1}\right)\right)}{\left(x_{1}--x_{1}\right)\left(x_{1}--x_{1}+y_{1}--y_{1}\right)} \\
& =-\frac{\left(2 y_{1}\right)\left(x_{1}^{2}+x_{1} y_{1}+x_{1}\left(-x_{1}-y_{1}\right)\right)}{\left(x_{1}+x_{1}\right)\left(x_{1}+x_{1}+y_{1}+y_{1}\right)} \\
& =-\frac{\left(2 y_{1}\right)(0)}{\left(2 x_{1}\right)\left(2 x_{1}+2 y_{1}\right)} \\
& =0
\end{aligned}
$$

Thus $P \oplus(\ominus P)=O$.
The slope of the tangent line on the curve $E(\mathbb{K}): a x\left(y^{2}+x y+f\right)=b y\left(x^{2}+x y+g\right)$, where $\operatorname{abfg}(a-b) \neq 0$ could be computed by implicit differentiation, thus by differentiation of $E(\mathbb{K})$ with respect to $x$, we have

$$
\begin{aligned}
a f+2 a x y+a y^{2}+a x^{2} y^{\prime}+2 a x y y^{\prime} & =2 b x y+b y^{2}+b g y^{\prime}+b x^{2} y^{\prime}+2 b x y y^{\prime} \\
y^{\prime} & =\frac{a f+2 a x y+a y^{2}-2 b x y-b y^{2}}{b g-a x^{2}+b x^{2}-2 a x y+2 b x y} .
\end{aligned}
$$

For the point $P=\left(x_{1}, y_{1}\right)$, we can describe the slope as

$$
\lambda_{p}=\frac{a f+2 a x_{1} y_{1}+a y_{1}^{2}-2 b x_{1} y_{1}-b y_{1}^{2}}{b g-a x_{1}^{2}+b x_{1}^{2}-2 a x_{1} y_{1}+2 b x_{1} y_{1}}=\frac{a f+(a-b) y_{1}\left(2 x_{1}+y_{1}\right)}{b g-(a-b) x_{1}\left(x_{1}+2 y_{1}\right)} .
$$

Let

$$
\begin{gathered}
A_{1}=a f x_{1}+\left(2 a f+b g+(a-b) x_{1}^{2}\right) y_{1}, A_{2}=3(a-b) x_{1} y_{1}^{2}+2(a-b) y_{1}^{3}, \\
A_{3}=\left(b g-(a-b) x_{1}\left(x_{1}+2 y_{1}\right)\right)
\end{gathered}
$$

and

$$
\begin{gathered}
B_{1}=\left(a f+(a-b) y_{1}\left(2 x_{1}+y_{1}\right)\right), B_{2}=2(-a+b) x_{1}^{3}+b g y_{1}+3(-a+b) x_{1}^{2} y_{1}, \\
B_{3}=x_{1}\left(a f+2 b g+(-a+b) y_{1}^{2}\right)
\end{gathered}
$$

We claim that

$$
x_{2}=-\frac{A_{3}\left(A_{1}+A_{2}\right)}{\left(a f+b g+(-a+b) x_{1}^{2}+(a-b) y_{1}^{2}\right)\left(a f+(a-b) y_{1}\left(2 x_{1}+y_{1}\right)\right)}
$$

and

$$
y_{2}=-\frac{B_{1}\left(B_{2}+B_{3}\right)}{\left(a f+b g+(-a+b) x_{1}^{2}+(a-b) y_{1}^{2}\right)\left(b g-(a-b) x_{1}\left(x_{1}+2 y_{1}\right)\right)}
$$

are the second coordinates of the point of intersection for the tangent line at $P$.

We can prove our claim by simply checking the slope given by

$$
\lambda=\frac{y_{2}-y_{1}}{x_{2}-x_{1}}
$$

and by simplification we can obtain

$$
\lambda=\frac{a f+(a-b) y_{1}\left(2 x_{1}+y_{1}\right)}{b g-(a-b) x_{1}\left(x_{1}+2 y_{1}\right)}
$$

which have same slope as $\lambda_{p}$.

### 2.2 Projective formulae

Let $x=\frac{X}{Z}, y=\frac{Y}{Z}$ and $Z=1[15,31]$, then the affine coordinate $E(\mathbb{K}): a x\left(y^{2}+x y+f\right)=b y\left(x^{2}+x y+g\right)$, where $a, b, f, g \in \mathbb{K}$ and $\operatorname{abfg}(a-b) \neq 0$ becomes

$$
a \frac{X}{Z}\left(\frac{Y^{2}}{Z^{2}}+\frac{X Y}{Z^{2}}+f\right)=b \frac{Y}{Z}\left(\frac{X^{2}}{Z^{2}}+\frac{X Y}{Z^{2}}+g\right)
$$

Finally, multiplying by $Z^{3}$ on both the sides to get rid of denominators and achieve the projective form of the curve equation
$E(\mathbb{K}): a X\left(Y^{2}+X Y+f Z^{2}\right)=b Y\left(X^{2}+X Y+g Z^{2}\right)$, where $a, b, f, g \in \mathbb{K}$ and $\operatorname{abfg}(a-b) \neq 0$.

For the point $P=\left(X_{1}, Y_{1}, Z_{1}\right)$ and $Q=\left(X_{2}, Y_{2}, Z_{2}\right)$, the third point of intersection known as $R=\left(U_{3}, V_{3}, W_{3}\right)$ of the line joining $P$ and $Q$ has the coordinates as follows:

$$
\begin{align*}
U_{3} & =\left(X_{2} Z_{1}-X_{1} Z_{2}\right)^{2}\left(Y_{2} Z_{1}^{2}\left(X_{2}+Y_{2}\right)-Y_{1} Z_{2}^{2}\left(X_{1}+Y_{1}\right)\right) \\
V_{3} & =\left(Y_{2} Z_{1}-Y_{1} Z_{2}\right)^{2}\left(X_{2} Z_{1}^{2}\left(X_{2}+Y_{2}\right)-X_{1} Z_{2}^{2}\left(X_{1}+Y_{1}\right)\right) \\
W_{3} & =-Z_{1} Z_{2}\left(X_{2} Z_{1}-X_{1} Z_{2}\right)\left(Y_{2} Z_{1}-Y_{1} Z_{2}\right)\left(Z_{1}\left(X_{2}+Y_{2}\right)-Z_{2}\left(X_{1}+Y_{1}\right)\right) . \tag{2.3}
\end{align*}
$$

For doubling points, the coordinates are as follows:

$$
\begin{align*}
U_{2}= & -\left(X_{1}(a-b)\left(X_{1}+2 Y_{1}\right)-b g Z_{1}^{2}\right)^{2} \\
& \left(Y_{1}(a-b)\left(X_{1}+Y_{1}\right)\left(X_{1}+2 Y_{1}\right)+Z_{1}^{2}\left(a f X_{1}+(2 a f+b g) Y_{1}\right)\right) \\
V_{2}= & -\left(Y_{1}(a-b)\left(2 X_{1}+Y_{1}\right)+a f Z_{1}^{2}\right)^{2} \\
& \left(-X_{1}(a-b)\left(X_{1}+Y_{1}\right)\left(2 X_{1}+Y_{1}\right)+Z_{1}^{2}\left(X_{1}(a f+2 b g)+b g X_{1}\right)\right) \\
W_{2}= & Z_{1}\left(Y_{1}(a-b)\left(2 X_{1}+Y_{1}\right)+a f Z_{1}^{2}\right)\left(-X_{1}(a-b)\left(X_{1}+2 Y_{1}\right)+b g Z_{1}^{2}\right) \\
& \left(-(a-b)\left(X_{1}^{2}-Y_{1}^{2}\right)+(a f+b g) Z_{1}^{2}\right) \tag{2.4}
\end{align*}
$$

Projective coordinates may be preferred for faster arithmetic than the affine formula. The affine formulae equation 2.1 and 2.2 for addition of two different point on $E(\mathbb{K})$ is described by equation 2.3.

We let cost of a multiplication be $m$ and the cost of a square be $s$ in the field $\mathbb{K}$. Then, we have

$$
\begin{gathered}
m_{1}=X_{1} Z_{2}, m_{2}=X_{2} Z_{1}, m_{3}=Y_{1} Z_{2}, m_{4}=Y_{2} Z_{1}, \\
m_{5}=m_{4}\left(m_{2}+m_{4}\right), m_{6}=m_{3}\left(m_{1}+m_{3}\right), m_{7}=m_{2}\left(m_{2}+m_{4}\right), \\
m_{8}=m_{1}\left(m_{1}+m_{3}\right), m_{9}=-Z_{1} Z_{2}, \\
s_{1}=\left(m_{2}-m_{1}\right)^{2}, s_{2}=\left(m_{4}-m_{3}\right)^{2}, \\
U_{3}=s_{1}\left(m_{5}-m_{6}\right), V_{3}=s_{2}\left(m_{7}-m_{8}\right), \\
W_{3}=m_{9}\left(m_{2}-m_{1}\right)\left(m_{4}-m_{3}\right)\left(m_{2}+m_{4}-m_{1}-m_{3}\right),
\end{gathered}
$$

Therefore, the total cost of point addition on the curve $E(\mathbb{K})$ is $14 m+2 s$. For the doubling point as described by equation 2.4, we have

$$
\begin{gathered}
s_{1}=Z_{1}^{2}, s_{2}=X_{1}^{2}, s_{3}=Y_{1}^{2}, \\
m_{1}=X_{1}(a-b)\left(X_{1}+2 Y_{1}\right), m_{2}=\left(X_{1}+Y_{1}\right)\left(X_{1}+2 Y_{1}\right), \\
m_{3}=s_{1}\left(a f X_{1}+Y_{1}(2 a f+b g)\right), m_{4}=(a-b) Y_{1} m_{2}, m_{5}=Y_{1}(a-b)\left(2 X_{1}+Y_{1}\right) \\
m_{6}=\left(X_{1}+Y_{1}\right)\left(2 X_{1}+Y_{1}\right), m_{7}=s_{1}\left((a f+2 b g) X_{1}+b g Y_{1}\right), \\
m_{8}=-X_{1} m_{6}(a-b), m_{9}=\left(m_{5}+a f s_{1}\right)\left((a-b)\left(s_{2}+s_{3}\right)+s_{1}(a f+b g)\right) \\
U_{2}=-\left(m_{1}-b g s_{1}\right)^{2}\left(m_{3}+m_{4}\right), V_{2}=-\left(m_{5}+a f s_{1}\right)^{2}\left(m_{7}+m_{8}\right), \\
W_{2}=-m_{1} m_{9} Z_{1} .
\end{gathered}
$$

Therefore, the total cost of point addition on the curve $E(\mathbb{K})$ is $13 m+5 s$.

Theorem 1. Let $\mathbb{K}$ be a finite field of characteristic $\neq 2$. Let $P_{1}=\left(X_{1}, Y_{1}, Z_{1}\right)$ and $P_{2}=\left(X_{2}, Y_{2}, Z_{2}\right)$ be two points on $E(\mathbb{K})$. Then, the addition formula given by equation 2.3 is valid provided that $X_{1} Z_{2} \neq X_{2} Z_{1}, Y_{1} Z_{2} \neq Y_{2} Z_{1}$ and $X_{1} Z_{2}+Y_{1} Z_{2} \neq X_{2} Z_{1}+Y_{2} Z_{1}$.

Proof. Let $P_{1}$ and $P_{2}$ be finite, we can write $P_{1}=\left(x_{1}, y_{1}\right)$, where $\left(x_{1}, y_{1}\right) \neq(0,0)$ and $P_{2}=\left(x_{2}, y_{2}\right)$. The point addition given by the equations 2.1 and 2.2 is only valid if $x_{1} \neq x_{2}, y_{1} \neq y_{2}$ and $x_{1}-x_{2}+y_{1}-y_{2} \neq 0$, which translate to projective coordinates as $X_{1} Z_{2} \neq X_{2} Z_{1}, Y_{1} Z_{2} \neq Y_{2} Z_{1}$ and $X_{1} Z_{2}+Y_{1} Z_{2} \neq X_{2} Z_{1}+Y_{2} Z_{1}$, respectively.

It remains to analyze that the condition is satisfied at the infinity points. The points at infinity are $(1: 0: 0),(0: 1: 0)$ and $(a, b, 0)$, if $P_{1}$ or $P_{2} \in\{(1: 0: 0),(0: 1: 0)\}$, then $X_{1} Z_{2} \neq X_{2} Z_{1}, Y_{1} Z_{2} \neq Y_{2} Z_{1}$ and $X_{1} Z_{2}+Y_{1} Z_{2} \neq X_{2} Z_{1}+Y_{2} Z_{1}$ is not satisfied. Since $P_{1} \notin\{O,(1: 0: 0),(0:$ $1: 0)\}$ then the addition law is valid for $P_{2}=(a: b: 0)$ as mentioned earlier.

### 2.3 Jacobian formulae

Let $x=\frac{X}{Z^{2}}, y=\frac{Y}{Z^{3}}$ and $Z=1[15,31]$. Then the affine coordinate $E(\mathbb{K}): a x\left(y^{2}+x y+f\right)=b y\left(x^{2}+x y+g\right)$, where $a, b, f, g \in \mathbb{K}$ and $a b f g(a-b) \neq 0$ after simplification becomes $E(\mathbb{K}): a X\left(Y^{2}+X Y Z+f Z^{6}\right)=b Y\left(X Z^{2}+X Y Z+g Z^{6}\right)$, where $a, b, f, g \in \mathbb{K}$ and $a b f g(a-b) \neq 0$.

For the point $P=\left(X_{1}, Y_{1}, Z_{1}\right)$ and $Q=\left(X_{2}, Y_{2}, Z_{2}\right)$, the third point of intersection known as $R=\left(U_{3}, V_{3}, W_{3}\right)$ of the line joining $P$ and $Q$ has the coordinates as follows:

$$
\begin{aligned}
U_{3} & =-Z_{1} Z_{2}\left(X_{2} Z_{1}^{2}-X_{1} Z_{2}^{2}\right)^{2}\left(Y_{2}^{2} Z_{1}^{6}+X_{2} Y_{2} Z_{1}^{6} Z_{2}-Y_{1} Z_{2}^{6}\left(Y_{1}+X_{1} Z_{1}\right)\right) \\
V_{3} & =-\left(Y_{2} Z_{1}^{3}-Y_{1} Z_{2}^{3}\right)^{2}\left(X_{2} Y_{2} Z_{1}^{5}+X_{2}^{2} Z_{1}^{5} Z_{2}-X_{1} Z_{2}^{5}\left(Y_{1}+X_{1} Z_{1}\right)\right) \\
W_{3} & =Z_{1}^{2} Z_{2}^{2}\left(Y_{2} Z_{1}^{3}-Y_{1} Z_{2}^{3}\right)\left(X_{2} Z_{1}^{3} Z_{2}-X_{1} Z_{1} Z_{2}^{3}\right)\left(Y_{2} Z_{1}^{3}+X_{2} Z_{1}^{3} Z_{2}-Z_{2}^{3}\left(Y_{1}+X_{1} Z_{1}\right)\right) .
\end{aligned}
$$

For doubling points, the coordinates are as follows:

$$
\begin{aligned}
U_{2}= & -Z_{1}\left(2 X_{1} Y_{1}(-a+b)+(-a+b) X_{1}^{2} Z_{1}+b g Z_{1}^{5}\right)^{2} \\
& \left(2(a-b) Y_{1}^{3}+3(a-b) X_{1} Y_{1}^{2} Z_{1}+a f X_{1} Z_{1}^{7}+Y_{1} Z_{1}^{2}\left((a-b) X_{1}^{2}+(2 a f+b g) Z_{1}^{4}\right)\right) \\
V_{2}= & -\left((a-b) Y_{1}^{2}+2(a-b) X_{1} Y_{1} Z_{1}+a f Z_{1}^{6}\right)^{2} \\
& \left(3(-a+b) X_{1}^{2} Y_{1} Z_{1}+2(-a+b) X_{1}^{3} Z_{1}^{2}+b g Y_{1} Z_{1}^{5}+X_{1}\left((-a+b) Y_{1}^{2}+(a f+2 b g) Z_{1}^{6}\right)\right) \\
W_{2}= & Z_{1}^{3}\left(2(-a+b) X_{1} Y_{1}+(-a+b) X_{1}^{2} Z_{1}+b g Z_{1}^{5}\right)\left((a-b) Y_{1}^{2}+2(a-b) X_{1} Y_{1} Z_{1}+a f Z_{1}^{6}\right) \\
& \left((a-b) Y_{1}^{2}+(-a+b) X_{1}^{2} Z_{1}^{2}+(a f+b g) Z_{1}^{6}\right)
\end{aligned}
$$

The costs of point addition and doubling point on the curve $E(\mathbb{K})$ are $32 m+4 s$ and $29 m+5 s$, respectively.

### 2.4 Lopez-Dahab formuale

Let $x=\frac{X}{Z}, y=\frac{Y}{Z^{2}}$ and $Z=1[15,31]$. Then the affine coordinate $E(\mathbb{K}): a x\left(y^{2}+x y+f\right)=b y\left(x^{2}+x y+g\right)$, where $a, b, f, g \in \mathbb{K}$ and $a b f g(a-b) \neq 0$ after simplification becomes
$E(\mathbb{K}): a X\left(Y^{2}+X Y Z+f Z^{5}\right)=b Y\left(X Z^{2}+X Y+g Z^{6}\right)$, where $a, b, f, g \in \mathbb{K}$ and $\operatorname{abfg}(a-b) \neq 0$.

For the point $P=\left(X_{1}, Y_{1}, Z_{1}\right)$ and $Q=\left(X_{2}, Y_{2}, Z_{2}\right)$, the third point of intersection known as $R=\left(U_{3}, V_{3}, W_{3}\right)$ of the line joining $P$ and $Q$ has the coordinates as follows:

$$
\begin{aligned}
U_{3} & =-Z_{1} Z_{2}\left(X_{2} Z_{1}-X_{1} Z_{2}\right)^{2}\left(Y_{2}^{2} Z_{1}^{4}+X_{2} Y_{2} Z_{1}^{4} Z_{2}-Y_{1} Z_{2}^{4}\left(Y_{1}+X_{1} Z_{1}\right)\right) \\
V_{3} & =-\left(Y_{2} Z_{1}^{2}-Y_{1} Z_{2}^{2}\right)^{2}\left(X_{2} Y_{2} Z_{1}^{3}+X_{2}^{2} Z_{1}^{3} Z_{2}-X_{1} Z_{2}^{3}\left(Y_{1}+X_{1} Z_{1}\right)\right) \\
W_{3} & =Z_{1}^{2} Z_{2}^{2}\left(X_{2} Z_{1}-X_{1} Z_{2}\right)\left(Y_{2} Z_{1}^{2}-Y_{1} Z_{2}^{2}\right)\left(Y_{2} Z_{1}^{2}+Z_{2}\left(X_{2} Z_{1}^{2}-Z_{2}\left(Y_{1}+X_{1} Z_{1}\right)\right)\right)
\end{aligned}
$$

For doubling points, the coordinates are as follows:

$$
\begin{aligned}
U_{2}= & -Z_{1}\left(2(-a+b) X_{1} Y_{1}+(-a+b) X_{1}^{2} Z_{1}+b g Z_{1}^{3}\right)^{2} \\
& \left(2(a-b) Y_{1}^{3}+3(a-b) X_{1} Y_{1}^{2} Z_{1}+a f X_{1} Z_{1}^{5}+Y_{1} Z_{1}^{2}\left((a-b) X_{1}^{2}+(2 a f+b g) Z_{1}^{2}\right)\right) \\
V_{2}= & -\left((a-b) Y_{1}^{2}+2(a-b) X_{1} Y_{1} Z_{1}+a f Z_{1}^{4}\right)^{2} \\
& \left(3(-a+b) X_{1}^{2} Y_{1} Z_{1}+2(-a+b) X_{1}^{3} Z_{1}^{2}+b g Y_{1} Z_{1}^{3}+X_{1}\left((-a+b) Y_{1}^{2}+(a f+2 b g) Z_{1}^{4}\right)\right) \\
W_{2}= & Z_{1}^{2}\left(2(-a+b) X_{1} Y_{1}+(-a+b) X_{1}^{2} Z_{1}+b g Z_{1}^{3}\right)\left((a-b) Y_{1}^{2}+2(a-b) X_{1} Y_{1} Z_{1}+a f Z_{1}^{4}\right) \\
& \left((a-b) Y_{1}^{2}+(-a+b) X_{1}^{2} Y_{1}^{2}+(a f+b g) Z_{1}^{4}\right)
\end{aligned}
$$

The costs of point addition and doubling point on the curve $E(\mathbb{K})$ are $32 m+6 s$ and $26 m+5 s$, respectively.

### 2.5 Hasse's Theorem

For the elliptic curve $E(\mathbb{K})$ : $a x\left(y^{2}+x y+f\right)=b y\left(x^{2}+x y+g\right)$, where $a, b, f, g \in \mathbb{K}$ and $\operatorname{abf} g(a-b) \neq 0$, we replace $\mathbb{K}$ by $\mathbb{F}_{q}$, where $q$ is a prime. We observe that for each $x$ yields at most two values for $y$, and the point of infinity $(0,0)$ is always on the curve $E\left(\mathbb{F}_{q}\right)$. Thus, we can set up an upper bound for the number of rationals on $E\left(\mathbb{F}_{q}\right)$ as

$$
\# E\left(\mathbb{F}_{q}\right) \leq 2 q+1 .
$$

However, computing the exact number of points on the curve $E\left(\mathbb{F}_{q}\right)$ is a challenge to us. Hasse's theorem on elliptic curve $E\left(\mathbb{F}_{q}\right)$ provides an estimate on the number of points over the finite field $\mathbb{F}_{q}$ as

$$
\left|\# E\left(\mathbb{F}_{q}\right)-(q+1)\right| \leq 2 \sqrt{q} .
$$

For the understanding purpose, the curve
$E\left(\mathbb{F}_{q}\right): a x\left(y^{2}+x y+f\right)=b y\left(x^{2}+x y+g\right)$, where $a, b, f, g \in \mathbb{F}_{q}$ and $a b f g(a-$ b) $\neq 0$ with the condition
$\operatorname{abfg} g(a-b) \neq 0$ could be rearranged as
$a f x+\left(-b g+a x^{2}-b x^{2}\right) y+(a x-b x) y^{2}=0$ and may be seen as quadratic equation of $y$. The discriminant can be calculated by
$\Delta=-4 a f x(a x-b x)+\left(-b g+a x^{2}-b x^{2}\right)^{2}$ and $y$ can be rational if and only if $\Delta=j^{2}$ for some rational $j$. The variables of the curve are $a, b, g$ and $f$ and we can easily find some points on the curve by simply assigning values of $a, f$ and $g$ and solving for $b$. The examples below will show how one can obtain $y$ coordinate.

Example. We assign $a=1, f=1, x=1$ and $g=-1$. The discriminant formula then becomes

$$
\begin{aligned}
i^{2} & =-4 a(a x-b x)+\left(-b g+a x^{2}-b x^{2}\right)^{2} \\
i^{2} & =-4(1-b)+1 \\
i^{2} & =4 b-3 .
\end{aligned}
$$

We note that $4 b-3$ should be a rational square. Thus choosing $4 b-3=1$ yields $b=1$ but we omit this value due to the initial condition of the curve. We now use $4 b-3=4$ and it gives $b=3$. Now our curve becomes $E\left(\mathbb{F}_{17}\right): x\left(y^{2}+x y+1\right)=3 y\left(x^{2}+x y-1\right)$ which has a rational coordinate of $(1,1)$. Since $(1,1)$ is on the curve then so does $(-1,-1)$. We now apply
point doubling formula on the points $(1,1)$ and $(-1,-1)$. The solution to $(1,1)$ is another point $\left(\frac{18}{5},-\frac{10}{3}\right)$ and solution to $(-1,-1)$ is $\left(-\frac{18}{5}, \frac{10}{3}\right)$. We now apply point addition of the point $(1,1)$ and $\left(-\frac{18}{5}, \frac{10}{3}\right)$ which yields $\left(\frac{299}{119}, \frac{91}{391}\right)$. We can also apply point addition of points $(-1,-1)$ and $\left(\frac{18}{5},-\frac{10}{3}\right)$ which yields $\left(-\frac{299}{119},-\frac{91}{391}\right)$. We can use this method to generate more points on the curve $E\left(\mathbb{F}_{17}\right)$.

### 2.6 Computational cost analysis

In this subsection, we evaluate efficiency of point addition and doubling point on the curve $E(\mathbb{K})$. The computation cost ratio between square $(s)$ and multiplication $(m)$ is typically $s=0.8 m$. We omit other operations such as addition and subtraction as computation cost is lower. The following table summarizes the computational cost of point addition and doubling point in standard coordinate such as projective, Jacobian and Lopez-Dahab. We note that the computational cost using projective coordinate system on the curve $E(\mathbb{K})$ is lower than the Jacobian and Lopez Dahab coordinates. Thus, we recommend to use projective coordinates as the cost is lower for point addition and doubling points.

Table 1: Computational cost comparison

| Coordinates | Cost |  |
| :---: | :---: | :---: |
|  | Addition | Doubling |
| Projective | $14 \mathrm{~m}+2 \mathrm{~s}$ | $13 \mathrm{~m}+5 \mathrm{~s}$ |
| Jacobian | $32 \mathrm{~m}+4 \mathrm{~s}$ | $29 \mathrm{~m}+5 \mathrm{~s}$ |
| Lopez-Dahab | $32 \mathrm{~m}+6 \mathrm{~s}$ | $26 \mathrm{~m}+5 \mathrm{~s}$ |

## 3 Applicability in Cryptography

Elliptic curves have been widely used in cryptography [22, 19, 7, 18, 21], integer factorization $[26,3]$ and primality test [17]. In the cryptography, one of the famous computational problem, ECDLP is employed. We can also define the ECDLP on our curves $E\left(\mathbb{F}_{q}\right)$ as follows: Given two points $P$ and $Q$ on the curves $E\left(\mathbb{F}_{q}\right)$, compute $n \in \mathbb{F}_{q}$ is hard such that $Q=P \oplus P \oplus P \oplus \ldots \oplus P=n P$. One requires $O(\sqrt{q})$ operations to break the ECDLP by Pollard Rho method [30]. The ECDLP has been widely used in cryptographic applications such as key exchange protocol, encryption, and digital signatures. Furthermore, one can use our curve for cryptography.

## 4 Conclusion

This paper introduced a generalized model of Huff's elliptic curve. We have presented formulae for point addition and doubling on the affine, projective, Jacobian and Lopez-Dahab coordinates. We have noted that the computational cost of the point addition and doubling point is lower on the projective coordinates than the other mentioned coordinates. It remains to conduct a comparative study of the computational cost for the point addition and doubling point with the other curves such Weierstrass, Montegomery and Edwards. Furthermore, we can extend the study to supersingular elliptic curves and isogeny-based cryptography.

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