# Complexity of Estimating Renyi Entropy of Markov Chains 


#### Abstract

Estimating entropy of random processes is one of the fundamental problems of machine learning and property testing. It has numerous applications to anything from DNA testing and predictability of human behaviour to modeling neural activity and cryptography. We investigate the problem of Renyi entropy estimation for sources that form Markov chains. Kamath and Verdú (ISIT' 16) showed that good mixing properties are essential for that task. We show that even with very good mixing time, estimation of minentropy requires $\Omega\left(K^{2}\right)$ sample size, while collision entropy requires $\Omega\left(K^{3 / 2}\right)$ samples, where $K$ is the size of the alphabet. Our results hold both in asymptotic and non-asymptotic regimes. We achieve the results by applying Le Cam's method to two Markov chains which differ by an appropriately chosen sparse perturbation; the discrepancy between these chains is estimated with help of perturbation theory. Our techniques might be of independent interest.


## 1 Introduction

We follow up after [Han et al., 2018] to investigate efficiency of estimators for other popular notions of entropy - namely min-entropy and collision entropy.
Entropy estimation is one of the fundamental problems in the field of distribution testing. In addition to being mathematically interesting it has multiple applications to anything from DNA introns identification to predictability of human behaviour [Lanctôt et al., 2000; Song et al., 2010; Takaguchi et al., 2011; Wang and Huberman, 2012; Krumme et al., 2013]. In all of those applications one could easily replace Shannon entropy with any other Renyi entropy.
Renyi entropy [Rényi, 1960] arises in many applications as a generalization of Shannon Entropy [Shannon, 2001]. It is also of interests on its own right, with a number of applications including unsupervised learning (like clustering) [Xu, 1998; Jenssen et al., 2003], multiple source adaptation [Mansour et al., 2009], image processing [Ma et al., 2000; Neemuchwala et al., 2006; Sahoo and Arora, 2004], password guessability [Arikan, 1996; Pfister and Sullivan, 2004; Hanawal and Sundaresan, 2011], network anomaly detection [Li et al., 2009], quantifying neural activity [Paninski, 2003] or to analyze information flows in financial data [Jizba et al., 2012].
In particular Renyi entropy of order 2, known also as collision entropy, is used in quality tests for random number generators [Knuth, 1998; van Oorschot and Wiener, 1999], to estimate the number of random bits that can be extracted from a physical source [Impagliazzo and Zuckerman, 1989; Bennett et al., 1995], characterizes security of certain key derivation functions [Barak et al., 2011; Dodis and Yu, 2013], helps testing graph expansion [Goldreich and Ron, 2011] and closeness of distributions to uniformity [Batu et al., 2013; Paninski, 2008] and bounds the number of reads needed to reconstruct a DNA sequence [Motahari et al., 2013].
There are two models of randomness source which we consider when estimating entropy: model with iid samples, and one where samples form a Markov chain. Over the years asymptotic regime for iid
samples got the most attention [Wyner and Ziv, 1989; Antos and Kontoyiannis, 2001; Effros, 1999; Cai et al., 2006; Han et al., 2017]. More recent work considers an exact, non-asymptotic behaviour of the estimators for iid case [Paninski, 2003; Valiant and Valiant, 2011; Wu and Yang, 2014; Han et al., 2014]. Only recent papers considered Renyi entropy for iid samples [Acharya et al., 2015; Obremski and Skorski, 2017].
Estimation of entropy of Markov chains is a much harder task. [Kamath and Verdú, 2016] gave Renyi entropy estimators for reversible Markov chains in a non-asymptotic regime. They also showed that giving any guarantees on the estimator is impossible for chains with bad mixing time properties. In [Han et al., 2018] authors give bounds for Shannon entropy of Markov chains.
In this paper we investigate lower bounds on sample complexity of Renyi entropy estimator in Markov chain model. Our results hold both when estimating asymptotic entropy of Markov chain, and when estimating entropy of any fixed number of steps with any starting distribution. Our bounds hold even for the Markov chains with close to optimal mixing properties.

### 1.1 Estimation for Iid Samples

It is interesting to recall the lower bounds for Renyi entropy estimators sample complexity for the case of iid samples, bounds were achieved in a series of papers by [Acharya et al., 2015; Obremski and Skorski, 2017].

| Entropy | Accuracy | Sample Complexity |
| :---: | :---: | :--- |
| $1<\alpha<2$ | $\delta \leqslant 1$ | $\Omega(1) \cdot \min \left(\delta^{-\frac{1}{2}} K^{\frac{1}{2}}, \delta^{-\alpha} K^{1-\frac{1}{\alpha}}\right)$ |
|  | $\delta>1$ | $\Omega(1) \cdot \min \left(\left(2^{-\delta} K\right)^{\frac{1}{2}}, 2^{-\left(1-\frac{1}{\alpha}\right) \delta} K^{1-\frac{1}{\alpha}}\right)$ |
| $2 \leqslant \alpha$ | $\delta \leqslant 1$ | $\Omega(1) \cdot \delta^{-\frac{1}{\alpha}} K^{1-\frac{1}{\alpha}}$ |
|  | $\delta>1$ | $\Omega(1) \cdot\left(2^{-\left(1-\frac{1}{\alpha}\right) \delta} K\right)^{1-\frac{1}{\alpha}}$ |

Table 1: Lower bounds for Renyi entropy $\alpha$ and iid samples from an alphabet of size $K$, as in [Obremski and Skorski, 2017]

### 1.2 Our Results and Techniques (Renyi Entropy Rates)

Our main results

- we establish lower bounds for the sample complexity under Markov model of dependency, for Renyi entropy, known results only concern IID samples
- we show that those bounds hold both when estimating asymptotic entropy of Markov chain, and when estimating entropy of any fixed length path taken from any starting distribution.


## Our techniques

- we develop a lemma which measures closeness of sample paths of two chains; it non-trivially extends the classical result on the distance of two IID sequences and is of independent interest (the motiviation is Le Cam's method on Markov chains)
- we use perturbation theory to get insights into spectral properties of matrices; this technique greatly simplifies otherwise complicated calculations and is of independent interest.


## 2 Preliminaries

### 2.1 Notation

By $\mathbf{1}_{p, q}$ we denote the matrix of ones of size $p \times q$. By $\mathbf{0}_{p, q}$ we denote the matrix of zeros of size $p \times q$. By $I_{p}$ we denote the identity matrix of size $p \times p$

| Entropy | Num. of samples |
| :--- | :--- |
| $\mathbf{H}_{\infty}$ | $\Omega\left(\|S\|^{2}\right)$ |
| $\mathbf{H}_{2}$ | $\Omega\left(\|S\|^{\frac{3}{2}}\right)$ |
| $\mathbf{H}_{\alpha}(1<\alpha<\infty)$ | $\Omega\left(\|S\|^{2-\frac{1}{\alpha}}\right)$ |

Table 2: Lower Bounds for Markov Chain Entropy Estimation

The spectral radius of $M$ is denoted by $\rho(M)$. The $\alpha$-th Hadamard power of $M$ is defined as $M_{i, j}^{\diamond \alpha}=\left(M_{i, j}\right)^{\alpha}$ (the entry-wise power).
Matrix norms induced by vector $p$-th norms are denoted as usual by $\|\cdot\|_{p}$.

### 2.2 Entropy Rates

### 2.2.1 Entropy $\mathbf{H}_{\infty}$

Min-entropy of a discrete random variable $X$ is defined as $\mathbf{H}_{\infty}(X)=-\log \max _{x} \log \operatorname{Pr}[X=x]$. It is known that the min-entropy rate of a markov chain is determined by the average heaviest cycle [Kamath and Verdú, 2016]. The average weight of a cycle $\mathcal{C}=s_{0} \rightarrow s_{1} \rightarrow s_{2} \rightarrow \ldots s_{n}=s_{0}$ is defined as $\mathbf{w}(\mathcal{C})=\left(\prod_{i=1}^{n} M\left(s_{i-1}, s_{i}\right)\right)^{\frac{1}{n}}$ where $M$ is the transition matrix; the entropy rate equals

$$
\mathbf{H}_{\infty}(M)=-\log \max _{\mathcal{C}} \mathbf{w}(\mathcal{C})
$$

### 2.2.2 Entropy $\mathbf{H}_{\alpha}$

To evaluate the limiting Renyi entropy of order $\alpha$, one considers the spectral properties of the Hadamard power of the transition matrix. Namely for a chain with a transition matrix $M$ by [Rached et al., 2001] we have

$$
\mathbf{H}_{\alpha}(M)=\frac{1}{1-\alpha} \log \rho\left(M^{\diamond \alpha}\right)
$$

### 2.3 Le Cam's method

The popular technique of proving lower bounds on a minimax estimator is to find two sample distributions such that (a) they are statistically close and (b) the true values of estimated parameters or functionals are far away.
Since the values of estimated parameters are far away, we can use the estimator as a distinguisher between two sample distributions. But the samples are close together (say $\epsilon$-close) thus any distinguisher with constant chance of success requires at least $\Omega(1 / \epsilon)$ samples, which provides lower bound.

### 2.4 Perturbation Theory

The spectrum of a matrix remains (somewhat) stable under perturbations. There are many results of this form and we refer to [IPSEN, 2003] or [Zhan and Society, 2013] for more details and a survey; for our needs the classical result due to Bauer-Firke will be enough.
Lemma 2.1 (Bauer-Firke Eigenvalue Perturbation [Bauer and Fike, 1960]). If $A$ is a real normal matrix, that is $A A^{T}=A^{T} A$ then each eigenvalue of the matrix $A+E$ is at most $\delta$-close to some eigenvalue of $A$, where $\delta=\|E\|_{2}$.

Also the perturbations of eigenvectors have been studied. We will need to apply them to the stochastic matrices; in our case we will use bounds depending on a hitting times, due to Cho and Meyer.
Lemma 2.2 (Perturbation of MC stationary distributions [Cho et al., 2000]). The stationary distribution before and after the perturbation by a matrix $E$ differ in $\ell_{1}$-norm by at most $\kappa \cdot\|E\|_{\infty}$, for any $\kappa$ such that $\frac{m_{i, j}}{m_{j, j}} \leqslant 2 \kappa$ for all $i, j$ and $m_{i, j}$ is the expected time of hitting $j$ when the chain starts from $i$.

Note that for a uniform random walk over state space $S$ hitting times equal $m_{i, j}=|S|$. Indeed the probability that the walk returns to the starting state after more than $n$ steps equals $\left(1-|S|^{-1}\right)^{n}$; thus the expectation equals $|S|$.

### 2.5 Coupling

Coupling refers to building joint distribution with given marginals and is a powerful technique used to study Markov chains [Frank, 2010]. The following lemma slightly extends the standard construction of coupling
Proposition 2.1 (Consistent Coupling). For any four discrete random variables $X_{1}, X_{2}, Y_{1}, Y_{2}$ there exist distributions $X_{1}^{\prime}, X_{2}^{\prime}, Y_{1}^{\prime}, Y_{2}^{\prime}$ over same probability space, such that $X_{1}^{\prime}=X_{1}, X_{2}^{\prime}=X_{2}, Y_{1}^{\prime}=$ $Y_{1}, Y_{2}^{\prime}=Y_{2}$ and $\operatorname{Pr}\left[X_{1}^{\prime} \neq Y_{1}^{\prime}\right]=d_{T V}\left(X_{1}, Y_{1}\right)$.

### 2.6 Chernoff-Type Bounds for Markov Chains

Chernoff-type bounds hold also for Markov chains with exponentially small tails, but the constant depends on spectral properties of the transition matrix [Lezaud, 1998] or (which is related) on return times of the corresponding random walk [Chung et al., 2012]. In our case this translates to the sample complexity dependency also on the spectral gap.

## 3 Results

### 3.1 Sample Paths of Perturbed Markov Chains

The lemma below states that sample paths of two chains with close transition matrices remains statistically close, when the number of samples is not too big.
Lemma 3.1 (Total Variation of Markov Chains with Close Transitions). Consider two Markov chains with transition matrices $M$ and $M+E$, starting from their stationary distributions $\mu^{M}, \mu^{M+E}$. The total variation between $n+1$ samples is bounded by

$$
d_{\mathrm{TV}} \leqslant\left\|\mu^{M}-\mu^{M+E}\right\|_{1}+n \cdot\left(\mu^{M}\right)^{T} \cdot|E| \cdot \mathbf{1}
$$

where $|E|$ is the matrix of absolute entries of $E$ and $\mathbf{1}$ is the vector of ones.
Before we proceed to the proof let us make few remarks.
Remark 3.1 (Sparsity of Perturbation Helps). Note that $\left(\mu^{M}\right)^{T} \cdot|E| \cdot \mathbf{1}$ is a combination of row-sums of $E$ with weights $\mu_{M}$. For fixed $\mu$ the mapping $E \rightarrow \mu^{T} \cdot|E| \cdot \mathbf{1}$ is a matrix norm which captures sparsity.
Remark 3.2 (Bounds for IID distributions). Consider the following matrices $M_{X}=$ $\left[\begin{array}{cc}\frac{1}{m-\ell} & \mathbf{1}_{m, m-\ell}\end{array} \mathbf{0}_{m, \ell}\right]$ and $M_{Y}=\left[\begin{array}{ll}\mathbf{0}_{m, \ell} & \frac{1}{m-\ell} \mathbf{1}_{m, m-\ell}\end{array}\right]$. They describe IID distributions $\mu^{X}$ uniform over $1, \ldots, m-\ell$ and $\mu^{Y}$ uniform over $\ell, \ldots, m$ respectively. We can write $M_{Y}=M_{X}+E$ where $E=\left[\begin{array}{lll}-\frac{1}{m-\ell} \mathbf{1}_{m, \ell} & \mathbf{0}_{m, m-2 \ell} & \frac{1}{m-\ell} \mathbf{1}_{m, \ell}\end{array}\right]$. Applying Lemma 3.1 we get that the total variation between $n$ samples from $X$ and $n$ samples from $Y$ is bounded by $n \cdot \frac{\ell}{m-\ell}=n \cdot d_{\mathrm{TV}}\left(\mu^{X} ; \mu^{Y}\right)$, as in the standard bound for the distance of IID variables.

We give two proofs of Lemma 3.1- one by a coupling, the other by a dynamic programming technique where the distance for $n$ samples is expressed in terms of the distance of $n-1$ samples, and the connection is explicit due to factorization of finite-sample distributions under the Markov assumption.

Coupling. Let $X_{0}, \ldots, X_{n}$ and $Y_{0}, \ldots, Y_{n}$ be samples from Markov chains that have transition matrices $M_{X}$ and $M_{Y}$ respectively. For any coupling

$$
\begin{align*}
d_{T V}\left(X_{\leqslant n}, Y_{\leqslant n}\right)= & \operatorname{Pr}\left[X_{\leqslant n-1}=Y_{\leqslant n-1}\right] \cdot d_{T V}\left(X_{n} ; Y_{n} \mid X_{\leqslant n-1}=Y_{\leqslant n-1}\right)  \tag{1}\\
& +\operatorname{Pr}\left[X_{\leqslant n-1} \neq Y_{\leqslant n-1}\right] \cdot d_{T V}\left(X_{n} ; Y_{n} \mid X_{\leqslant n-1} \neq Y_{\leqslant n-1}\right) \\
\leqslant & d_{T V}\left(X_{n} ; Y_{n} \mid X_{n-1}=Y_{n-1}\right)+\operatorname{Pr}\left[X_{\leqslant n-1} \neq Y_{\leqslant n-1}\right] \tag{2}
\end{align*}
$$

where we used $d_{T V}\left(X_{n} ; Y_{n} \mid X_{\leqslant n-1}=Y_{\leqslant n-1}\right)=d_{T V}\left(X_{n} ; Y_{n} \mid X_{n-1}=Y_{n-1}\right)$ which follows from the Markov property. For two Markov matrices $M_{X}, M_{Y}$ and any distribution $\mu$ we have

$$
\left\|\mu^{T}\left(M_{X}-M_{Y}\right)\right\|_{1} \leqslant \mu^{T} \cdot\left|M_{X}-M_{Y}\right| \cdot \mathbf{1}
$$

If $X$ starts from the stationary distribution $\mu_{X}^{T}$ we have $X_{n}=\mu_{X}$ for all $n$. Therefore

$$
\begin{equation*}
d_{T V}\left(X_{n} ; Y_{n} \mid X_{n-1}=Y_{n-1}\right) \leqslant \mu_{X}^{T} \cdot\left|M_{X}-M_{Y}\right| \cdot \mathbf{1} \tag{3}
\end{equation*}
$$

There is a coupling such that

$$
\begin{equation*}
\operatorname{Pr}\left[X_{\leqslant n-1} \neq Y_{\leqslant n-1}\right]=d_{T V}\left(X_{\leqslant n-1}, Y_{\leqslant n-1}\right) \tag{4}
\end{equation*}
$$

Putting Equation (3) and Equation (4) into Equation (2) we get

$$
d_{T V}\left(X_{\leqslant n}, Y_{\leqslant n}\right) \leqslant \mu^{T} \cdot\left|M_{X}-M_{Y}\right| \cdot \mathbf{1}+\operatorname{Pr}\left[X_{\leqslant n-1} \neq Y_{\leqslant n-1}\right]
$$

so that the statement follows by induction.
Dynamic Programming. Consider the variation distance of $n+1$ samples

$$
d_{\mathrm{TV}}^{n}=\sum_{s_{0}, \ldots, s_{n}}\left|\mu_{s_{0}}^{M} \prod_{i=1}^{n} M_{s_{i-1}, s_{i}}-\mu_{s_{0}}^{M+E} \prod_{i=1}^{n}(M+E)_{s_{i-1}, s_{i}}\right|
$$

Writing $\mu_{s_{0}}^{M} \prod_{i=1}^{n} M_{s_{i-1}, s_{i}}$ as the difference of $\mu_{s_{0}}^{M} \prod_{i=1}^{n} M_{s_{i-1}, s_{i}} \cdot\left(M_{s_{n-1}, s_{n}}+E\right)$ and $\mu_{s_{0}}^{M} \prod_{i=1}^{n} M_{s_{i-1}, s_{i}} \cdot E$ and and applying the triangle inequality we get $d_{T V} \leqslant I_{1}+I_{2}$ where

$$
I_{1}=\sum_{s_{0}, \ldots, s_{n-1}}\left|\mu_{s_{0}}^{M} \prod_{i=1}^{n-1} M_{s_{i-1}, s_{i}}-\mu_{s_{0}}^{M+E} \prod_{i=1}^{n-1} M_{s_{i-1}, s_{i}}\right| \cdot\|M+E\|_{\infty}
$$

with $\|M+E\|_{\infty}=\max _{s_{n-1}} \sum_{s_{n}}\left|(M+E)_{s_{n-1}, s_{n}}\right|$ and

$$
I_{2}=\sum_{s_{0}, \ldots, s_{n-1}} \mu_{s_{0}}^{M} \prod_{i=1}^{n-1} M_{s_{i-1}, s_{i}} \cdot \sum_{s_{n}}\left|E_{s_{n-1}, s_{n}}\right|
$$

with $\|E\|_{\infty}=\max _{s_{n-1}} \sum_{s_{n}}\left|E_{s_{n-1}, s_{n}}\right|$. Observe that $\|M+E\|_{\infty}=1$ because $M+E$ is stochastic. Therefore

$$
\begin{equation*}
I_{1} \leqslant \sum_{s_{0}, \ldots, s_{n-1}}\left|\mu_{s_{0}}^{M} \prod_{i=1}^{n-1} M_{s_{i-1}, s_{i}}-\mu_{s_{0}}^{M+E} \prod_{i=1}^{n-1}(M+E)_{s_{i-1}, s_{i}}\right|=d_{\mathrm{TV}}^{n-1} \tag{5}
\end{equation*}
$$

If $\mu_{M}$ is stationary for $M$ then by Chappman-Klomogorov

$$
\begin{aligned}
I_{2} & =\left(\mu^{M}\right)^{T} \cdot(M+E)^{n-1} \cdot|E| \cdot \mathbf{1} \\
& =\left(\mu^{M}\right)^{T} \cdot M^{n-1} \cdot|E| \cdot \mathbf{1} \\
& =\left(\mu^{M}\right)^{T} \cdot|E| \cdot \mathbf{1}
\end{aligned}
$$

Summing up we get

$$
d_{\mathrm{TV}}^{n} \leqslant d_{\mathrm{TV}}^{n-1}+\left(\mu^{M}\right)^{T} \cdot|E| \cdot \mathbf{1}
$$

which by induction implies the statement.

### 3.2 Construction of Extreme Matrix

From now on we assume that the state space has $|S|=m$ elements. We apply Le Cam's method to two Markov chains:

- the uniform random walk
- perturbation of uniform random walk which overweights one element, the transition matrix of this chain is defined below

$$
M=\left[\begin{array}{cc}
\frac{1}{m} \mathbf{1}_{m-1, m-1} & \frac{1}{m} \mathbf{1}_{m-1,1}  \tag{6}\\
\left(\frac{1}{m}-\frac{\epsilon}{m-1}\right)^{\mathbf{1}_{1, m-1}} & \left(\frac{1}{m}+\epsilon\right)
\end{array}\right]
$$

Because the perturbation is sparse, the change in the distance of finite samples will be small. On the other hand we will see that it has a significant effect on the spectrum of Hadamard powers.

### 3.3 Mixing Time is Good

[Kamath and Verdú, 2016] showed that bad mixing properties heavily impact the efficiency of an estimator. Here we argue that Markov chains we mentioned above have very good mixing times, thus concluding that estimation of entropy is still hard even when restricted to Markov chains with good mixing properties.

For the unperturbed matrix eigenvalues are 1 (single) and 0 (multiplicity of $m-1$ ); this follows from well-known properties of matrix of ones [Horn and Johnson, 2013]. It follows that the spectral gap is constant. After the perturbation we maintain the constant spectral gap, which follows again by perturbation theory (Lemma 2.1). Note that elementary row operations change eigenvalues, so calculating explicitly the spectrum is hard (although doable for this specific case)!

### 3.4 Entropy Rates

We state our results for entropy rates which, for stochastic sources such as Markov chains, are understood as the limiting entropy per symbol (for Markov chains they exist under standard assumptions such as ergodicity).

### 3.4.1 Rate Evaluation for $\mathbf{H}_{\infty}$

We need to find the change in the entropy rate and statistical distance when changing from $\epsilon$ to $\epsilon=0$ in Equation (6).
Claim 3.1 (Min-Entopy Rate). For the chain with transition matrix as in (6)

$$
\mathbf{H}_{\infty}(M)=-\log \left(\frac{1}{m}+\epsilon\right)
$$

Proof. The heaviest cycle is the self-loop at the $m$-th state.
Claim 3.2 (Statistical Distance Closeness). The variational distance between n samples from $M$ in Equation (6) and the random walk, assuming both chains start from their stationary distributions, is bounded by $O(\epsilon+n \epsilon / m)$.

Proof. This follows from Lemma 3.1 applied to $M$ being the matrix of the random walk and $E$ equal to

$$
E=\left[\begin{array}{cc}
\mathbf{0}_{m-1, m-1} & \mathbf{0}_{m-1,1} \\
-\frac{\epsilon}{m-1} \mathbf{1}_{1, m-1} & \epsilon
\end{array}\right]
$$

Since $\mu^{M}=\frac{1}{m} \mathbf{1}_{m, 1}$ we get

$$
\mu^{M} \cdot|E| \cdot \mathbf{1}_{m, 1}=O(\epsilon / m)
$$

note that the sparsity of $E$ helps! The distance between stationary distributions can be bounded by $O(\epsilon)$ according to Lemma 2.2.

Corollary 3.1 (Entropy Separation). If we take $\epsilon=1 / m$, then min-entropy of perturbed chain will be $\log \left(\frac{m}{2}\right)$ while min-entropy of uniformly random walk remains $\log (m)$, thus the min-entropies of two Markov chains differ by 1.
Corollary 3.2 (Statistical Distance). Let $\epsilon=\frac{1}{m}$, by Claim 3.2 the distance between $n$ samples is bounded by $O\left(n \cdot m^{-2}\right)$.

By the two above corollaries and the Le Cam's method described in Section 2.3 we get our lower bound for min-entropy.

### 3.4.2 Rate Evaluation for $\mathrm{H}_{2}$

In the lemmas below we estimate the difference in entropy and closeness in statistical distance for these two chains. The results are given in Corollary 3.4 and Corollary 3.3 below.

Lemma 3.2 (Spectral Radious Gap). Consider the matrix in Equation (6). The spectral radius of its second Hadamard power satisfies

$$
\rho\left(M^{\diamond 2}\right)=\max \left(\frac{1}{m},\left(\frac{1}{m}+\epsilon\right)^{2}\right)+O\left(m^{-\frac{3}{2}}\right)
$$

More generally, the eigenvalues are $O\left(m^{-\frac{3}{2}}\right)$ (with $m-2$ repeats), $\frac{1}{m}+O\left(m^{-\frac{3}{2}}\right)$ and $\left(\frac{1}{m}+\epsilon\right)^{2}+$ $O\left(m^{-\frac{3}{2}}\right)$.
Corollary 3.3 (Entropy Separation). For $\epsilon=\sqrt{2 / m}$ one obtains $\rho\left(M^{\diamond 2}\right)=\frac{2+o(1)}{m}$ for large $m$. For $\epsilon=0$ we have $\rho\left(M^{\diamond 2}\right)=\frac{1}{m}$. Therefore collision entropy rates of these two Markov chains differ by 1 bit.
Corollary 3.4 (Statistical Distance). By Claim 3.2, for $\epsilon=\sqrt{2 / m}$ the distance between $n$ samples is bounded by $O\left(n \cdot m^{-3 / 2}\right)$.

Again by applying the Le Cam's method described in Section 2.3 to above corollaries we get our lower bound for collision entropy.

Proof of Lemma 3.2. We have

$$
M^{\diamond 2}=\left[\begin{array}{cc}
\frac{1}{m^{2}} \mathbf{1}_{m-1, m-1} & \frac{1}{m^{2}} \mathbf{1}_{m-1,1} \\
\left(\frac{1}{m}-\frac{\epsilon}{m-1}\right)^{2} \mathbf{1}_{1, m-1} & \left(\frac{1}{m}+\epsilon\right)^{2}
\end{array}\right]
$$

We want to compute the spectral radious of $M^{\diamond 2}$. We can write

$$
M^{\diamond 2}=Z+E
$$

where $Z$ is the block-diagonal matrix given by

$$
Z=\left[\begin{array}{cc}
\frac{1}{m^{2}} \mathbf{1}_{m-1, m-1} & \mathbf{0}_{m-1,1} \\
\mathbf{0}_{1, m-1} & \left(\frac{1}{m}+\epsilon\right)^{2}
\end{array}\right]
$$

and $E$ has non-zero elements only in the last row and column, of magnitude $O\left(\mathrm{~m}^{-2}\right)$. In particular we obtain $\|E\|_{2} \leqslant O\left(m^{-\frac{3}{2}}\right)$ (for example by bounding the Frobenius norm which in turn bounds the second norm) and by Lemma 2.1 ( $Z$ is symmetric hence normal!)

$$
\rho\left(M^{\diamond 2}\right)=\rho(Z)+O\left(m^{-\frac{3}{2}}\right)
$$

so that we can focus on finding the spectrum of $Z$. But they follow from the block-diagonal structure - the first $m-1 \times m-1$ minor has eigenvalues $\frac{m-1}{m^{2}}$ (simple) and 0 (repeated $m-2$ times); the $m$-th eigenvalue is $\left(\frac{1}{m}+\epsilon\right)^{2}$. In view of the previous bound this finishes the proof.

### 3.4.3 Rate Evaluation for $\mathbf{H}_{\alpha}$

By proceeding in the same way as for $\mathbf{H}_{2}$ we arrive at $\rho\left(M^{\diamond \alpha}\right)=\rho(Z)+O\left(m^{-\frac{2 \alpha-1}{2}}\right)$ where $Z$ has same structure but the power of 2 is replaced by $\alpha$. This gives us

$$
\rho\left(M^{\diamond \alpha}\right)=\max \left(\frac{1}{m^{\alpha-1}},\left(\frac{1}{m}+\epsilon\right)^{\alpha}\right)+O\left(m^{-\frac{2 \alpha-1}{2}}\right)
$$

Let $\epsilon=(2 / m)^{\frac{\alpha-1}{\alpha}}$ then we get $\rho\left(M^{\diamond \alpha}\right)=(2 / m)^{\alpha-1}(1+o(1))$ for large $m$. This gives a constant entropy gap and the statistical distance of $O\left(n \cdot m^{-2+\frac{1}{\alpha}}\right)$ between the two paths studied in Le Cam's method.
Note: when deriving formulas above we assumed large $m$ in $o(1)$ terms, but in fact we have lower bounds of form $\rho\left(M^{\diamond \alpha}\right) \geqslant(2 / m)^{\alpha-1}$ which is sufficient.

### 3.5 Upper Bounds

We can apply Chernoff-type bounds to get frequencies up to a multiplicative error term. This will cost $|S|^{2} \operatorname{polylog}(|S|, 1 / \epsilon)$ samples. We defer the easy proof to the final version.

## 4 Finite Sample Bounds

Our bounds were derived for the problem of estimating asymptotic entropy rate, but they remain valid also for the task of estimating entropy of finite number of samples. We will give the argument for min-entropy, the Renyi entropy case will be discussed in the full version.

For the min-entropy this follows because the entropy of $n$ samples for both matrices considered equals $n$ times the entropy rate. Indeed, the min-entropy of $n$ samples generated from the chain with the transition matrix as in Equation (6) is full when $\epsilon=0$ and for the case $\epsilon>0$ achieved for $n$ repetitions of the $m$-th symbol.

## 5 Conclusions

We have shown lower bounds for Renyi entropy rate estimation under the Markov chain model.

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