Sine Series Approximation of the Mod Function for Bootstrapping of Approximate HE

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Abstract

While it is well known that the sawtooth function has a point-wise convergent Fourier series, the rate of convergence is not the best possible for the application of approximating the mod function in small intervals around multiples of the modulus. We show a different sine series, such that the sine series of order n has error $O(\epsilon^{2n+1})$ for approximating the mod function in ϵ-sized intervals around multiples of the modulus. Moreover, the resulting polynomial, after Taylor series approximation of the sine function, has small coefficients, and the whole polynomial can be computed at a precision that is only slightly larger than $-(2n+1)\log\epsilon$, the precision of approximation being sought. This polynomial can then be used to approximate the mod function to almost arbitrary precision, and hence allows practical CKKS-HE bootstrapping with arbitrary precision. We validate our approach by an implementation and obtain 100 bit precision bootstrapping as well as improvements over prior work even at lower precision.

1 Introduction

The work of [CKKS17, CHK+18b] presented a new homomorphic encryption (HE) scheme for approximate arithmetic (called the CKKS-HE scheme) over real/complex numbers. The CKKS-HE scheme was considerably more efficient than other schemes for approximately evaluating arithmetic circuits and leveraged properties of approximate arithmetic to achieve these efficiency gains. One of the key insights was to treat the homomorphic encryption error as part of the approximate arithmetic error, and, thus, no additional mechanism was required to round away the homomorphic encryption error after decryption. The CKKS-HE scheme has found many applications, among them privacy-preserving machine learning and secure genome analysis (see [KSK+18, MHS+20, BHHH19, KSW+18, SPTP+20, KHB+20] for some examples).

However, the initial CKKS-HE scheme was only capable of evaluating low-depth circuits since it lacked a bootstrapping procedure to "refresh" the ciphertext modulus to enable further homomorphic computation. This was remedied when [CHK+18a] introduced the first bootstrapping procedure for the CKKS-HE scheme. This involved viewing a ciphertext ct with a small modulus q as a ciphertext with respect to the largest modulus q_L and then homomorphically computing coefficient rounding modulo q to obtain a new ciphertext ct' that encrypts approximately the same message as ct with respect to a larger modulus q_ℓ, enabling further homomorphic computation. Thus, a challenge here is to compute the mod function homomorphically, which is not easily representable via an arithmetic circuit. In fact, the mod function modulo q on the interval $[-Kq, Kq]$ for some integer K is not even a continuous function. However, [CHK+18a] made the clever observation that in the CKKS-HE scheme, we have an upper bound m on the size of the message, which can be made much smaller than q. In this situation, we actually only need to be able to compute the mod function on points in $[-Kq, Kq]$ that are a distance at most m from a multiple of q. In this case, the mod function is periodic with period q and is linear on each of the small intervals around a multiple of q. Figure 1 shows the mod function along with the small intervals for approximation.

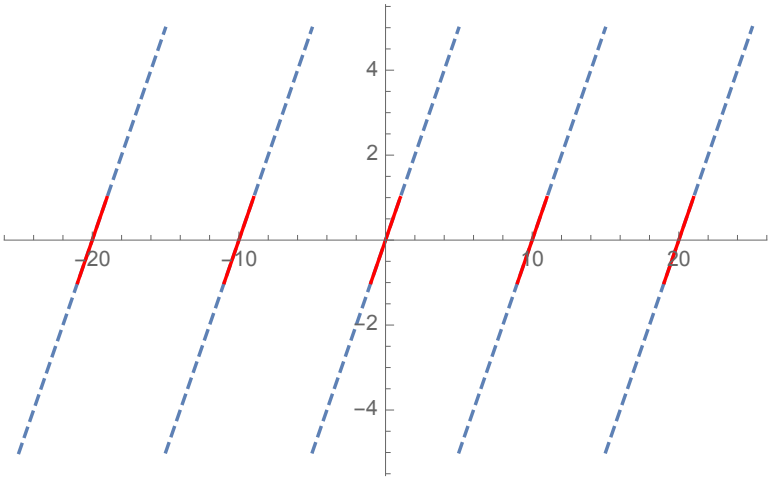

Figure 1: The mod function with modulus $q = 10$. The solid red lines represent the small intervals on which we need to approximate.

The work of [CHK+18a] further observed that the mod function $[t]_q$ on these intervals can be approximated via a scaled sine function $S(t) = \frac{q}{2\pi} \sin\left(\frac{2\pi t}{q}\right)$. This approximation introduces an inherent error that depends on the message upper bound m. Let ϵ denote the ratio $\frac{m}{q}$. Then,

it can be shown that

$$|[t]_q - S(t)| \leq \frac{2\pi^2}{3} q\epsilon^3.$$

If ϵ is small enough, then this error can be sufficiently small for use in bootstrapping provided that $S(t)$ can be well-approximated by a low degree polynomial. The work of [CHK$^+$18a] along with several followup works [CCS19, HK20] proceeded to provide methods of approximating this scaled sine function (or scaled cosine function in the case of [HK20]) by a low-degree polynomial, which can then be plugged into the bootstrapping procedure of [CHK$^+$18a]. However, due to the inherent error between the mod function $[t]_q$ and the scaled sine function $S(t)$, this approach has a "fundamental error" that will occur regardless of how $S(t)$ is approximated. One of the problems with this is that in order for the error to be $O(1)$ (and, therefore, not destroy the message), m must be $O(q^{2/3})$. This means that we must begin bootstrapping while the size of the encrypted message is considerably smaller than q, which is a source of inefficiency in the bootstrapping procedure, particularly in applications that require high precision. An even greater problem is that when homomorphically computing the mod function, we must treat $qI + m$ for some integer I as the input, which we refer to as the bootstrapping plaintext. The issue with this is that if q is significantly larger than m, then since the number of modulus bits "consumed" by each homomorphic multiplication of the mod function is the size of the bootstrapping plaintext, these homomorphic multiplications will consume significantly more modulus bits than normal homomorphic operations. Thus, it is *inefficient* to obtain high-precision bootstrapping by simply increasing q to decrease ϵ. Instead, in order to obtain high-precision bootstrapping, it is beneficial to obtain good polynomial approximations to the mod function for fixed ϵ. An additional challenge to obtaining high-precision bootstrapping is that the approximation to the mod function must be representable by a *low-degree* polynomial. If the degree of the polynomial is too high, evaluating it homomorphically may consume almost all of the ciphertext modulus, leaving the ciphertext after bootstrapping incapable of performing many homomorphic operations. Compounding this challenge is the fact that the coefficients of the low-degree polynomial approximation to the mod function must additionally be small. This is because if the coefficients are large, when evaluating the polynomial, the basis polynomials must be computed to higher precision to ensure the stability of the computation, since errors introduced by approximate arithmetic are amplified by large coefficients.

The reason obtaining high-precision bootstrapping for CKKS-HE is important is that one of the main applications for CKKS-HE is privacy-preserving machine learning. However, many ML algorithms require high precision computation in order to converge. This may be especially true during the learning phase of neural networks, which involves back propagation and integer division by private integers. Additional nonlinear steps involve pooling functions, threshold functions, etc. Moreover, due to their high depth, computing these ML algorithms homomor-

phically without bootstrapping is infeasible. Thus, for privacy-preserving ML applications, high-precision bootstrapping is required.

Recently, the works of [LLL+20] and [JM20] were able to bypass the "fundamental error" in the approximation of the mod function by a scaled sine function to obtain higher-precision bootstrapping. [LLL+20] attempts to avoid the scaled sine function by finding the optimal minimax polynomial of a fixed degree that approximates the mod function via algorithmic search. They use a variant of the Remez algorithm [Rem34] to obtain an approximation to the optimal minimax polynomial of a given degree that approximates the modular reduction function on the union of intervals containing points close to multiples of q. Unfortunately, as observed by [LLL+20], the size of the coefficients of these polynomials are too large to enable high-precision bootstrapping. They then show that by using a composition of sine/cosine and the inverse sine function and using the Remez algorithm to algorithmically search for good polynomial approximations to these functions, one can obtain higher-precision bootstrapping, but their bootstrapping method has only been shown to obtain 40 bit message precision in the latest version of their work. [JM20] avoids the "fundamental error" by finding direct polynomial approximations of the mod function on small intervals around the modulus via a new technique called modular Lagrange interpolation. The coefficients of these polynomials were small enough to enable high-precision bootstrapping. However, the coefficients were still large enough that in order to evaluate the polynomial approximations, one would need to operate at a higher precision than the bootstrapping plaintext. Ultimately, this fact corresponded to the bootstrapping procedure losing additional levels, since the computations during bootstrapping were operating at a higher precision. The authors are able to obtain 67 bit precision bootstrapping in the latest version of their work.

1.1 This Work

In this work, we show how to obtain arbitrary precision bootstrapping via a different method from that of [JM20] and more in line with the original sine function approach of [CHK+18a]. Instead of approximating the mod function directly, we first approximate the mod function by a sine series and then approximate the sine function by its Taylor series (more precisely, the Taylor series of e^{ix}). This is then followed by a series of squarings to approximate the other terms in the sine series. We show that the sine series converges to the mod function in small intervals around the modulus. In particular, our sine series of order n has error $O(\epsilon^{2n+1})$ for approximating the mod function in ϵ-sized intervals around multiples of the modulus.

Thus, we avoid the fundamental error of the scaled sine approach and are able to obtain an approximation with arbitrarily small error in the desired intervals. Furthermore, the coefficients of the sine series are small (in fact, they have norm < 2). This, combined with the fact that the

Taylor series expansion of $\sin x$ has small coefficients, leads to a polynomial approximation of the mod function with small coefficients. Due to these small coefficients, the whole polynomial can be computed at a precision only slightly larger than $(-2n-1)\log\epsilon$, the precision of the approximation being sought.

We validate our approach by an implementation and obtain 100 bit precision bootstrapping as well as improvements over prior work even at lower precision.

1.2 Problem Overview

Here, we provide a brief overview of the challenges of approximating the mod function for use in CKKS-HE bootstrapping. We provide a thorough overview of the bootstrapping procedure in Section 3. The goal of CKKS-HE bootstrapping is to take a ciphertext ct at the lowest level and bring it up to the highest level so that homomorphic computation can continue. In other words, we wish to obtain a ciphertext ct' such that

$$\langle \mathsf{ct}, \mathsf{sk} \rangle \bmod q \approx \langle \mathsf{ct}', \mathsf{sk} \rangle \bmod q_\ell,$$

where q is the lowest level modulus and q_ℓ represents a higher level modulus. Since errors accumulated during homomorphic computation are not eliminated by decryption in CKKS-HE, the goal is not to reduce the error in the ciphertext, but, rather, to increase the modulus so that more computations can be performed. If one simply views the ciphertext ct as operating at the highest level q_L, then it follows that $\langle \mathsf{ct}, \mathsf{sk} \rangle \bmod q_L = qI + m$. The magnitude of I can be upper bounded and $m << q$ and, thus, the challenge then becomes to compute mod q on small intervals near multiples of q (we defer additional complications such as computing on slots vs. coefficients to Section 3). Since CKKS-HE can compute homomorphic additions and multiplications, we need a polynomial approximation to the mod function. However, there are three crucial criteria that are relevant to the bootstrapping application.

- **Error:** The error of the approximation contributes additional error to the message m, which, if large, will cause a loss in plaintext precision.

- **Degree:** The degree of the polynomial approximation determines the multiplicative depth required to evaluate it. A larger multiplicative depth corresponds to losing more modulus levels and, thus, if too large, the polynomial will not be able to be evaluated homomorphically.

- **Coefficient Magnitude:** The size of the coefficients of the polynomial approximation determine the "evaluation precision" at which one must operate during bootstrapping.

Larger coefficients correspond to a larger "evaluation precision" in order to maintain numerical stability, which, in turn, corresponds to losing more modulus bits per level.

Thus, it is critical that we obtain good low-degree polynomial approximations to the mod function in small intervals around multiples of the modulus that additionally have small coefficients. Moreover, as discussed previously, it is important the ratio $m/q = \epsilon$ is not too small, since then the size of the bootstrapping plaintext $qI + m$ will be significantly larger than m, and homomorphically evaluating the approximation to the mod function will consume a large number of modulus bits. Thus, one can think of ϵ as fixed to be, say 2^{-10}.

1.3 Sine Series

As mentioned previously, several prior approaches to CKKS-HE bootstrapping approximated the mod function via a scaled sine function. For simplicity, we will ignore the scaling for the moment and try to obtain a good approximation to the mod 2π function. Thus, prior works used $\sin x$ as an approximation of this function and noted that, for $|x| < \epsilon$, the error of approximation is $O(\epsilon^3)$. It is well-known that the Fourier series of the mod function (or sawtooth function) converges everywhere except the discontinuities. Unfortunately, the rate of convergence is too slow, and the Fourier series does not give a good approximation when the number of terms is small. Instead, we will approximate the mod function by a different sine series such that it converges to the mod function near multiples of the modulus very quickly. As a warmup, suppose we added a $\sin 2x$ term to our approximation of the mod function. If we can determine coefficients β_1 and β_2 such that the Taylor series expansion of $\beta_1 \sin x + \beta_2 \sin 2x$ is $x + x^5 p(x)$ for some polynomial $p(x)$, then for $|x| < \epsilon$, the error of approximation will be $O(\epsilon^5)$, an improvement on $\sin x$. Thus, looking at the x and x^3 terms in the Taylor series expansions of $\sin x$ and $\sin 2x$, we wish to determine β_1, β_2 such that $\beta_1 + 2\beta_2 = 1$ (so that the coefficient of x is 1) and $\beta_1 + 2^3\beta_2 = 0$ (so that the coefficient of x^3 is 0). This can be solved to yield $\beta_1 = 4/3, \beta_2 = -1/6$. This intuition can then be extended to give an n-term sine series with error $O(\epsilon^{2n+1})$. We will show that the β_i's are small and, thus, the resulting low-degree polynomial approximation has small coefficients. Moreover, we will show that the constants hiding in the big-O notation are reasonable, and the dependence on n is minor.

1.4 On Approximating Arcsine

An alternative way to view our result is that having computed the periodic function $\sin x$, our sine series allows us to compute arcsin (of $\sin x$) using an angle-multiplication computation. In other words, since we showed above that $x = 4/3 \sin x - 1/6 \sin 2x + O(x^5)$ (for small x, and hence small $\sin x$), then equivalently $\arcsin y = 4/3\ y - 1/6\ d(y) + O(y^5)$, where d is a function

such that $d(\sin x) = \sin 2x$. However, $d(\sin x)$ is not a simple polynomial function of $\sin x$ (as opposed to the easy double-angle formula for $\cos x$), and this way of computing $\arcsin y$ cannot use a simple polynomial of y. While good polynomial approximations of $\arcsin y$ might exist (for small y), there seems no simple methodology to obtain this. Instead, [LLL$^+$20] use the Remez algorithm to obtain a best fit low degree polynomial approximation of arcsin. This algorithmic approach has the drawback that while the polynomial degree maybe small, the coefficients of the polynomial output by Remez algorithm can be of arbitrary size. Fortunately, [LLL$^+$20] report that the coefficients are small enough to obtain 40-bit precision bootstrapping, although it is not clear if this holds in general.

Our approach is different, as we utilize the potential of CKKS-HE to compute on complex numbers. Thus, instead of first computing $\sin x$ and then its arcsin, we first compute the periodic function e^{ix} (using its Taylor series approximation) and then compute its logarithm. Thus, given that $x = 4/3 \sin x - 1/6 \sin 2x + O(x^5)$, we also get that $x = \mathrm{Im}(4/3\, e^{ix} - 1/6\, e^{2ix}) + O(x^5)$ (for small x). Most importantly, it is a polynomial in its argument (i.e. e^{ix}) with small coefficients. Thus, this allows for an easy homomorphic computation.

1.5 Organization

In Section 2, we formalize the above intuition and prove explicit error bounds for the sine series approximation of the mod function. In Section 3, we overview the bootstrapping procedure for CKKS-HE. In Section 4, we explain how to approximate the sine series by a low-degree polynomial for bootstrapping. In Section 5, we implement bootstrapping using our sine series approximation and give performance metrics and comparisons with prior approaches.

2 Sine Series Approximation

In this section, we will show the following theorem and corollaries, giving a sine series approximation to the mod function in small intervals around the modulus that can be used for CKKS-HE bootstrapping.

Theorem 1 *For every $n \geq 1$, there exists a sequence of rational numbers $\beta_1, ...\beta_n$ such that for every ϵ, $0 < \epsilon < 2/\sqrt{n}$, for every $|x| < \epsilon$,*

$$\left| x - \sum_{k=1}^{n} \beta_k \sin(kx) \right| < e^2 * (n+1) * (\epsilon/2)^{2n+1}$$

Using the periodicity of the sine function, we immediately arrive at the following corollary.

Corollary 2 *For every $n \geq 1$, there exists a sequence of rational numbers $\beta_1, ...\beta_n$ such that for every ϵ, $0 < \epsilon < 2/\sqrt{n}$, for every integer m, for every x such that $|x - 2m\pi| < \epsilon$,*

$$\left|(x \bmod 2\pi) - \sum_{k=1}^{n} \beta_k \sin(kx)\right| < e^2 * (n+1) * (\epsilon/2)^{2n+1}$$

A further simple manipulation leads to the following scaled version of the corollary.

Corollary 3 *For every $n \geq 1$, there exists a sequence of rational numbers $\beta_1, ...\beta_n$ such that for every ϵ, $0 < \epsilon < \frac{1}{\pi\sqrt{n}}$, for every integer $q \geq 1$, for every integer m, for every x such that $|x - m * q| < \epsilon * q$,*

$$\left|(x \bmod q) - \frac{q}{2\pi} * \sum_{k=1}^{n} \beta_k \sin(2\pi k * x/q)\right| < \frac{e^2 * q}{2\pi} * (n+1) * (\epsilon\pi)^{2n+1}$$

Determining the β_i's: To prove Theorem 1, for each n, we will determine the rational numbers $\{\beta_i\}_{i\in[n]}$. In particular, these are *not* the same as the Fourier coefficients of the sawtooth function, as we are focused on x that is potentially much smaller than the period of the sawtooth function. Recall that we wish to determine $\{\beta_i\}_{i\in[n]}$ such that the resulting sine series has a Taylor series expansion of the form $x + x^{2n+1}p(x)$ for some polynomial $p(x)$. In particular, there are no terms of degree $< 2n+1$ (except for x). These constraints give a system of equations that can be solved to determine the β_i's.

We begin by formalizing this intuition. For every $n > 0$, for every sequence of n distinct integers $\mathbf{a} = (a_1, ..., a_n)$, let $V^{(n)}(\mathbf{a})$ denote the Vandermonde matrix of $\mathbf{a}$, i.e. it is the $n \times n$ matrix with the (i,j)-th element a_i^{j-1} (for $i, j \in [1..n]$). Define $S^{(n)}(\mathbf{a})$ to be the $n \times n$ matrix with the (i,j)-th element a_i^{2j-1}, i.e. each row is the odd powers of the elements of $\mathbf{a}$. Note that the first column of this matrix is just $\mathbf{a}$. Also, define a related matrix $\hat{S}^{(n)}(\mathbf{a})$ to be the $n \times n$ matrix which is same as $S^{(n)}(\mathbf{a})$ except that the first column (i.e. $\mathbf{a}$) is replaced by $(2n+1)$-th powers of $\mathbf{a}$. In other words, the $(i,1)$-th element of this matrix is $a_i^{(2n+1)}$.

Let $\vec{\beta} = (\beta_1, \beta_2, \ldots, \beta_n)$ be an n-vector of rational numbers. For the sine series approximation, we would like to determine $\vec{\beta}$ so that the transpose of the matrix $S^{(n)}(\mathbf{a})$ multiplied by $\vec{\beta}$ is a vector with all entries zero except the first, which is one. Since β_i refers to the coefficient of the $\sin(a_i x)$ term in the sine series, the above requirement ensures that when we Taylor expand each sine term in the sine series about the origin (or a multiple of 2π) and sum the terms, the resulting polynomial will be $x + x^{2n+1}p(x)$ for some polynomial $p(x)$. Thus, the $x^3, x^5, \ldots, x^{2n-1}$ terms in the Taylor series expansions of the $\sin(ix)$'s cancel out. We note

that since our sine series will include $\sin x, \sin 2x, \sin 3x, \ldots$ terms, we will later instantiate $\mathbf{a}$ with $(1, 2, \ldots, n)$. The required condition is drawn below.

$$\begin{pmatrix} a_1 & a_2 & \ldots & a_n \\ a_1^3 & a_2^3 & \ldots & a_n^3 \\ & & \vdots & \\ a_1^{2n-1} & a_2^{2n-1} & \ldots & a_n^{2n-1} \end{pmatrix} \cdot \begin{pmatrix} \beta_1 \\ \beta_2 \\ \vdots \\ \beta_n \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix} \tag{1}$$

Let d_i denote the $(i,1)$-th minor of $S^{(n)}(\mathbf{a})$. In other words, the list $\{d_i\}_i$ is the list of minors of the first column of $S^{(n)}(\mathbf{a})$.

Lemma 4

$$\beta_i \;=\; (-1)^{i+1} * \frac{d_i}{\det(S^{(n)}(\mathbf{a}))}.$$

Proof: From the above equation, $\vec{\beta}$ is just the first column of the inverse of $(S^{(n)}(\mathbf{a}))^T$. Note that the $(i,1)$-th element of the inverse of the transpose of $S^{(n)}(\mathbf{a})$ is $(-1)^{i+1} * d_i$ divided by the determinant of $S^{(n)}(\mathbf{a})$. □

We now give an explicit formula for the determinant of $S^{(n)}(\mathbf{a})$. We will also give an explicit formula for the determinant of $\hat{S}^{(n)}(\mathbf{a})$, which will be of use later. We will use the well-known fact that the determinant of the Vandermonde matrix is given by the following formula.

$$\det(V^{(n)}(\mathbf{a})) \;=\; \prod_{i=1}^{n} \prod_{1 \le j < i} (a_i - a_j).$$

Lemma 5 *The determinant of the matrix $S^{(n)}(\mathbf{a})$ is*

$$\left(\prod_{i=1}^{n} a_i\right) * \prod_{i=1}^{n} \prod_{1 \le j < i} (a_i^2 - a_j^2).$$

The determinant of the matrix $\hat{S}^{(n)}(\mathbf{a})$ is

$$(-1)^{n-1} \;*\; \det(S^{(n)}(\mathbf{a})) \;*\; \prod_{i=1}^{n} a_i^2.$$

Proof: We will first focus on the matrix $S^{(n)}(\mathbf{a})$. For computing the determinant, for each row i, we get a contribution of a factor a_i towards the determinant, and the remaining matrix

is then just a Vandermonde matrix with all powers of a_i^2. Thus,

$$\det(S^{(n)}(\mathbf{a})) = \left(\prod_{i=1}^{n} a_i\right) * \det(V^{(n)}(\mathbf{a}')),$$

where $\mathbf{a}' = (a_1^2, \ldots, a_n^2)$. The result then follows from the well-known determinant of Vandermonde matrices.

As for the claim for the matrix $\hat{S}^{(n)}(\mathbf{a})$, first consider a modified matrix that is obtained by moving the first column to the last. Since this can be accomplished by $(n-1)$ column exchanges, the determinant of the modified matrix is $(-1)^{n-1}$ times the determinant of $\hat{S}^{(n)}(\mathbf{a})$. Furthermore, the determinant of the modified matrix is easily related to determinant of $S^{(n)}(\mathbf{a})$ by noting that i-th row in the modified matrix is a_i^2 times the i-th row in $S^{(n)}(\mathbf{a})$. □

We observe from the formula for the determinant of $S^{(n)}(\mathbf{a})$ that if the sequence of integers $\mathbf{a}$ are in increasing order and lower bounded by one, then the determinant of $S^{(n)}(\mathbf{a})$ is positive. We now show the following lemma, characterizing the β_i's.

Lemma 6 *For the matrix $S^{(n)}(\mathbf{a})$ with $\mathbf{a}$ set to the sequence of integers from one to n,*

$$\beta_1 = \frac{2n}{n+1} < 2$$

and, for $i \geq 2$

$$|\beta_i| \ < \ 1.$$

Moreover, the β_i's alternate in sign and decrease in magnitude as i increases. That is,

$$|\beta_{i+1}| < |\beta_i|$$

for all $i \in [n]$, $\beta_{2j+1} > 0$, and $\beta_{2j} < 0$.

Proof: We will show this using the formula for β_i from Lemma 4. By definition,

$$d_i = \det \begin{pmatrix} a_1^3 & a_1^5 & \ldots & a_1^{2n-1} \\ a_2^3 & a_2^5 & \ldots & a_2^{2n-1} \\ & & \vdots & \\ a_{i-1}^3 & a_{i-1}^5 & \ldots & a_{i-1}^{2n-1} \\ a_{i+1}^3 & a_{i+1}^5 & \ldots & a_{i+1}^{2n-1} \\ & & \vdots & \\ a_n^3 & a_n^5 & \ldots & a_n^{2n-1} \end{pmatrix}$$

Thus,

$$d_i = \left(\prod_{j=1, j\neq i}^{n} a_j^2 \right) * \det(S^{(n-1)}(\mathbf{a}')),$$

where $\mathbf{a}'$ is $\mathbf{a}$ with a_i removed. Thus,

$$\beta_i = (-1)^{i+1} * \frac{\left(\prod_{j=1, j\neq i}^{n} a_j^2\right)}{a_i * \left(\prod_{j=1}^{i-1}(a_i^2 - a_j^2)\right) * \left(\prod_{j=i+1}^{n}(a_j^2 - a_i^2)\right)}.$$

We observe that every term in the above expression is positive except for $(-1)^{i+1}$ and, thus, the β_i's alternate sign with $\beta_{2j+1} > 0$ and $\beta_{2j} < 0$. It follows that

$$\beta_1 = \frac{2(n!)^2}{(n+1)!(n-1)!} = \frac{2n}{n+1} < 2.$$

Moreover, for $i \geq 2$,

$$|\beta_i| = \frac{1}{i} * \frac{2(n!)^2}{(2n)!} * \binom{2n}{n+i}$$

Observe that $|\beta_{i+1}| < |\beta_i|$. Moreover, since $\binom{2n}{n+i} < \binom{2n}{n}$ for $i \geq 2$, it follows that

$$|\beta_i| < \frac{2}{i} \leq 1$$

for $i \geq 2$. □

Bounding the Error: A First Attempt Having characterized the β_i's, we now turn our focus to bounding the error between $f(x) = \sum_{k=1}^{n} \beta_k \sin(kx)$ and x for $|x| < \epsilon$. We note that $f(x)$ is an analytic function since it is the sum of analytic functions and, therefore, its Taylor series converges to $f(x)$. Thus, taking the Taylor series expansion of $f(x)$ around 0,

$$f(x) = x + \sum_{m=2n+1}^{\infty} \frac{f^{(m)}(0)}{m!} x^m.$$

We can bound $|x - f(x)|$ for $|x| < \epsilon$ using the Lagrange remainder term of the $2n$-th Taylor polynomial of $f(x)$. Thus,

$$|x - f(x)| = \left| \frac{f^{(2n+1)}(\xi)}{(2n+1)!} x^{2n+1} \right|$$

for some real number ξ between 0 and x. We have that

$$f^{(2n+1)}(x) = \pm \sum_{k=1}^{n} \beta_k k^{2n+1} \cos(kx).$$

Upper bounding $f^{(2n+1)}(\xi)$ gives

$$|x - f(x)| < \sum_{k=1}^{n} |\beta_k| k^{2n+1} \frac{|x^{2n+1}|}{(2n+1)!}.$$

By Lemma 6, $\beta_k < 2/k$, which gives

$$|x - f(x)| < |x^{2n+1}| * \frac{2}{(2n+1)!} * \sum_{k=1}^{n} k^{2n}.$$

This then gives an upper bound of $\epsilon^{2n+1} * \frac{2*n*n^{2n}}{(2n+1)!}$, and no better than $\epsilon^{2n+1} * \frac{2*n^{2n}}{(2n+1)!} \approx (\epsilon/2)^{2n+1} * e^{2n}/(\sqrt{\pi(n+1)} * n)$ However, we will now show that a more sophisticated, yet elementary, approach that improves upon this bound by approximately a factor of e^{2n}, essentially giving us an upper bound of $(\epsilon/2)^{2n+1}$.

A Better Bound via the Alternating Series Test To obtain a better error bound, we will show that the Taylor series expansion of our sine series satisfies Leibniz's alternating series test. This will enable us to bound the error of the sine series $f(x)$ from the mod function by the $(2n+1)-$th term in the Taylor series expansion (the first nonzero term after x). We can write the Taylor series expansion of $f(x)$ as $x - \sum_{m=n+1}^{\infty} (-1)^m * b_m$, where

$$b_m = \sum_{j=1}^{n} \beta_j * \frac{(jx)^{2m-1}}{(2m-1)!}. \tag{2}$$

To bound the error, we will show, for any x in the domain of approximation, that the series $\sum_{m=n+1}^{\infty} (-1)^m * b_m$ satisfies the alternating series test. The alternating series test requires that the b_m satisfy the following three conditions.

1. $\lim_{m\to\infty} b_m = 0$
2. All b_m are positive (or all b_m are negative)
3. $|b_m| \geq |b_{m+1}|$ for all natural numbers $m \geq n+1$.

Theorem 7 *Alternating Series Test [Leibniz]. If the series above satisfies the alternating series test then* $\sum_{m=n+1}^{\infty}(-1)^m * b_m$ *converges. Moreover, for all* $k \geq 0$,

$$\left| \sum_{m=n+1}^{\infty} (-1)^m * b_m - \sum_{m=n+1}^{n+1+k-1} (-1)^m * b_m \right| \leq |b_{n+1+k}|.$$

We will show the following lemma.

Lemma 8 *(***Main Lemma***) For every* $|x| < 2/\sqrt{n}$*, the above series given by* b_m *satisfies the Leibniz alternating series test.*

A Naive Proof Attempt We briefly explain why the following naive approach to proving this lemma fails. For simplicity, assume that n is odd, so that β_n is positive and β_{n-1} is negative by Lemma 6. Then, the naive approach would be to prove that

$$\beta_n * \frac{(n*x)^{2m-1}}{(2m-1)!} + \beta_{n-1} * \frac{((n-1)*x)^{2m-1}}{(2m-1)!}$$

(and similarly paired other terms) decreases as m increases, starting from $m = n+1$. Since powers of $n*x$ are larger than powers of $(n-1)*x$, this would eventually be true for some $m > n+1$. However, since $|\beta_n| < |\beta_{n-1}|$ and β_{n-1} is negative (see Lemma 6), this is not necessarily true at $m = n+1$. In fact, calculations show that this indeed fails for a few terms beyond $m = n+1$. Thus, a more advanced approach is required to prove that the Leibniz test holds starting at $m = n+1$. We will show that the test holds for $|x| < 2/\sqrt{n}$.

Preparing for the Proof We prove Lemma 8 in the next subsection, but first we show several additional lemmas which will assist us in the proof of Lemma 8.

Define $V^{(n,k)}(\mathbf{a})$ to be an $n \times n$ matrix, which is same as the Vandermonde matrix $V^{(n)}(\mathbf{a})$ except the last column is replaced by the $(n-1+k)$-th powers (instead of the $(n-1)$-th powers).

Let $h_k(\mathbf{a})$ be the *complete homogeneous symmetric polynomial* of degree k in $\mathbf{a}$ given by

$$h_k(\mathbf{a}) = \sum_{1 \leq i_1 \leq \ldots \leq i_k \leq n} a_{i_1} * \cdots * a_{i_k}.$$

The base polynomial $h_0(\mathbf{a})$ is taken to be one. Note that the polynomials $h_k(\mathbf{a})$ differ from the elementary symmetric polynomials $e_k(\mathbf{a})$, since in the latter the summation is taken over $1 \leq i_1 < \ldots < i_k \leq n$. The following lemma is a consequence of the well known *generating series* of the complete homogeneous symmetric polynomials, but we give a simple proof for completeness in Supplementary Material A.

Lemma 9 *For any $k \geq 0$, any* $\mathbf{a}$ *of length $n > 0$, and an independent formal variable t,*

$$\sum_{j=0}^{k} h_j(\mathbf{a}) t^j \;=\; \prod_{i=1}^{n} \sum_{j=0}^{k} (ta_i)^j \;\; mod \;\; t^{k+1}.$$

Lemma 10 *For $k \geq 1$, the determinant of the matrix $V^{(n,k)}(\mathbf{a})$ is*

$$\det(V^{(n)}(\mathbf{a})) \;*\; h_k(\mathbf{a})$$

Proof:

Fix any $k \geq 1$. Consider an $n \times n$ matrix M which is same as $V^{(n,k)}(\mathbf{a})$ except that the last row is powers of an indeterminate x. In other words the last row is $(x^0, x^1, ..., x^{n-2}, x^{n-1+k})$. Let $\mathbf{a}'$ stand for the $(n-1)$ length truncation of $\mathbf{a}$. Treating the elements of $\mathbf{a}'$ as scalars, the determinant of the matrix M is a polynomial in x of degree $n-1+k$. Call this polynomial $f(x)$. Since the determinant of a matrix with two equal (or even scaled by a constant) rows is zero, the polynomial $f(x)$ has roots $\mathbf{a}'$. Thus,

$$f(x) = g(x) * \prod_{i=1}^{n-1} (x - a_i), \tag{3}$$

where $g(x)$ is a polynomial (to be determined) of degree k . However, $f(x)$, the degree $n-1+k$ polynomial, has zero coefficients for all monomials x^j with j in $[n-1..n-1+k-1]$. If we introduce a new formal variable $t = 1/x$, then the above equation (3) can be written as

$$\tilde{f}(t) = \tilde{g}(t) * \prod_{i=1}^{n-1} (1 - ta_i). \tag{4}$$

where $\tilde{f}$ (resp. $\tilde{g}$) is the polynomial f (resp. g) with coefficients reversed. Note, all the zero coefficients of $f(x)$ described above imply that coefficient of monomial t^j in $\tilde{f}(t)$ is zero for every j in $[1..k]$, and the constant term in $\tilde{f}(t)$ is f_{n-1+k}, where f_{n-1+k} denotes the coefficient of x^{n-1+k} in $f(x)$. Thus, $\tilde{f}(t) = f_{n-1+k} \bmod t^{k+1}$. Considering equation (4) modulo t^{k+1}, we get

$$f_{n-1+k} \;*\; \prod_{i=1}^{n-1} (1 - ta_i)^{-1} = \tilde{g}(t) \bmod \;\; t^{k+1}. \tag{5}$$

The above equation is well-formed as inverse of $(1 - ta_i)$ modulo t^{k+1} is well-defined. Indeed, it is easy to check that $(1 - ta_i) * \sum_{j=0}^{k} (ta_i)^j$ is 1 mod t^{k+1}. Hence, we also get,

$$f_{n-1+k} \;*\; \prod_{i=1}^{n-1} \sum_{j=0}^{k} (ta_i)^j = \tilde{g}(t) \bmod \;\; t^{k+1}. \tag{6}$$

Since $g(x)$ is of degree k, $\tilde{g}(t)$ has degree at most k as well. Denote by $\tilde{g}_j$ the coefficient of t^j in $\tilde{g}_j$, which is same as g_{k-j}. Then, by comparing coefficients of t^j on both sides, by Lemma 9 we get that for each $j \in [0..k]$,

$$g_{k-j} = \tilde{g}_j = f_{n-1+k} \ * \ h_j(\mathbf{a}').$$

Thus, having determined $g(x)$, we also have $f(x)$ by (3). Letting $x = a_n$, then we get

$$\begin{aligned}
\det\ (V^{(n,k)}(\mathbf{a})) &= f(a_n) \\
&= \prod_{i=1}^{n-1}(a_n - a_i) \ * \ g(a_n) \\
&= \prod_{i=1}^{n-1}(a_n - a_i) \ * \ f_{n-1+k} \ * \ \sum_{j=0}^{k} a_n^{k-j} h_j(\mathbf{a}') \\
&= \prod_{i=1}^{n-1}(a_n - a_i) \ * \ f_{n-1+k} \ * \ h_k(\mathbf{a}) \\
&= \det(V^{(n)}(\mathbf{a})) * h_k(\mathbf{a}),
\end{aligned}$$

where the last equality follows by noting that the top coefficient of $f(x)$, i.e. f_{n-1+k} is the (n,n)-minor of $V^{(n,k)}(\mathbf{a})$, which is same as the (n,n)-minor of Vandermonde matrix $V^{(n)}(\mathbf{a})$, which, in turn, is $(-1)^{n+n} * \det\ V^{(n-1)}(\mathbf{a}')$. □

Lemma 11 *For* $\mathbf{a} = (1^2, 2^2, 3^2, \ldots, n^2)$*, for all* $k \geq 0$*,*

$$\frac{h_{k+1}(\mathbf{a})}{h_k(\mathbf{a})} \leq n^3.$$

Proof: First note that $h_{k+1}(\mathbf{a}) = \sum_{i=1}^{n} a_i * h_k(\mathbf{a}_{(i)})$, where $\mathbf{a}_{(i)}$ is $\mathbf{a}$ restricted to first i entries. Since a_i are monotonically increasing, it follows that $h_{k+1}(\mathbf{a}) \leq n * a_n * h_k(\mathbf{a})$, from which the claim follows. □

Lemma 12 *For the matrix* $S^{(n)}(\mathbf{a})$ *with* $\mathbf{a}$ *set to the sequence of integers from one to* n*, let* β_i *be given by the formula in Lemma 4. Then,*

$$\sum_{i=1}^{n} \beta_i * i^{2n+1} = (-1)^{n-1} * (n!)^2.$$

Proof: With $\mathbf{a}$ set to the sequence of integers from one to n, $\sum_{i=1}^{n} \beta_i * i^{2n+1}$ is the inner product of the first column of $\hat{S}^{(n)}(\mathbf{a})$ and $\vec{\beta}$. In the following, the i-th column of a matrix M will be denoted by M_i, and the (i,j)-th entry of M will be denoted by $M_{i,j}$. Thus, using Lemma 4, we have

$$\begin{aligned}
\sum_{i=1}^{n} \beta_i * i^{2n+1} &= \vec{\beta}^{\top} \cdot (\hat{S}^{(n)}(\mathbf{a}))_1 \\
&= \frac{1}{\det(S^{(n)}(\mathbf{a}))} * \sum_{i=1}^{n} (-1)^{i+1} d_i * (\hat{S}^{(n)}(\mathbf{a}))_{i,1} \\
&= \frac{\det(\hat{S}^{(n)}(\mathbf{a}))}{\det(S^{(n)}(\mathbf{a}))} \\
&= (-1)^{n-1} * \prod_{i=1}^{n} a_i^2 \\
&= (-1)^{n-1} * (n!)^2,
\end{aligned}$$

where we have used Lemma 5 in the second-to-last equality. □

2.1 Alternating Series Test (Proof of Main Lemma)

Having shown Lemmas 10, 11, and 12, we are now ready to prove the main lemma (Lemma 8).

Proof: (of Lemma 8) In this proof, we will fix $\mathbf{a}$ to be the sequence of integers from 1 to n. Note, each b_m can be written as $b_m = c_m * \frac{x^{2m-1}}{(2m-1)!}$, where $c_m = \sum_{j=1}^{n} \beta_j * j^{2m-1}$. We now prove the three properties required of b_m so that the series $\sum_{m=n+1}^{\infty} (-1)^m * b_m$ satisfies the alternating series test.

1. We show that b_m goes to zero, as m goes to infinity. Since n is fixed and all β_i are bounded by Lemma 6, we just need to show that for every x in the domain of approximation, for every $j \in [n]$, $\frac{(jx)^{2m-1}}{(2m-1)!}$ goes to zero as m goes to infinity. Since the domain of approximation is bounded, $|x|$ itself is bounded. Since, $k! \geq e(k/e)^k$, the above is upper bounded by $e^{-1} * (jx * e/(2m-1))^{2m-1}$, which goes to zero as m goes to infinity.

2. To show that all b_m are positive (or all are negative), it suffices to show that all c_m are positive (or all c_m are negative). As a warmup, we first focus on c_{n+1} (i.e. m set to $n+1$). By Lemma 12, this quantity is simply $(-1)^{(n-1)} * (n!)^2$ and hence is positive if n is odd, and negative when n is even.

Let $\hat{S}^{(n,k)}(\mathbf{a})$ be the matrix that is the same as $\hat{S}^{(n)}(\mathbf{a})$ except that the first column is replaced by the $(2n-1+2k)$ powers of $\mathbf{a}$. Thus, $\hat{S}^{(n,1)}(\mathbf{a})$ is same as $\hat{S}^{(n)}(\mathbf{a})$. As in the proof of Lemma 12,

$$\begin{aligned} c_{n+k} &= \sum_{i=1}^{n} \beta_i * i^{2n-1+2k} \\ &= \vec{\beta}^{\top} \cdot (\hat{S}^{(n,k)}(\mathbf{a}))_1 \\ &= \frac{1}{\det(S^{(n)}(\mathbf{a}))} * \sum_{i=1}^{n} (-1)^{i+1} d_i * (\hat{S}^{(n,k)}(\mathbf{a}))_{i,1} \\ &= \frac{\det(\hat{S}^{(n,k)}(\mathbf{a}))}{\det(S^{(n)}(\mathbf{a}))} \end{aligned}$$

To give an expression for $\det(\hat{S}^{(n,k)}(\mathbf{a}))$, we will use Lemma 10. To use this lemma, we first relate $\hat{S}^{(n,k)}(\mathbf{a})$ to $V^{n,k}(\mathbf{a})$. Recall, the first column of $\hat{S}^{(n,k)}(\mathbf{a})$ is $(2n-1+2k)$ powers of $\mathbf{a}$. Also, for other columns, the (i,j)-th entry is a_i^{2j-1} $(2 \leq j \leq n)$. Since $k \geq 1$, each entry in the i-th row has at least one power of a_i, and hence the determinant of $\hat{S}^{(n,k)}(\mathbf{a})$ is $\prod_{i=1}^{n} a_i$ times the determinant of a new matrix M, which has as its first column $(2n+2(k-1))$ powers of $\mathbf{a}$, and all other columns as $2(j-1)$-th powers of $\mathbf{a}$ $(2 \leq j \leq n)$. Let $\mathbf{a}^{(2)}$ be the sequence $\mathbf{a}$, but with each entry squared. Then this matrix M is same as the matrix $V^{n,k-1}(\mathbf{a}^{(2)})$ but with the first and last column exchanged. Thus, using Lemma 10, it follows that $\det(\hat{S}^{(n,k)}(\mathbf{a}))$ is

$$(-1)^{n-1} * h_{k-1}(\mathbf{a}^{(2)}) * \prod_{i=1}^{n} \prod_{1 \leq j < i} (a_i^2 - a_j^2) \; * \; \prod_{i=1}^{n} a_i^3,$$

From Lemma 5, we also have that the determinant of $S^{(n)}(\mathbf{a})$ is

$$\left(\prod_{i=1}^{n} a_i \right) * \prod_{i=1}^{n} \prod_{1 \leq j < i} (a_i^2 - a_j^2).$$

Recalling that a_i is just i, we thus have that for $k \geq 1$, all c_{n+k} are positive if n is odd, and all c_{n+k} are negative if n is even.

3. We now show that $|b_m| \geq |b_{m+1}|$ for all $m \geq n+1$. We have,

$$\begin{aligned}
\frac{|b_{m+1}|}{|b_m|} &= \frac{(-1)^{n-1} * h_{m+1-(n+1)}(\mathbf{a}^{(2)}) * \prod_{i=1}^{n} \prod_{1 \leq j < i} (a_i^2 - a_j^2) \ * \ \prod_{i=1}^{n} a_i^3 \ * \ \frac{x^{2m+1}}{(2m+1)!}}{(-1)^{n-1} * h_{m-(n+1)}(\mathbf{a}^{(2)}) * \prod_{i=1}^{n} \prod_{1 \leq j < i} (a_i^2 - a_j^2) \ * \ \prod_{i=1}^{n} a_i^3 \ * \ \frac{x^{2m-1}}{(2m-1)!}} \\
&= \frac{h_{m+1-(n+1)}(\mathbf{a}^{(2)}) \ * \ \frac{x^{2m+1}}{(2m+1)!}}{h_{m-(n+1)}(\mathbf{a}^{(2)}) \ * \ \frac{x^{2m-1}}{(2m-1)!}} \\
&= \frac{h_{m+1-(n+1)}(\mathbf{a}^{(2)})}{h_{m-(n+1)}(\mathbf{a}^{(2)})} \ * \ \frac{x^2}{2m(2m+1)} \\
&\leq n^3 \ * \ \frac{x^2}{2m(2m+1)} \text{ (by Lemma 11)} \\
&\leq 1 \text{ (for } |x| < 2/\sqrt{n}).
\end{aligned}$$

□

We are now ready to prove Theorem 1.

Proof: (of Theorem 1) Let β_k, for $k \in [1..n]$, be defined as in equation (1) with $\mathbf{a}$ set to the sequence of numbers from 1 to n. From the Taylor series expansion of the sine series, which converges since the sine series is analytic, it follows that

$$\sum_{k=1}^{n} \beta_k \sin(kx) = x - \sum_{m=n+1}^{\infty} (-1)^m * b_m,$$

where b_m are defined in equation (2), i.e. $b_m = \sum_{k=1}^{n} \beta_k * \frac{(kx)^{2m-1}}{(2m-1)!}$. Thus, by Lemma 8 and Leibniz's alternating series test (Theorem 7), we have for $|x| < 2/\sqrt{n}$,

$$\begin{aligned}
\left| x - \sum_{k=1}^{n} \beta_k \sin(kx) \right| &\leq |b_{n+1}| \\
&= \left| \sum_{k=1}^{n} \beta_k * \frac{(kx)^{2n+1}}{(2n+1)!} \right| \\
&= \frac{|x^{2n+1}|}{(2n+1)!} * \left| \sum_{k=1}^{n} \beta_k * k^{2n+1} \right| \\
&= \frac{(n!)^2}{(2n+1)!} * |x^{2n+1}|,
\end{aligned}$$

where we used Lemma 12 in the last equality.

Restricting $|x| < \epsilon$, Theorem 1 follows from the fact that

$$\begin{aligned}\frac{(n!)^2}{(2n+1)!}\epsilon^{2n+1} &< \frac{((n+1)/e)^{2n+2}e^2}{((2n+1)/e)^{2n+1}}\epsilon^{2n+1} \\ &= e*(n+1)*\left(\frac{n+1}{2n+1}\right)^{2n+1}*\epsilon^{2n+1} \\ &= e*(n+1)*\left(\frac{2n+2}{2n+1}\right)^{2n+1}*\left(\frac{\epsilon}{2}\right)^{2n+1} \\ &< e^2*(n+1)*\left(\frac{\epsilon}{2}\right)^{2n+1},\end{aligned}$$

where we have used the fact that

$$\left(\frac{n}{e}\right)^n < n! < \left(\frac{n+1}{e}\right)^{n+1} e$$

for all $n \geq 1$ and that $(1+1/n)^n < e$ for all $n \geq 1$. □

3 Application to Bootstrapping for Approximate HE

In Section 1, we explained that approximating the mod function on small intervals around the modulus is a necessary step in bootstrapping for approximate homomorphic encryption (CKKS). In this section, we will briefly overview the bootstrapping procedure for the CKKS-HE scheme introduced in [CHK+18a].

Notation and Necessary Preliminaries: Let M be a power of 2 and $\Phi_M(X) = X^N + 1$ be the Mth cyclotomic polynomial of degree $N = M/2$. Let $\mathcal{R} = \mathbb{Z}[X]/\Phi_M(X)$. For an integer q, let $\mathcal{R}_q = \mathbb{Z}_q[X]/\Phi_M(X)$. Using the canonical embedding σ, it is possible to map an element $m(X) \in \mathcal{R}$ into $\mathbb{C}^N$ by evaluating $m(X)$ at the Mth primitive roots of unity. Using the same canonical embedding, it is also possible to define an isometric ring isomorphism between $\mathcal{S} = \mathbb{R}[X]/\Phi_M(X)$ and $\mathbb{C}^{N/2}$, where for an element $m(X) \in \mathcal{S}$, it has the canonical embedding norm $||m||_\infty^{\mathsf{can}} = ||\sigma(m)||_\infty$.

Overview of the CKKS-HE Scheme: The CKKS-HE scheme [CKKS17] is an HE scheme for approximate arithmetic over real/complex numbers. Its security is based on the ring-LWE (RLWE) assumption. The message space of the scheme is polynomials $m(X)$ in $\mathcal{R}$ with

$||m||_\infty^{\mathsf{can}} < q/2$ for a prime q. Using the canonical embedding and appropriate scaling, one can map a vector in $\mathbb{C}^{N/2}$ of fixed precision into $\mathcal{R}$. The fact that canonical embedding induces an isometric ring isomorphism between $\mathcal{S}$ and $\mathbb{C}^{N/2}$ implies that operations on the message space $\mathcal{R}$ map to the same operations performed coordinate-wise on $\mathbb{C}^{N/2}$. Thus, the CKKS-HE scheme supports packing $N/2$ complex numbers into a single plaintext and operating on them in single instruction multiple data (SIMD) manner. Please refer to [CKKS17] for more details on this encoding procedure. We will refer to $m(X) \in \mathcal{R}$ as the plaintext/message and the corresponding vector in $\mathbb{C}^{N/2}$ as the plaintext "slots."

A ciphertext ct encrypting a message $m \in \mathcal{R}$ is an element of $\mathcal{R}_{q_\ell}^2$ for some $\ell \in \{0, \ldots, L\}$. ℓ refers to the "level" of the ciphertext. In [CKKS17], $q_\ell = p^\ell * q$ for primes p and q. However, q_ℓ can be set in other ways (such as via an RNS basis [CHK+18b]). The decryption structure is $\langle \mathsf{ct}, \mathsf{sk} \rangle \bmod q_\ell = m + e$ for some small error $e \in \mathcal{R}$. Observe that there is no way to remove e and some of the least significant bits of m are unrecoverable. A fresh ciphertext is generated at the highest level L. Homomorphic operations increase the magnitude of the error and the message and one must apply a rescaling procedure or modular reduction to bring a ciphertext to a lower level to continue homomorphic computation. Eventually, a ciphertext is at the lowest level (an element of $\mathcal{R}_q^2$), and no further operations can be performed.

Bootstrapping Procedure for CKKS-HE: [CHK+18a] introduced the first bootstrapping procedure for the CKKS-HE scheme. Subsequent works [CCS19, HHC19, HK20, BMTPH21] improved various aspects of bootstrapping, but the overall procedure remains the same. The goal is to take a ciphertext at the lowest level and bring it up to a higher level so that homomorphic computation can continue. Thus, given a ciphertext ct at the lowest level, we want to obtain another ciphertext ct' such that

$$\langle \mathsf{ct}, \mathsf{sk} \rangle \bmod q \approx \langle \mathsf{ct}', \mathsf{sk} \rangle \bmod q_\ell$$

for some $\ell > 1$. For simplicity in the following, we will include the starting decryption error in the message m. That is, we will assume that $\langle \mathsf{ct}, \mathsf{sk} \rangle \bmod q = m$.

Bootstrapping is done via the following sequence of steps:

1. **Modulus Raising:** By simply considering ct as a ciphertext at the highest level, it follows that $\langle \mathsf{ct}, \mathsf{sk} \rangle \bmod q_L = qI + m$ for some $I \in \mathcal{R}$.

2. **Coefficients to Slots:** We need to perform the modular reduction on the polynomial coefficients of $t = qI + m$. However, recall that homomorphic computations evaluate coordinate-wise on the plaintext "slots," not the polynomial coefficients. Thus, we need

to transform our ciphertext so that the polynomial coefficients are in the "slots." This can be done by evaluating a linear transformation homomorphically.

3. **Compute the Mod Function:** We need a procedure to compute/approximate the mod function homomorphically. This is a significant challenge since we can only compute arithmetic operations homomorphically.

4. **Slots to Coefficients:** Finally, we need to undo the coefficients to slots step. This can be done by homomorphically evaluating the inverse of the previous linear transform.

Observe that if we can approximate the mod function, then the above procedure will give us a ct' at some higher level ℓ that decrypts to $m + e$ for some small error e. Since we are dealing with approximate arithmetic, this error from bootstrapping can be absorbed into the other errors that occur during approximate arithmetic and homomorphic evaluation. We can upper bound $|I| < K$ for some integer K so that we only need to approximate the mod function on the interval $[-Kq - m, Kq + m]$, where we have overloaded notation to make m an upper bound on the size of the message.

4 Evaluating the Sine Series Approximation of the Mod Function

In order to use the sine series approximation of the mod function given by Corollary 3 for bootstrapping, we must approximate the sine series by a low-degree polynomial, since the CKKS-HE scheme cannot compute sine directly. In this section, using our sine series approximation of the mod function and the well-known Taylor series expansion of the sine function, we will give explicit low-degree polynomial approximations of the mod function on small intervals around multiples of the modulus to (almost) arbitrary precision. The resulting polynomials have small coefficients, as the Taylor series of the sine function has small coefficients, and the sine series itself has small coefficients by Lemma 6. Recall that small coefficients are beneficial in contrast to large coefficients, as in the latter case one is forced to compute the different power monomials to much higher precision in order to obtain an accurate polynomial evaluation. This, in turn, causes the computational precision that we must operate at during bootstrapping to be higher, which causes each "level" to consume more bits of the modulus. We next explain how we evaluate the sine series and then determine the degree and evaluation precision required for the Taylor series approximation of sine.

Evaluating the Sine Series: To evaluate the sine series, we first compute a Taylor series approximation of e^{ix} (recall that CKKS-HE allows us to compute over complex numbers). We can obtain an approximation to $\sin x$ by extracting the imaginary part. The other higher order $\sin kx$ terms can be obtained conveniently by computing e^{ikx} from e^{ix} and extracting the imaginary part. As for computing the Taylor series approximation of the sine function, note that the domain of approximation is small intervals around ℓq, where $\ell \in [-K..K]$ and q is the modulus. The bound K comes from the bound on the Hamming-weight of the secret key and is typically 12 to 32. If our input is $X = x + \ell q$ for some small offset x and $\ell \in [-K..K]$, our goal is to compute $e^{i(2\pi(x+\ell q)/q)}$. This then requires a Taylor series that has powers of $2\pi(x + \ell q)/q$, which can be more than one. Earlier works noted that one can instead first compute $e^{i(2\pi(x+\ell q)/(q2^r))}$ using a Taylor series expansion (for some $r > 0$) and then compute $e^{i(2\pi(x+\ell q)/q)}$ using r squarings.

Determining the Degree of the Taylor Series Approximation: Next, we must determine the degree to which we compute the Taylor series expansion of $e^{2\pi i(x+\ell q)/(q2^r)}$. The Taylor series expansion is

$$\sum_{m=0}^{\infty} (2\pi i(x + \ell q)/(q2^r))^m/m!.$$

We now determine for which range of values of $(x + \ell q)$ the above restricted to the sine terms, i.e. the imaginary terms or odd powers of x, satisfies the alternating series test (so that the partial series error can be bound by the absolute value of the next missing term). Thus, we need to determine the conditions under which

$$\begin{aligned} 1 &> \frac{(2\pi|(x + \ell q)|/(q2^r))^{(2m+1)}/(2m + 1)!}{(2\pi|(x + \ell q)|/(q2^r))^{(2m-1)}/(2m - 1)!} \\ &= \frac{(2\pi|(x + \ell q)|/(q2^r))^2}{(2m + 1)(2m)} \end{aligned}$$

Assuming $x << q$ and $2^r \approx K + 1$, the above holds when $m > \pi$. Thus, if the Taylor series is computed partially up to any degree $2m - 1$, then the error in the approximation of sine is at most

$$(2\pi)^{2m+1}/(2m + 1)! < (2\pi e/(2m + 1))^{2m+1},$$

which is at most $2^{-(2m+1)}$ if we require that $m > 2\pi e$.

Thus, having computed $\sin(2\pi(x + \ell q)/(q2^r))$ partially up to m terms, we now investigate the error for the higher order terms in the sine series, i.e. $\sin(2\pi k(x + \ell q)/q)$ for $k \geq 1$. If the error in the approximation of the original term is small, say $\delta << 1$, then the error for this

k-th term is approximately $k2^r * \delta$ (as it requires $r + \log k$ squarings). Thus, the total error in the sine series due to the Taylor series approximation of $\sum_{k=1}^{n} \beta_k \sin(2\pi k(x + \ell q)/q)$ is upper bounded in absolute value by $\sum_{k=1}^{n} |\beta_k| * k2^r\delta$, which is approximately $(K+1)\delta \sum_{k=1}^{n} |\beta_k| * k$, which is at most $n^2(K+1)\delta$ by Lemma 6, which, in turn, is at most $n^2(K+1)2^{-(2m+1)}$.

Finally, using Corollary 3, the total error in the mod function approximation, for an input $X = x + \ell q$ with $\ell \in [-K..K]$ and $|x| < \epsilon * q$ for any $\epsilon < 1/\pi\sqrt{n}$ is

$$(q/2\pi) * n^2(K+1)2^{-(2m+1)} + \frac{e^2 * q}{2\pi} * (n+1) * (\epsilon * \pi)^{2n+1}.$$

Thus, it makes sense to have m about $-n \log_2(\epsilon * \pi)$ (which is typically greater than $2\pi e$ for $n > 1$; if this value is less than $2\pi e$, then the above analysis must be redone for potentially a larger r).

Determining the Evaluation Precision: We must also determine the precision to which to evaluate the polynomials. Setting $Y = 2\pi(x + \ell q)/(q2^r)$, we observe that the degree m Taylor expansion of $e^{2\pi i(x+\ell q)/(q2^r)}$ is simply the polynomial

$$\sum_{j=0}^{m} (iY)^j/j!.$$

Recall that we have chosen r so that $|Y| < 1$. Moreover, setting $c_j = i^j/j!$, the polynomial becomes $\sum_{j=0}^{m} c_j Y^j$, where $|c_j| \leq 1$. We need to determine the precision to which we evaluate the powers Y^j (we will first evaluate the Y^{2^j}'s by repeated squaring and then use these powers to evaluate all intermediate powers). Let Y^j denote the exact values and let $\tilde{Y}^j$ denote the approximated values (to some precision to be determined). Suppose we evaluate the powers Y^j up to w bits (and simply chop off the additional bits). Then, $|\tilde{Y} - Y| < 2^{-w}$. Computing $\tilde{Y}^2$ by squaring $\tilde{Y}$ and rounding, we have that $\tilde{Y}^2$ differs from Y^2 by at most $\approx 2 * 2^{-w}$. To see this, note that $\tilde{Y} = Y \pm \delta$, where $\delta < 2^{-w}$. Then, $\tilde{Y}^2 = Y^2 \pm 2Y\delta + \delta^2 < Y^2 \pm 2\delta + \delta^2 \approx Y^2 \pm 2 * 2^{-w}$. By an analogous argument, it follows that $\tilde{Y}^j$ differs from Y^j by at most approximately $j * 2^{-w}$. Thus, the error of $\sum_{j=0}^{m} c_j \tilde{Y}^j$ is bounded by

$$\sum_{j=0}^{m} j * 2^{-w} * \frac{1}{j!} = \sum_{j=1}^{m} \frac{2^{-w}}{(j-1)!} < e * 2^{-w}.$$

Thus, to obtain error 2^{-d}, it suffices to compute the powers $\tilde{Y}^j$ to precision w for $w > d + \log_2 e$, only slightly higher than the minimum precision d required to obtain this approximation.

In the above, we saw that having small coefficients c_j (and coefficients that decrease in magnitude as j increases) enabled the approximation of the polynomial $\sum_{j=0}^{m} c_j Y^j$ by evaluating the powers of Y to precision only a couple bits larger than the minimum precision required for the desired error. This is crucial during bootstrapping as a higher evaluation precision directly corresponds to losing more bits of the modulus during the polynomial evaluation. In contrast, suppose that the c_j's were large and bounded in magnitude $|c_j| < 2^k$ for some k. Then, if the powers of Y are evaluated to precision w, the error of the polynomial evaluation is bounded by

$$\sum_{j=0}^{m} j * 2^{-w} * 2^k < \frac{m(m+1)}{2} * 2^{k-w}.$$

Thus, to obtain error 2^{-d}, the powers of Y would need to be evaluated to precision $w > d + k + 2\log m - 1$. Note the additional dependence on both k and the number of terms m.

5 Implementation

To demonstrate the applicability of our polynomial approximation to high precision bootstrapping for approximate homomorphic encryption, we updated the bootstrapping procedure of the HEAAN library [HEA] to utilize our sine series during the "Compute the Mod Function" step (see Section 3). Additionally, we updated HEAAN to use the quadmath library, since we wanted to achieve bootstrapping error smaller than the precision of a double. We ran our implementation using a PC with an AMD Ryzen 5 3600 3.6 GHz 6-Core CPU.

Table 1 gives our bootstrapping results for sine series of various orders. As before, ϵ represents the ratio p/q, where p is an upper bound on the size of the message (including any errors associated from the approximate arithmetic and prior homomorphic operations) and q is the size of the modulus prior to bootstrapping. In Table 1, ϵ is set to 2^{-10}. The key-sparsity is set to $h = 256$, so that on average K is about $\sqrt{h} = 16$. However, our implementation can handle K as large as 31. q_L denotes the modulus of the largest level, which is the modulus of a fresh ciphertext prior to any homomorphic operations. N denotes the ring dimension, which we increase as q_L increases to maintain 128-bit security [CP19, Alb17, APS15]. Results in this table were obtained using 8 slots, and the dependence on a larger number of slots is reported below. $q_{\ell'}$ denotes the modulus of the ciphertext after bootstrapping. The reported error is the decryption error after performing bootstrapping. In other words, if the decryption before bootstrapping would have resulted in message slot value M, then the decryption after bootstrapping would result in a message slot value M' such that $|M' - M| \leq \beta_{\mathsf{bs}}|M|$. As can be seen from Table 1, for $\log_2 p = 80$ and $\log_2 p = 100$, the bootstrapping error is essentially zero. This is because the bootstrapping procedure is performed at a precision that is ten bits

Table 1: High-Precision Bootstrapping Results for $\epsilon = 2^{-10}$. The secret-key sparsity is set to $h = 256$. The errors reported are for K up to 31.

Input Precision† $\log_2 p$	Sine Series Order	Modulus (Fresh) $\log_2 q_L$	Ring Dim. N	Boot. prec.	Modulus (After) $\log_2 q_{\ell'}$	Error (Boot.) $\beta_{\mathsf{bs}} = \mathrm{err}/p$	Runtime†† (secs)
30	2	1200	2^{16}	55	344	2^{-25}	22
50	3	1600	2^{16}	75	531	2^{-45}	32
60	4	2400	2^{17}	85	1008	2^{-54}	119
80	5	2400	2^{17}	105	583	$< 2^{-80}$	129
100	6	3000	2^{17}	125	843	$< 2^{-100}$	167

† The modulus q_ℓ of the ciphertext prior to bootstrapping is p/ϵ. The number of bits of q_ℓ is $p - \log \epsilon = p + 10$, and bootstrapping (computational) precision is set to $(p - \log \epsilon + \log_2 K) + 10$.

†† Includes runtime of "Coefficients to Slots" and "Slots to Coefficients" steps. Number of slots fixed to be 8 so that the "Compute the Mod Function" step dominates runtime. Results reported are from an AMD Ryzen 5 3600 3.6 GHz 6-Core CPU using quadmath, NTL and GMP software libraries.

more than the number of bits required to represent $M + Kq$ (i.e. the value which needs to be reduced mod q).

Recall that the sine series approach begins by approximating e^{ix} using a Taylor series approximation, since CKKS-HE allows computation on complex numbers. In this particular implementation, we approximated $e^{ix/K}$ to degree 63 using the Paterson-Stockmeyer polynomial evaluation optimization [PS73] and then performed $\log K$ squarings to obtain an approximation of e^{ix}. Below, we report results for other variants for approximating e^{ix}.

We see that our methodology is capable of achieving high precision bootstrapping, with the resulting message precision as large as 100 bits. Prior to our work, the highest precision bootstrapping of CKKS was the recent work of [JM20] which could achieve a resulting message precision of up to 67 bits. However, that result was only for $K = 12$ and key sparsity $h = 64$, whereas our 100 bit precision bootstrapping is for $h = 256$ and can handle K up to 31. Observe that using a sparser key (in addition to weakening security) reduces the number of intervals required for approximation, making the approximation easier. Thus, we view our result as a substantial improvement for bootstrapping in settings where high precision is required, such as the inference step of a convolution neural network or even the learning stage of the neural network. As mentioned earlier, since CKKS is for approximate arithmetic, it is only possible to have unlimited computation for stable computations that do not lose precision. However, even such stable computations lose precision in early stages prior to convergence. Thus, it is

Table 2: Timing and Error Dependence on Number of Slots. In this table $\epsilon = 2^{-10}$, $\log_2 p = 80$, and the sine series order is fixed to $n = 5$.

Num Slots	Input Precision $\log_2 p$	Sine Series Order	Modulus (Fresh) $\log_2 q_L$	Ring Dim. N	Boot. prec.	Modulus (After) $\log_2 q_{\ell'}$	Error (Boot.) $\beta_{\mathsf{bs}} = \mathrm{err}/p$	Runtime[††] (secs)
8	80	5	2400	2^{17}	105	583	$< 2^{-80}$	129
16	80	5	2400	2^{17}	105	583	$< 2^{-80}$	151
32	80	5	2400	2^{17}	105	583	2^{-72}	178
64	80	5	2400	2^{17}	105	583	2^{-71}	208
128	80	5	2400	2^{17}	105	583	2^{-69}	269

[††] Includes runtime of "Coefficients to Slots" and "Slots to Coefficients" steps. For all rows, the mod function evaluation time is almost the same at 82 secs.

important to begin such computations with high precision and, later, one can switch to smaller precision during the stable regime.

5.1 Time and Error Dependence on the Number of Slots

As the number of slots is increased, the time of the mod function evaluation step during bootstrapping remains the same (assuming we use at most $N/4$ slots, so that all the polynomial coefficients can be packed into a single ciphertext during the "Coefficients To Slots" step). However, the linear transforms that send the coefficients to slots and vice versa take a substantial hit since their runtime scales with the number of slots. Since the linear transforms also involve more rotations, key-switchings, multiplications by constants, and additions, for every doubling of the number of slots, the bootstrapping error also increases proportionately. However, since our error is so low, the error for a high number of slots still remains low enough to be termed high-precision. This dependence of runtime and bootstrapping error is reported in Table 2 for one particular parameter, where the sine series is of order five. Observe that for 8 and 16 slots, our bootstrapping method gives essentially no error. However, for a larger number of slots, the error is about 2^{-69}. This is because once the number of slots becomes larger, the error is dominated by the error introduced during the linear transform steps.

5.2 Comparison with Basic Sine and Other Variants

While the implementation results reported in Table 1 used a Taylor series approximation of degree 63 of $e^{ix/K}$, the implementation in [HEA] instead used a degree 7 approximation

Table 3: Comparison with [LLL+20]. Note, [LLL+20] cites results for $K = 25$, whereas our results are for K up to 31.

[LLL+20]			This Work		
Key Sparsity (h)	Ciphertext Bits Lost	Bootstrapping Precision (bits)	Key Sparsity (h)	Ciphertext Bits Lost	Bootstrapping Precision (bits)
192	1080	40.5	256	1069	44
N/A	N/A	N/A	256	1392	53
N/A	N/A	N/A	256	1817	80
N/A	N/A	N/A	256	2157	100

of $e^{ix/K*2^4}$ followed by 4 additional squarings. We investigated if we could use a similar approach for the sine series, as the different order sine terms are obtained by squarings of e^{ix} anyways. We found that for small precision, i.e. $\log_2 p \leq 40$, this approach can lead to a faster implementation while yielding effectively the same error. However, for $\log_2 p \geq 50$, this approach led to substantially worse error. For example, at $\log_2 p = 50$, the error increased from 2^{-45} to 2^{-30}. But, as mentioned, for smaller $\log_2 p$ we get the following improvements. First of all, the basic sine approach (i.e. $n = 1$) with $r = 4$ and degree 7 Taylor series yields an error of 2^{-19} for $\log_2 p = 30$. If the fresh modulus used is 1600 bits, then the modulus after bootstrapping has 795 bits. The time taken is 10.5 secs. Interestingly, with sine series of order two, i.e. $n = 2$, using the same approach we get an error of 2^{-26}, with modulus after bootstrapping having 685 bits. Moreover, the time taken is 10.7 secs. Yet another implementation, with a degree 31 Taylor series approximation, and $r = 0$, also yields error 2^{-25}, but takes time 16.5 secs. However, the modulus after bootstrapping has more bits at 744 bits. Regardless, it seems that the sine series of order two with a degree 7 Taylor series and $r = 4$ seems to be beneficial at low precision.

We also experimented with different values of ϵ, in particular ϵ set to 2^{-5}, 2^{-10}, 2^{-15}, 2^{-20}. The errors at each input precision were not much different, and, in fact, $\epsilon = 2^{-10}$ seems to be the best option.

5.3 Comparison with Other Prior Works

The work [CCS19] followed an interesting approach of obtaining Chebyshev interpolants of the scaled sine function. In particular, using the Taylor series of $\sin(2\pi K \cos x)$, they obtained approximations of $\sin(2\pi K x)$ in terms of Chebyshev polynomials. Furthermore, this approach also leads to an almost optimal minmax polynomial approximation, as well as yielding small coefficients. Since the scaling K is already incorporated in the function, it removes the $\log K$

Table 4: Comparison with Modular Lagrange Interpolation [JM20]. Note, [JM20] cites results for $K = 12$, whereas our results are for K up to 31.

	[JM20]			This Work		
Input Precision	Key Sparsity (h)	Ciphertext Bits Lost	Error (Boot.)	Key Sparsity (h)	Ciphertext Bits Lost	Error (Boot.)
30	64	935	2^{-24}	256	856	2^{-25}
50	64	1725	2^{-46}	256	1069	2^{-45}
60	64	1800	2^{-54}	256	1392	2^{-54}
80	64	2150	2^{-63}	256	1817	$< 2^{-80}$
100	N/A	N/A	N/A	256	2157	$< 2^{-100}$

squarings required in [CHK+18a] and in this work. However, Chebyshev interpolants do not readily submit to the Paterson-Stockmeyer evaluation optimization and while [CCS19] did show a variant of this method, it leads to coefficients increasing in size. Thus, as explained in Section 3, this then requires a larger computational precision that leads to loss of many more (ciphertext modulus) bits per multiplication depth in the bootstrapping circuit. For a direct comparison of our approach to [CCS19], we take data from Tables 2-4 from that work, as their implementation is unfortunately not public, and note that the best approximation they obtain has error 2^{-21} for data set IV*. A look at our Table 1 shows that the worst error we obtain is 2^{-25} for $\log_2 p = 30$. The number of ciphertext (modulus) bits lost for that error is $1200 - 344 = 856$, whereas [CCS19] loses $1240 - 43 * 6 = 982$ bits. Moreover, our implementation can handle K up to 31 since we set the key sparsity $h = 256$, whereas [CCS19] gives results for $K = 12$ and use key sparsity $h = 64$. Thus, our approach is clearly better at even this low precision.

In [HK20], the authors obtain better approximation error than [CCS19] by leveraging the fact the approximation is only needed in small intervals around multiples of the modulus. However, their approach also uses a baby-step giant-step, or alternately the Paterson-Stockmeyer variant applied to Chebyshev polynomials that can lead to a blowup in the size of coefficients. The authors do not give details on the number of ciphertext (modulus) bits lost in the bootstrapping procedure, nor is their implementation public. The maximum bootstrapping precision they achieve is 18.5 bits.

In [LLL+20], the authors report high-precision bootstrapping using a composition of sine/cosine and arcsine. The polynomials to approximate these functions are found via algorithmic search using the Remez algorithm (which gives no guarantee on the size of the coefficients), and the authors do not provide any details on the size of these coefficients apart from noting that they

"are small enough not to distort the messages." Moreover, their implementation is not public. The authors report a practical implementation of up to 40-bits precision bootstrapping. In Table 3, we compare our results with theirs using the relevant available information in their paper. We note that [LLL+20] gives an implementation of RNS-CKKS [CHK+18b], which improves performance over the original CKKS implementation by utilizing an RNS basis. This introduces an additional challenge of having to ensure that rescaling errors are small, but this can be done without significantly increasing error, and, in fact, the recent work [KPP20] shows a method of managing the scaling factor so that homomorphic multiplication error in RNS-CKKS is about the same as that of the original CKKS scheme.

The work [JM20] gives a direct approximation of the mod function, i.e. without going through the sine function, and hence bypasses the fundamental error of the sine function approach. Thus, they can get arbitrarily high precision, and they also show that the coefficients of their polynomial approximation are not too large. Nevertheless, the coefficients are large enough that our approach beats [JM20]. Moreover, they only give implementation numbers for $K = 12$, and for $K = 31$, the number of ciphertext modulus bits lost during bootstrapping would be higher. In Table 4, we compare their results with ours for $\epsilon = 2^{-10}$ and various plaintext precisions.

The recent work [BMTPH21] optimized the performance of bootstrapping for RNS-CKKS. They introduce a scale-invariant polynomial evaluation method as well as a "double hoisting" technique for evaluating the homomorphic linear transforms. These techniques improve the performance of bootstrapping considerably and are compatible with our sine series approximation of the mod function. Moreover, to the best of our knowledge, [BMTPH21] gives the first public implementation of full RNS-CKKS with bootstrapping. We note that they do not focus on obtaining better approximations to the mod function and utilize previous techniques and variants thereof to perform the "Compute the Mod Function" step in bootstrapping. Their maximum bootstrapping precision achieved is 32.6 bits, but we stress that this was not the focus of their work. An interesting direction would be to combine both their bootstrapping optimizations with our sine series approximation of the mod function.

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A Proof of Lemma 9

Lemma 9 (restated) For any $k \geq 0$, any $\mathbf{a}$ of length $n > 0$, and an independent formal variable t,

$$\sum_{j=0}^{k} h_j(\mathbf{a}) t^j \;=\; \prod_{i=1}^{n} \sum_{j=0}^{k} (t a_i)^j \bmod\; t^{k+1}.$$

Proof: We prove this lemma by induction over n. The base case for $n = 1$ follows as $h_j(a) = a^j$ for every j in $[0..k]$. Suppose the lemma holds for $n - 1$. Then, let $\mathbf{a}'$ be truncation of $\mathbf{a}$ to its

first $n-1$ components. We have, modulo t^{k+1},

$$\begin{aligned}
\prod_{i=1}^{n}\sum_{j=0}^{k}(ta_i)^j &= \sum_{z=0}^{k}(ta_n)^z \ * \ \prod_{i=1}^{n-1}\sum_{j=0}^{k}(ta_i)^j \\
&= \sum_{z=0}^{k} t^z a_n^z \ * \ \sum_{j=0}^{k} h_j(\mathbf{a}')t^j \\
&= \sum_{j=0}^{k}\sum_{z=0}^{k} a_n^z * h_j(\mathbf{a}')t^{j+z} \\
&= \sum_{z=0}^{k}\sum_{j=0}^{k} a_n^z * h_j(\mathbf{a}')t^{j+z} \\
&= \sum_{z=0}^{k}\sum_{j=0}^{k-z} a_n^z * h_j(\mathbf{a}')t^{j+z} \\
&= \sum_{z=0}^{k}\sum_{j'=z}^{k} a_n^z * h_{j'-z}(\mathbf{a}')t^{j'} \\
&= \sum_{z=0}^{k}\sum_{k\geq j';\, j'\geq z} a_n^z * h_{j'-z}(\mathbf{a}')t^{j'} \\
&= \sum_{z\leq k;\, j'\leq k;\, z\geq 0;\, z\leq j'} a_n^z * h_{j'-z}(\mathbf{a}')t^{j'} \\
&= \sum_{j'=0}^{k}\sum_{z=0}^{j'} a_n^z * h_{j'-z}(\mathbf{a}')t^{j'} \\
&= \sum_{j'=0}^{k} h_{j'}(\mathbf{a})t^{j'}
\end{aligned}$$

□