# The Simplest SAT Model of Combining Matsui's Bounding Conditions with Sequential Encoding Method 

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#### Abstract

As the first generic method for finding the optimal differential and linear characteristics, Matsui's branch and bound search algorithm has played an important role in evaluating the security of symmetric ciphers. By combining the Matsui's bounding conditions with automatic search models, the search efficiency can be improved. All the previous methods realize the bounding conditions by adding a set of constraints. This may increase the searching complexity of models. In this paper, by using Information Theory to quantify the effect of bounding conditions, we give the general form of bounding conditions that can use all the information provided by Matsui's bounding conditions. Then, a new method of combining bounding conditions with sequential encoding method is proposed. Different from all the previous methods, our new method can realize the bounding conditions by removing the variables and clauses from Satisfiability Problem (SAT) models based on the original sequential encoding method. With the help of some small size Mixed Integer Linear Programming (MILP) models, we build the simplest SAT model of combining Matsui's bounding conditions with sequential encoding method. Then, we apply our new method to search the optimal differential and linear characteristics of some SPN, Feistel, and ARX block ciphers. The number of variables, clauses and the solving time of the SAT models are decreased significantly. And we find some new differential and linear characteristics covering more rounds. For example, the optimal differential probability of the full rounds GIFT128 is obtained for the first time.


Keywords: Automatic search • SAT model • Matsui's bounding condition • Differential cryptanalysis • Linear cryptanalysis

## 1 Introduction

Differential [BS90] and linear [Mat93] cryptanalysis are two powerful methods which have been widely used in the security analysis of many symmetric ciphers. The core idea of these methods is to identify the differential or linear trails with high probability or correlation. However, searching the optimal differential
or linear trails is not an easy work. At EUROCRYPT 1994, Matsui [Mat94] proposed a branch and bound search algorithm which can be used to identify the optimal differentials with the maximum probability. Matsui's algorithm is one of the most powerful and efficient search tools. However, implementing it needs sophisticated programming skills when taking the cipher-specific optimizations into consideration. In order to meet the demands of security analysis of ciphers, many automatic search methods have been proposed and widely used in the search of numerous distinguishers.

Mixed Integer Linear Programming (MILP) is a kind of optimization or feasibility program whose objective function and constraints are linear, and the variables are restricted to be integers. MILP problem can be solved automatically with MILP solvers such as Gurobi [GRB]. In [WW11,MWGP11], the first automatic search method based on MILP was proposed to evaluate the security of word-oriented block ciphers against differential and linear cryptanalysis. Later, Sun et al. [SHS $\left.{ }^{+} 13, \mathrm{SHW}^{+} 14\right]$ proposed methods for generating inequalities to describe the bit-wise differential or linear characteristics of S-box. Therefore, their models can be used to obtain the minimum number of active S-box and search the best differential and linear characteristics of bit-oriented block ciphers. However, the above methods only work on small size S-box (e.g. 4-bit). At FSE 2017, Abdelkhalek et al. $\left[\mathrm{AST}^{+} 17\right]$ put forward the first MILP model for large S-box (e.g. 8-bit). Then, some efficient methods were proposed to generate inequalities of large S-box (e.g. [BC20,Udo21]). For ARX ciphers, Fu el al. $\left[F W \mathrm{~F}^{+} 16\right]$ built the MILP models for the differential and linear characteristics of modular addition and applied them to search the best differential and linear characteristics for SPECK. Moreover, as a powerful automatic search tool, MILP has been also widely used in other attacks, such as integral attacks [XZBL16, WHG ${ }^{+}$19], cube attacks [TIHM17], impossible differential attacks [ST17b], and zero-correlation linear attacks $\left[\mathrm{CJF}^{+} 16\right]$.

The Boolean Satisfiability Problem (SAT) is a problem which considers the satisfiability of a given boolean formula. And there are also many SAT solvers, such as CaDiCal [Bie19]. The first automatic search method based on SAT is introduced by Mouha and Preneel [MP13]. Then, at CRYPTO 2015, Kölbl et al. [KLT15] used the SAT/SMT solver to find the optimal differential and linear characteristics for SIMON. And at ACNS 2016, Liu et al. [LWR16] extended the SAT based automatic search algorithm to search the linear characteristics for ARX ciphers. At FSE 2018, Sun et al. [SWW18] built the SAT-based models for differential characteristics and got more accurate differential probability for LED64 and Midori64. Moreover, SAT can be used in searching impossible differential trails [LLL $\left.{ }^{+} 21\right]$ and integral distinguishers [SWW17].

Unlike Matsui's algorithm, the automatic search tools enable cryptanalysts to complete the search of distinguishers without sophisticated programming skills. It brings great convenience to the security evaluation of ciphers. However, when the number of variables or constrains in the model is large, the solver may not return the result within a reasonable time. Therefore, it is of great importance
to improve the efficiency of automatic search method. And a lots of work have been done on this issue. We divide them into three main categories.

Reducing the Variables and Constraints in the Model. Although Sasaki and Todo [ST17a] pointed out that the number of inequalities can not strictly determinant the efficiency of solving model, it still has an important impact on the solving time. And a lot of methods have been proposed to reduce the variables and constraints modeling S-box or linear layers [AST $\left.{ }^{+} 17, \mathrm{BC} 20, \mathrm{Udo} 21\right]$.

Divide and Conquer Approach. In order to obtain the result of a large model in reasonable time, we can divide it into appropriate parts. In [ $\mathrm{SHW}^{+} 14$ ], Sun et al. split r-rounds cipher into the two parts (the first $r_{0}$ and the last $\left(r-r_{0}\right)$ rounds). Then, they combined them after solving the models of the two parts respectively. At FSE 2019, Zhou et al. [ZZDX19] proposed a divide-and-conquer approach which divide the whole searching space according to the number of active $S$-boxes at a certain round.

Combining Matsui's Bounding Conditions into the Model. Matsui's bounding conditions may reduce the feasible region of the original model. The first method of combining Matsui's branch and bound search algorithm with the MILP based search model is proposed by Zhang et al. [ZSCH18]. Later, Sun et al. [SWW21] put forward a new encoding method to convert the Matsui's bounding conditions into boolean formulas of SAT model. Both methods are realized by adding the constraints derived from the Matsui's bounding conditions into the original model.

From the perspective of implementation effect, the SAT model combining Matsui's bounding conditions proposed by Sun et al. [SWW21] is the best choice at present. This method can obtain the complete bounds (full rounds) on the number of active S-boxes, the differential probabilities and linear correlations for many block ciphers for the first time. The efficiency of automatic search has been greatly improved. Just like the MILP models of combining Matsui's bounding conditions, according to the experiment results in [SWW21], adding more Matsui's bounding conditions may not necessarily improve the efficiency. This may because that all the previous methods realize the bounding conditions by adding a set of constraints. And some added constrains increase the searching complexity of models. Regrettably, there is no relevant theory for us to identify the constrains which have negative effects. By doing a considerable amount of experiments, Sun et al. put forward a strategy on how to organise the sets of bounding conditions that potentially achieve better performance. Because this strategy is experimental and lack sufficient theoretical guidance, we cannot really know its performance until completing its application. Therefore, it is meaningful to research the better way of combining Matsui's bounding conditions with the automatic search models and improve the search efficiency.

### 1.1 Our Contributions

In this paper, we study the properties of Matsui's bounding conditions and the new way of combining Matsui's bounding conditions into the SAT model. The contributions of this paper are classified into the following three parts.

The Properties of Matsui's Bounding Conditions. Although we know that the effect of Matsui's bounding conditions is to reduce the feasible region, no one has been able to describe it accurately. By separating Matsui's bounding conditions from specific ciphers, we use Information Theory to quantify the effect of bounding conditions. Thus, when converting the bounding conditions into other formula, we can evaluate the quality of the transformation. In this way, we give the general form of inequality constraints that can utilize all the information provided by Matsui's bounding conditions.

The Simplest SAT Model of Combining Matsui's Bounding Conditions with Sequential Encoding Method. Different from all the previous methods, we propose a new method which can realize the Matsui's bounding conditions by removing variables and constrains from the SAT model based on sequential encoding method. This will decrease the solving complexity of models. Then, with the help of some small size MILP models, we get the simplest SAT model of combining Matsui's bounding conditions with sequential encoding method which has the least variables and clauses.

Searching the Optimal Differential and Linear Characteristics of Block Ciphers. We apply the simplest SAT model to search the optimal differential and linear characteristics of SPN, Feistel and ARX block ciphers. Compared with the previous method, the number of variables, clauses and the solving time of the SAT models are decreased significantly which can be seen in Table 2. For block ciphers PRESENT, RECTANGLE, GIFT64, LBlock, TWINE, SPECK32, SPECK64, the optimal differential and linear characteristics of the full rounds are obtained which are consistent with the results in [SWW21]. For SPECK48, SPECK96, SPECK128 and GIFT128, we find some new differential and linear characteristics covering more rounds. For example, the optimal differential probability of the full rounds GIFT128 is obtained for the first time. And a comparison of the maximum length of optimal differential and linear trails with previous results are provided in Table 1. For all the above ciphers, our results reach the maximum length of optimal differential and linear trails at present.

Table 1. The comparison of the maximum length of optimal trails

| Trail | GIFT128 | SPECK48 | SPECK96 | SPECK128 | Ref. |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | 29 | 18 | 10 | 9 | $[$ SWW21] |
|  | $\mathbf{4 0}$ (Full) | $\mathbf{1 9}$ | 10 | 9 | Sect. 5 |
| Linear | 25 | 23 | 14 | 10 | $[$ SWW21] |
|  | $\mathbf{2 7}$ | 23 | $\mathbf{1 5}$ | $\mathbf{1 1}$ | Sect. 5 |

### 1.2 Outline

This paper is organized as follows: Sect. 2 provides the background of automatic search method based on SAT. In Sect. 3, the properties of Matsui's bounding
conditions are studied. In Sect. 4, we propose the simplest SAT model of combining bounding conditions with sequential encoding method. Sect. 5 uses the new method to search the optimal differential and linear characteristics of block ciphers. Sect. 6 concludes the paper. And some auxiliary materials are supplied in Appendix.

## 2 Automatic Search Method Based on SAT

### 2.1 Boolean Satisfiability Problem

For a formula, if it only consists of boolean variables, operators AND ( $\wedge$ ), OR ( V ), NOT $\left({ }^{-}\right)$and parentheses, we call it boolean formula. And SAT is the boolean satisfiability problem which considers whether there is a valid assignment to boolean variables such that the formula equals one. If such an assignment exists, the SAT problem is said satisfiable. It was shown that the problem is NPcomplete [Coo71]. However, many problem with millions of variables can be solved by modern SAT solvers, such as [Bie19].

For any boolean formula, we can convert it into Conjunctive Normal Form (CNF) denoted as $\bigwedge_{i=0}^{m}\left(\bigvee_{j=0}^{n_{i}} c_{i, j}\right)$, where $c_{i, j}$ is a boolean variable or constant or the NOT of a boolean variable. And each disjunction $\bigvee_{j=0}^{n_{i}} c_{i, j}$ is called a clause. Because CNF is a standard input format of SAT solvers. When using SAT to solve a problem, we have to translate it into a model consisted of boolean variables and clauses.

### 2.2 SAT Models for Some Basic Operations

When we use SAT to search differential or linear characteristics, we should translate the search problem into a series of clauses. And the clauses should describe the propagation properties of differential or linear characteristics through the cipher. Here, we will briefly introduce the SAT models for some basic operations which will be used in this paper. For more information, please refer to [SWW21,LWR16]. And in the following, we use $x_{0}$ to denote the most significant bit of the $n$-bit vector $x=\left(x_{0}, x_{1}, \ldots, x_{n-1}\right) \in \mathbb{F}_{2}^{n}$.

Differential Model 1 (Branching) [SWW21]. Let $y=f(x)$ be a branching function, where $x \in \mathbb{F}_{2}$ is the input variable, and the output variables $y=$ $\left(y_{0}, y_{1}, \ldots, y_{n-1}\right) \in \mathbb{F}_{2}^{n}$ is calculated as $y_{0}=y_{1}=\cdots=y_{n-1}=x$. Then, $\left(\alpha, \beta_{0}, \beta_{1}, \ldots, \beta_{n-1}\right)$ is a valid differential trail of $f$ if and only if it satisfies all the equations in the following:

$$
\left.\begin{array}{l}
\alpha \vee \overline{\beta_{i}}=1 \\
\bar{\alpha} \vee \beta_{i}=1
\end{array}\right\}, 0 \leq i \leq n-1 .
$$

Differential Model 2 (Xor) [SWW21]. Let $y=f(x)$ be a function compressed by an Xor, where $x=\left(x_{0}, x_{1}, \ldots, x_{n-1}\right) \in \mathbb{F}_{2}^{n}$ is the input variables, and the output variable $y \in \mathbb{F}_{2}$ is calculated as $y=x_{0} \oplus x_{1} \oplus \cdots \oplus x_{n-1}$.

When $n=2$, $\left(\alpha_{0}, \alpha_{1}, \beta\right)$ is a valid differential trail of $f$ if and only if it satisfies all the equations in the following:

$$
\left.\begin{array}{l}
\alpha_{0} \vee \alpha_{1} \vee \bar{\beta}=1 \\
\alpha_{0} \vee \overline{\alpha_{1}} \vee \beta=1 \\
\overline{\alpha_{0}} \vee \alpha_{1} \vee \beta=1 \\
\overline{\alpha_{0}} \vee \overline{\alpha_{1}} \vee \bar{\beta}=1
\end{array}\right\} .
$$

When $n \geq 3$, there are two main methods to model the Xor function. The first method decomposes the $n$-input Xor operation into ( $n-1$ ) 2-input Xor operations by introducing auxiliary boolean variables $u_{0}, u_{1}, \ldots, u_{n-3}$. Then $y=f(x)$ can be represented as the following 2-input Xor operations:

$$
\left\{\begin{array}{l}
x_{0} \oplus x_{1}=u_{0} \\
x_{i} \oplus u_{i-2}=u_{i-1}, 2 \leq i \leq n-2 \\
x_{n-1} \oplus u_{n-3}=y
\end{array}\right.
$$

After applying 2-input Xor model to the $(n-1) 2$-input Xor operations one by one, the model of $n$-input Xor operation can be expressed with $4 \times(n-1)$ clauses.

The second method does not introduce auxiliary boolean variables. Let $A$ be the set $\left\{\left(a_{0}, a_{1}, \ldots, a_{n}\right) \in \mathbb{F}_{2}^{n+1} \mid a_{0} \oplus a_{1} \oplus \ldots \oplus a_{n}=1\right\}$. Then, the differential trail $\left(\alpha_{0}, \alpha_{1}, \ldots, \alpha_{n-1}, \beta\right)$ is valid if and only if it satisfies all the following equations.
$\left(\alpha_{0} \oplus a_{0}\right) \vee\left(\alpha_{1} \oplus a_{1}\right) \vee \cdots \vee\left(\alpha_{n-1} \oplus a_{n-1}\right) \vee\left(\beta \oplus a_{n}\right)=1,\left(a_{0}, a_{1}, \ldots, a_{n}\right) \in A$.
According to $\left[\mathrm{SLR}^{+} 15\right]$, the linear masks propagation model for branching (resp. Xor) operation is the same as the differences propagation model for Xor (resp. branching) operation. Thus, we do not introduce the SAT models for linear mask propagation through branching and Xor operation.

Differential Model 3 (Modular Addition) [SWW21,LWR16]. Let $z=$ $f(x, y)$ be a n-bit modular addition operation. Then, $(\alpha, \beta, \gamma) \in \mathbb{F}_{2}^{3 \times n}$ is a valid differential trail if and only if it satisfies all the following equations:

$$
\begin{aligned}
& \alpha_{n-1} \oplus \beta_{n-1} \oplus \gamma_{n-1}=0 ; \\
& \alpha_{i} \vee \beta_{i} \vee \overline{\gamma_{i}} \vee \alpha_{i+1} \vee \beta_{i+1} \vee \gamma_{i+1}=1 \\
& \alpha_{i} \vee \overline{\beta_{i}} \vee \gamma_{i} \vee \alpha_{i+1} \vee \beta_{i+1} \vee \gamma_{i+1}=1 \\
& \overline{\alpha_{i}} \vee \beta_{i} \vee \gamma_{i} \vee \alpha_{i+1} \vee \beta_{i+1} \vee \gamma_{i+1}=1 \\
& \overline{\alpha_{i}} \vee \overline{\beta_{i}} \vee \overline{\gamma_{i}} \vee x_{i+1} \vee \overline{\beta_{i+1}} \vee \gamma_{i+1}=1 \quad 1 . \\
& \alpha_{i} \vee \underline{\beta_{i}} \vee \gamma_{i} \vee \overline{\alpha_{i+1}} \vee \overline{\beta_{i+1}} \vee \overline{\gamma_{i+1}}=1 \\
& \alpha_{i} \vee \overline{\beta_{i}} \vee \overline{\gamma_{i}} \vee \overline{\alpha_{i+1}} \vee \overline{\beta_{i+1}} \vee \overline{\gamma_{i+1}}=1 \\
& \overline{\alpha_{i}} \vee \beta_{i} \vee \overline{\gamma_{i}} \vee \overline{\alpha_{i+1}} \vee \overline{\beta_{i+1}} \vee \overline{\gamma_{i+1}}=1 \\
& \overline{\alpha_{i}} \vee \overline{\beta_{i}} \vee \gamma_{i} \vee \overline{\alpha_{i+1}} \vee \overline{\beta_{i+1}} \vee \overline{\gamma_{i+1}}=1 \text { ) }
\end{aligned}
$$

where the Xor operation denoted by $\oplus$ is symbolic representations which can be converted into CNF formulas with the method in Differential Model 2 (Xor). In
order to model the different probability, we will introduce $(n-1)$ binary variables denoted as $w_{0}, w_{1}, \ldots, w_{n-2}$. When they satisfy the following equations:

$$
\left.\begin{array}{l}
\alpha_{i+1} \vee \gamma_{i+1} \vee w_{i}=1 \\
\beta_{i+1} \vee \overline{\gamma_{i+1}} \vee w_{i}=1 \\
\alpha_{i+1} \vee \overline{\beta_{i+1}} \vee w_{i}=1 \\
\alpha_{i+1} \vee \beta_{i+1} \vee \gamma_{i+1} \vee \overline{w_{i}}=1 \\
\overline{\alpha_{i+1}} \vee \overline{\beta_{i+1}} \vee \overline{\gamma_{i+1}} \vee \overline{w_{i}}=1
\end{array}\right\} 0 \leq i \leq n-2
$$

the differential probability can be computed as $p(\alpha, \beta, \gamma)=2^{-\sum_{i=0}^{n-2} w_{i}}$.
The papers [SWW21,LWR16] have showed the model for the linear correlations through modular addition. Because the most-significant bit of modular addition is a constant value, we can omit this variable. So we give a new linear model for modular addition which is a little different from the previous.

Linear Model 1 (Modular Addition). For n-bit modular addition operation $z=f(x, y)$, we denote the two input linear masks as $\alpha$ and $\beta$ and the output mask as $\gamma$. And in order to model the correlation, $(n-1)$ binary variables denoted as $w=\left(w_{0}, w_{1}, \ldots, w_{n-2}\right)$ are introduced. Then, the correlation of the linear approximation $(\alpha, \beta, \gamma) \in \mathbb{F}_{2}^{3 \times n}$ is nonzero if and only if $(\alpha, \beta, \gamma, w)$ satisfies all the following equations:

$$
\left.\begin{array}{l}
\alpha_{0} \oplus \beta_{0} \oplus \gamma_{0} \oplus w_{0}=0 \\
\alpha_{j+1} \oplus \beta_{j+1} \oplus \gamma_{j+1} \oplus w_{j} \oplus w_{j+1}=0,0 \leq j \leq n-3 \\
\alpha_{0}=\beta_{0}=\gamma_{0} ; \\
\alpha_{i} \vee \gamma_{i} \vee w_{i-1}=1 \\
\overline{\alpha_{i}} \vee \gamma_{i} \vee w_{i-1}=1 \\
\beta_{i} \vee \gamma_{i} \vee w_{i-1}=1 \\
\overline{\beta_{i}} \vee \gamma_{i} \vee w_{i-1}=1
\end{array}\right\} 1 \leq i \leq n-1
$$

Then, the linear correlation is computed as $p(\alpha, \beta, \gamma)=2^{-\sum_{i=0}^{n-2} w_{i}}$.
For S-box, the paper [SWW18] showed an example of building the differential SAT model of 4-bit S-box. Then, the paper [SWW21] proposed the SAT model of active $n$-bit S-box. Based on the above two methods, we will show a general method for building SAT model of S-box.

Differential Model 4 (S-box). For an S-box $f: \mathbb{F}_{2}^{n} \rightarrow \mathbb{F}_{2}^{m}$, the differential probability is denoted as $p(\alpha, \beta)$, where $\alpha \in \mathbb{F}_{2}^{n}$ is the input difference and $\beta \in \mathbb{F}_{2}^{m}$ is the output difference. If the minimal non-zero differential probability of S-box is $2^{-s}$, where $s$ is an integer, we introduce $s$ auxiliary variables $w_{0}, w_{1}, \ldots, w_{s-1}$ satisfying $w_{i+1} \leq w_{i}, 0 \leq i \leq s-2$ to calculate the non-zero differential probability. In order to build the differential SAT model of S-box, we introduce a boolean function as follows:

$$
g(\alpha, \beta, w)=\left\{\begin{array}{l}
1, \text { if } p(\alpha, \beta)=2^{-\sum_{i=0}^{s-1} w_{i}} \\
0, \text { otherwise }
\end{array}\right.
$$

Let $A$ be a set which contains all vectors satisfying $g(a, b, c)=0$ denoted as

$$
A=\left\{(a, b, c) \in \mathbb{F}_{2}^{n+m+s} \mid g(a, b, c)=0\right\} .
$$

Then, the following $|A|$ clauses form a primary differential SAT model of the given $S$-box

$$
\bigvee_{i=0}^{n-1}\left(\alpha_{i} \oplus a_{i}^{l}\right) \vee \bigvee_{j=0}^{m-1}\left(\beta_{j} \oplus b_{j}^{l}\right) \vee \bigvee_{k=0}^{s-1}\left(w_{k} \oplus c_{k}^{l}\right)=1,\left(a^{l}, b^{l}, c^{l}\right) \in A
$$

where $|A|$ is the number of vectors in the set $A$ and $\left(a^{l}, b^{l}, c^{l}\right), 0 \leq l \leq|A|-1$ is the l-th vector in the set $A$.

Note that the solution space of the above $|A|$ clauses about $(\alpha, \beta, \gamma)$ is the same as that of the following boolean function:

$$
h(\alpha, \beta, \gamma)=\bigwedge_{l=0}^{|A|-1}\left(\bigvee_{i=0}^{n-1}\left(\alpha_{i} \oplus a_{i}^{l}\right) \vee \bigvee_{j=0}^{m-1}\left(\beta_{j} \oplus b_{j}^{l}\right) \vee \bigvee_{k=0}^{s-1}\left(w_{k} \oplus c_{k}^{l}\right)\right)=1
$$

Equivalently, we have

$$
\begin{aligned}
& h(\alpha, \beta, \gamma)= \\
& \bigwedge_{(a, b, c) \in \mathbb{F}_{2}^{n+m+s}}\left(h(a, b, c) \vee \bigvee_{i=0}^{n-1}\left(\alpha_{i} \oplus a_{i}\right) \vee \bigvee_{j=0}^{m-1}\left(\beta_{j} \oplus b_{j}\right) \vee \bigvee_{k=0}^{s-1}\left(w_{k} \oplus c_{k}\right)\right) .
\end{aligned}
$$

This equation is called the product-of-sum representation of $h$. The issue of reducing the number of clauses is turned into the problem of simplifying the product-of-sum representation of the boolean function. According to [AST ${ }^{+}$17], we know that this simplification problem can be solved by the Quine-McCluskey (QM) algorithm and Espresso algorithm, theoretically. Although it is also an NP-complete problem, the small-scale problem can be solved by some softwares, such as Logic Friday ${ }^{3}$. After simplification, the SAT model characterising the differential propagation through S-box can be established.

Using the same method of differential SAT model for S-box, the SAT model for linear correlations through S-box can be built easily. Here, we omit it.

### 2.3 Sequential Encoding Method

When we build SAT model of ciphers, we always aim at getting some cryptographic property such as the number of active S-boxes, the differential probability or the linear correlation. All kinds of these objections can be abstracted as the boolean cardinality constraint $\sum_{i=0}^{n-1} w_{i} \leq m$, where $w_{i}$ is a boolean variable, and $m$ is a non-negative integer. However, addition over integers is not a natural operation in SAT language, which is not easy to describe with only OR and AND

[^0]operations. The sequential encoding method is one of the best methods which can use relatively small amount of additional variables and a great reduction of clauses to characterise the constraint. Many papers [SWW21,SWW18,LWR16] use the sequential encoding method to convert the constraint into CNF formulas.

When $m=0$, the cardinality constraint $\sum_{i=0}^{n-1} w_{i} \leq m$ can be translated to $n$ clauses as $\overline{w_{i}}=1,0 \leq i \leq n-1$ which means all variables are zero.

When $m \geq 1$, in order to model constraint $\sum_{i=0}^{n-1} w_{i} \leq m$, auxiliary boolean variables $u_{i, j}(0 \leq i \leq n-2,0 \leq j \leq m-1)$ are introduced to return contradiction when the cardinality is larger than $m$. More specifically, for the partial sum $\sum_{i=0}^{k} w_{i}=m_{k}$, the values of the auxiliary boolean variables $u_{k, j}(0 \leq j \leq m-1)$ should satisfy the following equations:

$$
u_{k, j}=\left\{\begin{array}{l}
0, \text { if } m_{k} \leq j \leq m-1 \\
1, \text { if } 0 \leq j \leq m_{k}-1
\end{array}\right.
$$

Then, $\sum_{i=0}^{k} w_{i}=\sum_{j=0}^{m-1} u_{k, j}$, and the sequence $\left\{\sum_{i=0}^{k} w_{i} \mid 0 \leq k \leq n-2\right\}$ is non-decreasing. Therefore, the constraint $\sum_{i=0}^{n-1} w_{i} \leq m$ holds if the following implication predicates are satisfied.

```
if \(w_{0}=1\) then \(u_{0,0}=1\)
\(u_{0, j}=0,1 \leq j \leq m-1\)
if \(w_{i}=1\) then \(u_{i, 0}=1\)
if \(u_{i-1,0}=1\) then \(u_{i, 0}=1\)
\(\left.\left.\begin{array}{l}\text { if } w_{i}=1 \text { and } u_{i-1, j-1}=1 \text { then } u_{i, j}=1 \\ \text { if } u_{i-1, j}=1 \text { then } u_{i, j}=1 \\ \text { if } w_{i}=1 \text { then } u_{i-1, m-1}=0\end{array}\right\} 1 \leq j \leq m-1\right\} 1 \leq i \leq n-2\)
```

if $w_{n-1}=1$ then $u_{n-2, m-1}=0$

The above predicates can be interpreted as the following $2 \cdot m \cdot n-3 \cdot m+n-1$ clauses which are the SAT model for the cardinality constraint $\sum_{i=0}^{n-1} w_{i} \leq m$.

$$
\left.\left.\begin{array}{l}
\overline{w_{0}} \vee u_{0,0}=1 \\
\overline{u_{0, j}}=1,1 \leq j \leq m-1 \\
\overline{w_{i}} \vee u_{i, 0}=1 \\
\overline{u_{i-1,0}} \vee u_{i, 0}=1 \\
\overline{w_{i}} \vee \overline{u_{i-1, j-1}} \vee u_{i, j}=1 \\
\overline{u_{i-1, j}} \vee u_{i, j}=1 \\
\overline{w_{i}} \vee \overline{u_{i-1, m-1}}=1 \\
\overline{w_{n-1}} \vee \overline{u_{n-2, m-1}}=1
\end{array}\right\} 1 \leq j \leq m-1\right\} 1 \leq i \leq n-2
$$

### 2.4 Combining Matsui's Bounding Conditions with Sequential Encoding Method

At EUROCRYPT 1994, Matsui [Mat94] proposed a branch and bound search algorithm which can be used to identify the optimal difference with the maximum probability. Let $P_{\text {ini }}(R)$ be the initial estimation for the probability bound achieved by $R$-round trails. With the knowledge of $P_{o p t}(i), 1 \leq i \leq R-1$, where $P_{\text {opt }}(i)$ is the maximum probability achieved by $i$-round trails, a partial trail $\left(\alpha^{0}, \alpha^{1}, \ldots, \alpha^{r}\right), 1 \leq r \leq R-1$ covering the first $r$ rounds will never extend to be a better $R$-round trial if it does not satisfy the following condition:

$$
\begin{equation*}
\prod_{i=0}^{r-1} p\left(\alpha^{i} \rightarrow \alpha^{i+1}\right) \cdot P_{o p t}(R-r) \geq P_{i n i}(R) \tag{1}
\end{equation*}
$$

where $p\left(\alpha^{i} \rightarrow \alpha^{i+1}\right)$ is the probability of the $i$-th round. Therefore, we can give up the partial trail. In this way, the efficiency of search algorithm can be improved greatly.

Let $-\log _{2}\left(p\left(\alpha^{i} \rightarrow \alpha^{i+1}\right)\right)=\sum_{j=0}^{\varpi-1} w_{j}^{i}$, where $w_{j}^{i}, 0 \leq j \leq \varpi-1$ are the boolean variables used to calculate the probability weight of the trail propagation $\alpha^{i} \rightarrow \alpha^{i+1}$. By define the symbols $n=r \cdot \varpi$ and $w_{(\varpi \times i+j)}=w_{j}^{i}$. Then, the Eq. (1) can be rewritten as follows:

$$
\begin{equation*}
\sum_{i=0}^{r-1} \sum_{j=0}^{\varpi-1} w_{j}^{i}=\sum_{i=0}^{n-1} w_{i} \leq \log _{2}\left(P_{\text {opt }}(R-r)\right)-\log _{2}\left(\operatorname{Pr}_{\text {ini }}(R)\right) \tag{2}
\end{equation*}
$$

Note that the right-hand side of this equation is a constant, and the left-hand side of it matches the probability weight of the trail covering the first $r$ rounds. Generally, all the above bounding conditions can be replaced with an inequality constraint of the following form:

$$
\begin{equation*}
\sum_{i=e_{1}}^{e_{2}} w_{i} \leq m_{e_{1}, e_{2}}, 0 \leq e_{1} \leq e_{2} \tag{3}
\end{equation*}
$$

Matsui's bounding conditions can be incorporated into automatic search algorithms. In [ZSCH18], Zhang et al. incorporated Matsui's bounding conditions into the MILP based automatic search of differential characteristics. Then, Sun et al. [SWW21] integrate Matsui's bounding conditions into the SAT method so that the search for optimal differential and linear characteristics can be accelerated. Here, we will introduce the SAT model of combining Matsui's bounding conditions with sequential encoding method.

For the boolean cardinality constraint $\sum_{i=0}^{n-1} w_{i} \leq m$, based on the sequential encoding method, Sun et al. realized bounding conditions without claiming any new variables as follows.

Case 1. Bounding condition $\sum_{i=e_{1}}^{e_{2}} w_{i} \leq m_{e_{1}, e_{2}}$ with $e_{1}=0$ and $e_{2}<n-1$ can be modeled by the following $e_{2}$ clauses:

$$
\overline{w_{i}} \vee \overline{u_{i-1, m_{e_{1}, e_{2}}-1}}=1,1 \leq i \leq e_{2} .
$$

Case 2. Bounding condition $\sum_{i=e_{1}}^{e_{2}} w_{i} \leq m_{e_{1}, e_{2}}$ with $e_{1}>0$ and $e_{2}<n-1$ can be modeled by the following $m-m_{e_{1}, e_{2}}$ clauses:

$$
u_{e_{1}-1, j} \vee \overline{u_{e_{2}, j+m_{e_{1}, e_{2}}}}=1,0 \leq j \leq m-m_{e_{1}, e_{2}}-1 .
$$

Case 3. Bounding condition $\sum_{i=e_{1}}^{e_{2}} w_{i} \leq m_{e_{1}, e_{2}}$ with $e_{1}>0$ and $e_{2}=n-1$ can be modeled by the following $2 \cdot\left(m-m_{e_{1}, e_{2}}\right)+1$ clauses:

$$
\left\{\begin{array}{l}
u_{e_{1}-1, j} \vee \overline{u_{n-2, j+m_{e_{1}, e_{2}}}}=1,0 \leq j \leq m-m_{e_{1}, e_{2}}-1 \\
u_{e_{1}-1, j} \vee \overline{w_{n-1}} \vee \overline{u_{n-2, j+m_{e_{1}, e_{2}}-1}}=1,0 \leq j \leq m-m_{e_{1}, e_{2}}
\end{array}\right.
$$

The above method can intermix multiple Matsui's bounding conditions into one SAT problem with an increment on the number of clauses. At the same time, the number of variables remains the same as the original SAT model. According to the experiments, adding all the Matsui's bounding conditions into the SAT model is not the best choice. Thus, Sun et al. put forward a strategy on how to organise the sets of bounding conditions that potentially achieve better performance.

## 3 The Properties of Matsui's Bounding Conditions

We all know that the efficiency of Matsui's algorithm comes from the fact that it can eliminate some impossible solutions and reduce the search space. But, there is no relevant theory which can quantify this effect. In order to make better use of Matsui's bounding conditions, we will researching the properties of them.

### 3.1 Quantify the Effect of Matsui's Bounding Conditions

With the same mathematical symbols defined in Sect. 2, let $w_{i} \in \mathbb{F}_{2}, 0 \leq i \leq n-1$ be the variables which are used to calculate the differential probability or linear correlation of a cipher. Because we want to study the nature of the Matsui's bounding conditions without considering the specific cryptographic algorithm. In order to avoid the influence of the specific cryptographic algorithm, we propose the definition of ideal cryptographic algorithm.

Definition 1. Let $W=\left\{w^{i} \in \mathbb{F}_{2}^{n}, 0 \leq i \leq m-1\right\}$ be a cryptographic property vector set and $E$ be a cipher. The event that $E$ has property $w^{i} \in W$ is denoted as $E\left[w^{i}\right]$. And the event that $E$ does not has property $w^{i} \in W$ is denoted as $E\left[\overline{w^{i}}\right]$. Then, $E$ is an ideal cipher of $W$ if it satisfies the following conditions:
(1) For any vector $w^{i} \in W$, whether $E$ has property $w^{i}$ is random. That is, the probability of $E\left[w^{i}\right]$ is $\frac{1}{2}$, denoted as $p\left(E\left[w^{i}\right]\right)=\frac{1}{2}$.
(2) For any two vectors $w^{i}, w^{j} \in W, i \neq j, E\left[w^{i}\right]$ is independent with $E\left[w^{j}\right]$. That is $p\left(E\left[w^{i}, w^{j}\right]\right)=p\left(E\left[w^{i}\right]\right) \times p\left(E\left[w^{j}\right]\right)=\frac{1}{4}$, where $E\left[w^{i}, w^{j}\right]$ is the event that $E$ has the properties $w^{i}$ and $w^{j}$.

If we obtain a Matsui's bounding condition $\sum_{j=e_{1}}^{e_{2}} w_{j} \leq m_{e_{1}, e_{2}}$, all the vectors which do not satisfy $\sum_{j=e_{1}}^{e_{2}} w_{j} \leq m_{e_{1}, e_{2}}$ are not feasible cryptographic property. Thus, for vector $w^{i}=\left(w_{0}^{i}, w_{1}^{i}, \ldots, w_{n-1}^{i}\right)$ satisfying $\sum_{j=e_{1}}^{e_{2}} w_{j}^{i}>m_{e_{1}, e_{2}}$, we have $p\left(E\left[w^{i}\right]\right)=0$ and $p\left(E\left[\overline{w^{i}}\right]\right)=1$. In order to quantify the effect of Matsui's bounding conditions, we introduce the Information Theory of Shannon [Sha48] firstly.

Theorem 1. [Sha48] For a set of possibilities $P=\left\{p_{0}, p_{1}, \ldots, p_{n-1}\right\}$, the information produced by $P$ can be measured by $H(P)=-\sum_{i=0}^{n-1} p_{i} \log _{2}^{p_{i}}$.
Then, we use this theorem to measure the effect of Matsui's bounding conditions.
Lemma 1. Let $E$ be an ideal cipher of a cryptographic property vector set $W=$ $\left\{w^{i} \in \mathbb{F}_{2}^{n}, 0 \leq i \leq m-1\right\}$ and $C=\left\{C^{0}, C^{1}, \ldots, C^{l-1}\right\}$ be a bounding conditions set. If there are $N$ vectors of $W$ which do not satisfy all the $l$ conditions in $C$, the information of $P=\left\{p\left(E\left[u^{0}, u^{1}, \ldots, u^{m-1}\right]\right) \mid u^{i} \in\left\{w^{i}, \overline{w^{i}}\right\}, 0 \leq i \leq m-1\right\}$ decreased by $C$ is $N$. And this property is denoted as $H_{d}(P, C)=N$.

Proof. Without considering the bounding conditions, we can apply Definition 1 and Theorem 1 to calculate the information of $P$ as follows:

$$
\begin{aligned}
H(P) & \left.=-\sum_{u^{i} \in\left\{w^{i}, \overline{w^{i}}\right\}, 0 \leq i \leq m-1} p\left(E\left[u^{0}, u^{1}, \ldots, u^{m-1}\right]\right) \log _{2}^{p\left(E\left[u^{0}, u^{1}, \ldots, u^{m-1}\right]\right.}\right) \\
& =-\sum_{u^{i} \in\left\{w^{i}, \overline{w^{i}}\right\}, 0 \leq i \leq m-1} 2^{-m} \log _{2}^{2-m}=m .
\end{aligned}
$$

When considering the $l$ bounding conditions, if a vector $w^{i}$ doesn't satisfying all the $l$ bounding conditions, it cannot be the feasible cryptographic property. Without losing generality, we denote the $N$ vectors which do not satisfy all the $l$ conditions as $\left\{w^{i} \mid 0 \leq i \leq N-1\right\}$. Then, we have

$$
\left\{\begin{array}{l}
p^{\prime}\left(E\left[w^{i}\right]\right)=0, \quad \text { if } 0 \leq i \leq N-1 ;  \tag{4}\\
p^{\prime}\left(E\left[\overline{w^{i}}\right]\right)=1, \text { if } 0 \leq i \leq N-1 ; \\
\left.p^{\prime}\left(E\left[w^{i}\right]\right)\right)=\frac{1}{2}, \text { if } N \leq i \leq m-1 ; \\
p^{\prime}\left(E\left[\overline{w^{i}}\right]\right)=\frac{1}{2}, \text { if } N \leq i \leq m-1 .
\end{array}\right.
$$

For $P^{\prime}=\left\{p^{\prime}\left(E\left[u^{0}, u^{1}, \ldots, u^{m-1}\right]\right) \mid u^{i} \in\left\{w^{i}, \overline{w^{i}}\right\}, 0 \leq i \leq m-1\right\}$, we have

$$
\begin{aligned}
H\left(P^{\prime}\right) & \left.=-\sum_{u^{i} \in\left\{w^{i}, \overline{w^{i}}\right\}, 0 \leq i \leq m-1} p^{\prime}\left(E\left[u^{0}, u^{1}, \ldots, u^{m-1}\right]\right) \log _{2}^{p^{\prime}\left(E\left[u^{0}, u^{1}, \ldots, u^{m-1}\right]\right.}\right) \\
& =-\sum_{u^{i} \in\left\{w^{i}, \overline{w^{i}}\right\}, N \leq i \leq m-1} 2^{-m+N} \log _{2}^{2-m+N}=m-N .
\end{aligned}
$$

The information of $P$ decreased by $C$ is $H_{d}(P, C)=H(P)-H\left(P^{\prime}\right)=N$.
When building SAT models, we have to convert the Matsui's bounding conditions into other form of formulas. In the following, we will evaluate the property of the transformation.

Lemma 2. Let $P=\left\{p\left(E\left[u^{0}, u^{1}, \ldots, u^{m-1}\right]\right) \mid u^{i} \in\left\{w^{i}, \overline{w^{i}}\right\}, 0 \leq i \leq m-1\right\}$ be a cryptographic property possibilities set. If $c$ is a bounding conditions set converted from the bounding conditions set $C$. Then, we have $H_{d}(P, c) \leq H_{d}(P, C)$.

Proof. Let $w^{i}$ be a vector that satisfies all the bounding conditions in $C$. Because $c$ is converted from $C, w^{i}$ should also satisfies all the formulas in $c$. We have

$$
m-H_{d}(P, C) \leq m-H_{d}(P, c) \Rightarrow H_{d}(P, c) \leq H_{d}(P, C)
$$

Corollary 1. Let $c$ be the bounding conditions set which is converted from the bounding condition set $C$. When $H_{d}(P, c)=H_{d}(P, C)$, all the information provided by bounding conditions set $C$ has been fully utilized by $c$.

### 3.2 Further Insights into Matisui's Bounding Conditions

According to Sect. 2.4, Sun el al. summarized all the Matsui's bounding conditions as the form of $\sum_{i=e_{1}}^{e_{2}} w_{i} \leq m_{e_{1}, e_{2}}$. However, when researching the information decreased by the constraints of the form $\sum_{i=e_{1}}^{e_{2}} w_{i} \leq m_{e_{1}, e_{2}}$, we find that they cannot always utilized all the information provided by Matusui's bounding conditions. We will give an example to show this phenomenon.

For a toy cipher $E$ which has 3 rounds, let $\left(\alpha^{0}, \alpha^{1}, \alpha^{2}, \alpha^{3}\right)$ be the 3 -round trail. By introducing 6 boolean variables $w=\left\{w_{0}^{(0)}, w_{1}^{(0)}, w_{0}^{(1)}, w_{1}^{(1)}, w_{0}^{(2)}, w_{1}^{(2)}\right\}$, the probability of round function is calculated as follows:

$$
\begin{equation*}
-\log _{2}\left(p\left(\alpha^{i} \rightarrow \alpha^{i+1}\right)\right)=w_{0}^{(i)}+w_{1}^{(i)} \tag{5}
\end{equation*}
$$

Let $P_{\text {opt }}(1)=2^{-1}, P_{\text {opt }}(2)=2^{-2}$ and $P_{\text {ini }}(3)=2^{-3}$ be the Matsui's bounding conditions. Then, the vectors satisfying all the above 3 conditions are as follow:

$$
\begin{aligned}
& \{0,1,0,1,0,1\},\{0,1,0,1,1,0\},\{0,1,1,0,0,1\},\{0,1,1,0,1,0\} \\
& \{1,0,0,1,0,1\},\{1,0,0,1,1,0\},\{1,0,1,0,0,1\},\{1,0,1,0,1,0\}
\end{aligned}
$$

Thus, the information decreased by $\left\{P_{o p t}(1), P_{o p t}(2), P_{\text {ini }}(3)\right\}$ is $2^{6}-8=56$.
According to Sect. 2.4, all the form of $\sum_{i=e_{1}}^{e_{2}} w_{i} \leq m_{e_{1}, e_{2}}$ conditions deduced from Matsui's bounding conditions are as follows:

$$
\left\{\begin{array}{l}
C_{0}:-\log _{2}\left(p\left(\alpha^{0} \rightarrow \alpha^{1}\right)\right) \leq \log _{2}\left(P_{\text {opt }}(2)\right)-\log _{2}\left(P_{\text {ini }}(3)\right) ;  \tag{6}\\
C_{1}:-\sum_{i=0}^{1} \log _{2}\left(p\left(\alpha^{i} \rightarrow \alpha^{i+1}\right)\right) \leq \log _{2}\left(P_{\text {opt }}(1)\right)-\log _{2}\left(P_{\text {ini }}(3)\right) ; \\
C_{2}:-\log _{2}\left(p\left(\alpha^{1} \rightarrow \alpha^{2}\right)\right) \leq 2 \cdot \log _{2}\left(P_{\text {opt }}(1)\right)-\log _{2}\left(P r_{\text {ini }}(3)\right) ; \\
C_{3}:-\sum_{i=1}^{2} \log _{2}\left(P\left(\alpha^{i} \rightarrow \alpha^{i+1}\right)\right) \leq \log _{2}\left(P_{\text {opt }}(1)\right)-\log _{2}\left(P_{\text {ini }}(3)\right) ; \\
C_{4}:-\log _{2}\left(p\left(\alpha^{2} \rightarrow \alpha^{3}\right)\right) \leq \log _{2}\left(P_{\text {opt }}(2)\right)-\log _{2}\left(P_{\text {ini }}(3)\right) ; \\
C_{5}:-\sum_{i=0}^{2} \log _{2}\left(p\left(\alpha^{i} \rightarrow \alpha^{i+1}\right)\right) \leq-\log _{2}\left(P_{\text {ini }}(3)\right) .
\end{array}\right.
$$

Combining Eq. (5) and Eq. (6), we have

$$
\left\{\begin{array}{l}
C_{0}^{\prime}: w_{0}^{(0)}+w_{1}^{(0)} \leq 1 \\
C_{1}^{\prime}: w_{0}^{(0)}+w_{1}^{(0)}+w_{0}^{(1)}+w_{1}^{(1)} \leq 2 \\
C_{2}^{\prime}: w_{0}^{(1)}+w_{1}^{(1)} \leq 1 \\
C_{3}^{\prime}: w_{0}^{(1)}+w_{1}^{(1)}+w_{0}^{(2)}+w_{1}^{(2)} \leq 2 \\
C_{4}^{\prime}: w_{0}^{(2)}+w_{1}^{(2)} \leq 1 \\
C_{5}^{\prime}: w_{0}^{(0)}+w_{1}^{(0)}+w_{0}^{(1)}+w_{1}^{(1)}+w_{0}^{(2)}+w_{1}^{(2)} \leq 3
\end{array}\right.
$$

Then, the 27 vectors that satisfy all the conditions $\left\{C_{0}^{\prime}, C_{1}^{\prime}, C_{2}^{\prime}, C_{3}^{\prime}, C_{4}^{\prime}, C_{5}^{\prime}\right\}$ are as follow:

$$
\begin{aligned}
& \{0,0,0,0,0,0\},\{0,0,0,0,0,1\},\{0,0,0,0,1,0\},\{0,0,0,1,0,0\},\{0,0,0,1,0,1\}, \\
& \{0,0,0,1,1,0\},\{0,0,1,0,0,0\},\{0,0,1,0,0,1\},\{0,0,1,0,1,0\},\{0,1,0,0,0,0\}, \\
& \{0,1,0,0,0,1\},\{0,1,0,0,1,0\},\{0,1,0,1,0,0\},\{0,1,0,1,0,1\},\{0,1,0,1,1,0\}, \\
& \{0,1,1,0,0,0\},\{0,1,1,0,0,1\},\{0,1,1,0,1,0\},\{1,0,0,0,0,0\},\{1,0,0,0,0,1\}, \\
& \{1,0,0,0,1,0\},\{1,0,0,1,0,0\},\{1,0,0,1,0,1\},\{1,0,0,1,1,0\},\{1,0,1,0,0,0\}, \\
& \{1,0,1,0,0,1\},\{1,0,1,0,1,0\} .
\end{aligned}
$$

That is, the information decreased by conditions $\left\{C_{0}^{\prime}, C_{1}^{\prime}, C_{2}^{\prime}, C_{3}^{\prime}, C_{4}^{\prime}, C_{5}^{\prime}\right\}$ is $2^{6}-$ $27=37$. Therefore, the bounding conditions $\left\{C_{0}^{\prime}, C_{1}^{\prime}, C_{2}^{\prime}, C_{3}^{\prime}, C_{4}^{\prime}, C_{5}^{\prime}\right\}$ do not utilize all the information provided by $\left\{P_{\text {opt }}(1), P_{\text {opt }}(2), P_{\text {ini }}(3)\right\}$.

Here, we analyze the reasons for this phenomenon. When using Matsui's branch and bounding algorithm to search $R$-round optimal trails, we will firstly obtain a partial trail denoted as $\left(\alpha^{0}, \alpha^{1}, \ldots, \alpha^{r}\right)$ covering the first $r$ rounds. Then, we can use Eq. (1) to deduce the bound conditions of the form $\sum_{i=e_{1}}^{e_{2}} w_{i} \leq$ $m_{e_{1}, e_{2}}$. But, it should be noted that all the obtained partial trails are valid. That is, the partial trials should satisfy

$$
\sum_{i=0}^{r-1}-\log _{2}\left(p\left(\alpha^{i} \rightarrow \alpha^{i+1}\right)\right) \geq-\log _{2}\left(P_{o p t}(r)\right)
$$

Therefore, when combining Matsui's bounding conditions with automatic search algorithm, this kind of bounding conditions should also be considered.

Theorem 2. For an $R$-round cipher, the following bounding conditions can utilize all the information provided by $M=\left\{P_{\text {ini }}(R), P_{\text {opt }}(i), 1 \leq i \leq R-1\right\}$.

$$
\left.\begin{array}{c}
A_{j, r}: \sum_{i=j}^{r}\left(-\log _{2}\left(p\left(\alpha^{i} \rightarrow \alpha^{i+1}\right)\right)\right) \leq \log _{2}\left(P_{\text {opt }}(j)\right) \\
\quad+\log _{2}\left(P_{o p t}(R-1-r)\right)-\log _{2}\left(P_{\text {ini }}(R)\right) \\
B_{j, r}: \sum_{i=j}^{r}\left(-\log _{2}\left(p\left(\alpha^{i} \rightarrow \alpha^{i+1}\right)\right)\right) \geq-\log _{2}\left(P_{o p t}(r+1-j)\right)
\end{array}\right\} \begin{aligned}
& 0 \leq j \leq r \\
& r \leq R-1
\end{aligned}
$$

Proof. Let $\left(\alpha^{j}, \alpha^{j+1}, \ldots, \alpha^{r+1}\right)$ be a feasible partial trail covering $(r+1-j)$ rounds, where $0 \leq j \leq r \leq R-1$. Because of the constraint $P_{o p t}(r+1-j)$, the partial trail should satisfy the following bounding condition:

$$
B_{j, r}: \sum_{i=j}^{r}\left(-\log _{2}\left(p\left(\alpha^{i} \rightarrow \alpha^{i+1}\right)\right)\right) \geq-\log _{2}\left(P_{o p t}(r+1-j)\right)
$$

Then, due to the constrain of $P_{\text {ini }}(R)$, the partial trail will also not be extended to better $R$-round trail if the following bounding condition is violated

$$
P_{o p t}(j) \cdot \prod_{i=j}^{r}\left(p\left(\alpha^{i} \rightarrow \alpha^{i+1}\right)\right) \cdot P_{o p t}(R-1-r) \leq P_{i n i}(R)
$$

And the above bounding condition can be converted into

$$
\begin{aligned}
A_{j, r}: \sum_{i=j}^{r}\left(-\log _{2}\left(p\left(\alpha^{i} \rightarrow \alpha^{i+1}\right)\right)\right) \leq & \log _{2}\left(P_{\text {opt }}(j)\right)+\log _{2}\left(P_{o p t}(R-1-r)\right) \\
& -\log _{2}\left(P_{\text {ini }}(R)\right)
\end{aligned}
$$

That is, the bounding conditions $\left\{A_{j, r}, B_{j, r} \mid 0 \leq j<r \leq R-1\right\}$ is converted from $M=\left\{P_{\text {ini }}(R), P_{\text {opt }}(i), 1 \leq i \leq R-1\right\}$. According to Lemma 2, we have

$$
\begin{equation*}
H_{d}\left(P,\left\{A_{j, r}, B_{j, r} \mid 0 \leq j \leq r \leq R-1\right\}\right) \leq H_{d}(P, M) \tag{7}
\end{equation*}
$$

Let $\left(\alpha^{0}, \alpha^{1}, \ldots, \alpha^{R}\right)$ be a trail which does not satisfy all the Matsui's bounding conditions in $M$. If $\left(\alpha^{0}, \alpha^{1}, \ldots, \alpha^{R}\right)$ does not satisfy $P_{\text {ini }}(R)$, it will not satisfy $A_{0, R-1}$. If $\left(\alpha^{0}, \alpha^{1}, \ldots, \alpha^{R}\right)$ satisfies $P_{\text {ini }}(R)$, there is at least a partial trail covering $k$ round that does not satisfy $P_{o p t}(k)$. We denote this partial trail as $\left(\alpha^{j}, \alpha^{j+1}, \ldots, \alpha^{j+k}\right)$. Then, this partial trail will violate the bounding condition $B_{j, j+k-1}$. So the trail $\left(\alpha^{0}, \alpha^{1}, \ldots, \alpha^{R}\right)$ will not satisfy all the bounding conditions in $\left\{A_{j, r}, B_{j, r} \mid 0 \leq j<r \leq R-1\right\}$. Therefore, we have

$$
\begin{equation*}
H_{d}\left(P,\left\{A_{j, r}, B_{j, r} \mid 0 \leq j<r \leq R-1\right\}\right) \geq H_{d}(P, M) . \tag{8}
\end{equation*}
$$

Combining Eq. (7) and Eq. (8), we have

$$
H_{d}\left(P,\left\{A_{j, r}, B_{j, r} \mid 0 \leq j<r \leq R-1\right\}\right)=H_{d}(P, M)
$$

According to Corollary 1, the conditions set $\left\{A_{j, r}, B_{j, r} \mid 0 \leq j<r \leq R-1\right\}$ utilizes all the information provided by $\left\{P_{\text {ini }}(R), P_{\text {opt }}(i), 1 \leq i \leq R-1\right\}$.

Using the same mathematical symbols with Eq. (3), we have the following corollary.

Corollary 2. All the Matsui's bounding conditions can be replaced with inequality constraints of the form $l_{e_{1}, e_{2}} \leq \sum_{i=e_{1}}^{e_{2}} w_{i} \leq m_{e_{1}, e_{2}}$.

## 4 The Simplest SAT Model of Combining Bounding Conditions with Sequential Encoding Method

Although numerous Matsui's bounding conditions can be obtained, it is not sure which bounding condition can accelerate the solve efficiency of SAT model accurately. With the observations and experiences in the tests, Sun et al. [SWW21] put forward a strategy on how to create the sets of bounding conditions that probably achieve extraordinary advances. But this is an experimental and heuristic strategy. It is worth studying how to combine bounding conditions with sequential encoding method in a better way.

### 4.1 A New Method of Combining Bounding Conditions with Sequential Encoding Method

According to Sec. 2.3, in order to model the cardinality constraint $\sum_{i=0}^{n-1} w_{i} \leq m$, the normal sequential encoding method needs $(n-1) \cdot m$ auxiliary variables, denoted as $u_{i, j}(0 \leq i \leq n-2,0 \leq j \leq m-1)$. Then, the paper [SWW21] intermix the bounding conditions $\sum_{i=e_{1}}^{e_{2}} w_{i} \leq m_{e_{1}, e_{2}}$ into the sequential encoding method by adding corresponding clauses. Different from the above strategy, we will propose a new method of intermixing multiple Matsui's bounding conditions into the sequential encoding method by removing some variables and clauses.

From Corollary 2, we know that the more general form of bounding condition is $l_{e_{1}, e_{2}} \leq \sum_{i=e_{1}}^{e_{2}} w_{i} \leq m_{e_{1}, e_{2}}$. If we get the condition $l_{0, e_{2}} \leq \sum_{i=0}^{e_{2}} w_{i} \leq m_{0, e_{2}}$, according to the rules of sequential encoding method, we have

$$
u_{e_{2}, j}= \begin{cases}0, & \text { if } m_{0, e_{2}} \leq j \leq m-1 \\ 1, & \text { if } 0 \leq j \leq l_{0, e_{2}}-1 \\ \text { uncertain, otherwise }\end{cases}
$$

Therefore, the value of some auxiliary variables are determine. We can omit the variables and clauses which characterise these determined values. Because there are at least $m_{0, e_{2}}-l_{0, e_{2}}$ auxiliary variables whose values are uncertain. We have to introduce the boolean variables denoted as $\left\{u_{e_{2}, j} \mid l_{0, e_{2}} \leq j \leq m_{e_{2}}-1\right\}$ to represent these uncertain values. Then, we can use the following equation to compute the partial sum of $\sum_{i=0}^{e_{2}} w_{i}$.

$$
\sum_{i=0}^{e_{2}} w_{i}=\sum_{j=l_{0, e_{2}}}^{m_{0, e_{2}}-1} u_{e_{2}, j}+l_{0, e_{2}}
$$

Base on this idea, we propose a new method of combining bounding conditions with sequential encoding method.

Lemma 3. Let $\sum_{i=0}^{n-1} w_{i} \leq m, 1 \leq n$ be a cardinality constraint. Based on the sequential encoding method, the following clauses can utilized all the information

$$
\begin{aligned}
& \text { if } l_{0,0}=0 \text { and } m_{0,0}=1: \\
& \quad \overline{w_{0}} \vee u_{0,0}=1 \\
& \text { if } l_{0,0}=0 \text { and } m_{0,0}=0: \\
& \quad \overline{w_{0}}=1 \\
& \text { if } l_{0,0}=1 \text { and } m_{0,0}=1: \\
& \quad w_{0}=1
\end{aligned}
$$

And this is the simplest model of using the sequential encoding method to characterise the bounding condition $l_{0,0} \leq w_{0} \leq m_{0,0}$.

Proof. When using original sequential encoding method to model the cardinality constraint $\sum_{i=0}^{n-1} w_{i} \leq m$, we have to introduce $m$ auxiliary boolean variables $u_{0,0}, u_{0,1}, \ldots, u_{0, m-1}$ to represent to the value of partial sum $w_{0}$. Different from the method in Sect. 2.4, we can realise the bounding condition $l_{0,0} \leq w_{0} \leq m_{0,0}$ by removing variables and clauses as follows.

When $l_{0,0}=0$ and $m_{0,0}=1$, only the value of $u_{0,0}$ is uncertain. And all the values of other auxiliary variables $u_{0,1}, u_{0,2}, \ldots, u_{0, m-1}$ are determined. We can remove all these determined variables and related clauses. Then, the value of partial sum $w_{0}$ can be represented by the rules of sequential encoding method as $\overline{w_{0}} \vee u_{0,0}=1$.

When $l_{0,0}=m_{0,0}=0$, all the values of auxiliary variables are determined. Thus, no auxiliary variables need to be introduced. And the value of partial sum $w_{0}$ can be represented as the clause $\overline{w_{0}}=1$.

When $l_{0,0}=m_{0,0}=1$, all the values of auxiliary variables are determined. Thus, all the auxiliary variables and related clauses can be removed. And the value of partial sum $w_{0}$ can be represented as the clause $w_{0}=1$.

In the above three cases, all the introduced auxiliary variables are used to represent the uncertain value and all the clauses are the rules of sequential encoding method to determined the values of variables. They are all necessary which can not be removed. Take $l_{0,0}=m_{0,0}=1$ as an example, if we remove the clause $w_{0}=1$, the value of $w_{0}$ that removed by bounding condition can not be removed. It is contradictory to the state that clauses can use all the information provided by the bounding condition. Therefore, this is the simplest model of using the sequential encoding method to characterise the bounding condition $l_{0,0} \leq w_{0} \leq m_{0,0}$.

Lemma 4. Let $\sum_{i=0}^{n-1} w_{i} \leq m, 3 \leq n$ be a cardinality constraint. If the bounding condition $l_{0, e_{2}-1} \leq \sum_{i=0}^{e_{2}-1} w_{i} \leq m_{0, e_{2}-1}, 1 \leq e_{2} \leq n-2$ is known, the following
6

clauses can utilized all the information provided by $l_{0, e_{2}} \leq \sum_{i=0}^{e_{2}} w_{i} \leq m_{0, e_{2}}$.

$$
\begin{align*}
& \text { if } m_{0, e_{2}}=0: \\
& \left.\begin{array}{c}
w_{e_{2}} \\
\text { if } m_{0, e_{2}}>1 \\
\text { if } l_{0, e_{2}}=0: \\
\overline{w_{e_{2}}} \vee u_{e_{2}, 0}=1 \\
\text { if } l_{0, e_{2}-1}<m_{0, e_{2}-1}: \\
\overline{u_{e_{2}-1,0}} \vee u_{e_{2}, 0}=1 \\
\text { if } j=l_{0, e_{2}-1}: \\
\overline{w_{e_{2}}} \vee u_{e_{2}, j}=1 \\
\text { if } j>l_{0, e_{2}-1} \text { and } j \leq m_{0, e_{2}-1}: \\
\overline{w_{e_{2}}} \vee \overline{u_{e_{2}-1, j-1}} \vee u_{e_{2}, j}=1 \\
\text { if } j \geq l_{0, e_{2}-1} \text { and } j \leq m_{0, e_{2}-1}-1: \\
\overline{u_{e_{2}-1, j}} \vee u_{e_{2}, j}=1
\end{array}\right\} \max \left(l_{0, e_{2}}, 1\right) \leq j \leq m_{0, e_{2}}-1 \\
& \text { if } m_{0, e_{2}-1}=m_{0, e_{2}} \text { and } l_{0, e_{2}-1}<m_{0, e_{2}}: \\
& \overline{w_{e_{2}}} \vee \overline{u_{e_{2}-1, m_{0, e_{2}}-1}}=1 \\
& \text { if } l_{0, e_{2}-1}=m_{0, e_{2}}: \\
& \overline{w_{e_{2}}}=1
\end{align*}
$$

And this is the simplest SAT model of using sequential encoding method to characterise the bounding condition $l_{0, e_{2}} \leq \sum_{i=0}^{e_{2}} w_{i} \leq m_{0, e_{2}}$.

Proof. When using original sequential encoding method to model the cardinality constraint $\sum_{i=0}^{n-1} w_{i} \leq m$, we have to introduce $m$ auxiliary boolean variables $u_{e_{2}, 0}, u_{e_{2}, 1}, \ldots, u_{e_{2}, m-1}$ to represent to the value of partial sum $\sum_{i=0}^{e_{2}} w_{i}$. Different from the method in Sect. 2.4, we can realise the bounding condition $l_{0, e_{2}} \leq \sum_{i=0}^{e_{2}} w_{i} \leq m_{0, e_{2}}$ by removing variables and clauses as follows.

When $m_{0, e_{2}}=0$, all the values of auxiliary variables are determined. Thus, all the auxiliary variables and related clauses can be removed. And the value of $w_{e_{2}}$ can be represented as the clauses $\overline{w_{e_{2}}}=1$.

When $m_{0, e_{2}}>0$, in order to characterise the value of $\sum_{i=0}^{e_{2}} w_{i}$, the auxiliary variables $m_{0, e_{2}}-l_{0, e_{2}}$ whose values are uncertain must be introduced, denoted as $\left\{u_{e_{2}, j} \mid l_{0, e_{2}} \leq j \leq m_{0, e_{2}}-1\right\}$. And all the other auxiliary variables whose values are determined can be removed. Then, we use the rules of sequential encoding method to model these variables one by one.

If $l_{0, e_{2}}=0$, the value of $u_{e_{2}, 0}$ should satisfy the following rules of sequential encoding method.

$$
\left\{\begin{array}{l}
\text { if } w_{e_{2}}=1 \text { then } u_{e_{2}, 0}=1 \\
\text { if } u_{e_{2}-1,0} \text { is uncertain, when } u_{e_{2}-1,0}=1 \text { then } u_{e_{2}, 0}=1
\end{array}\right.
$$

For $\max \left(l_{0, e_{2}}, 1\right) \leq j \leq m_{0, e_{2}}-1$, the value of $u_{e_{2}, j}$ should satisfy the following rules of sequential encoding method.

$$
\left\{\begin{array}{l}
\text { if } u_{e_{2}-1, j-1} \text { is determined as } 1 \text { and } w_{e_{2}}=1 \text { then } u_{e_{2}, j}=1 \\
\text { if } u_{e_{2}-1, j-1} \text { is uncertain, when } u_{e_{2}-1, j-1}=1 \text { and } w_{e_{2}}=1 \text { then } u_{e_{2}, j}=1 ; \\
\text { if } u_{e_{2}-1, j} \text { is uncertain, when } u_{e_{2}-1, j}=1 \text { then } u_{e_{2}, j}=1
\end{array}\right.
$$

Because of the bounding condition $l_{0, e_{2}} \leq \sum_{i=0}^{e_{2}} w_{i} \leq m_{0, e_{2}}$ and the rules of sequential encoding method, auxiliary boolean variables $u_{e_{2}, j}$ will return contradiction when $\sum_{i=0}^{e_{2}} w_{i}>m_{0, e_{2}}$. Thus, the following clauses should be satisfied.
$\left\{\begin{array}{l}\text { if } m_{0, e_{2}-1}=m_{0, e_{2}}, u_{e_{2}-1, m_{0, e_{2}}-1} \text { is uncertain, } w_{e_{2}}=1 \text { then } u_{e_{2}-1, m_{0, e_{2}}-1}=0 ; \\ \text { if } l_{0, e_{2}-1}=m_{0, e_{2}} \text { then } w_{e_{2}}=0 .\end{array}\right.$
The above predicates can be interpreted as the clauses as Eq. (9). Moreover, because the values of $u_{e_{2}, j}, l_{0, e_{2}} \leq j \leq m_{e_{2}}-1$ are uncertain. According to the rules of sequential encoding method, all these variables and corresponding clauses should not be omit. Therefore, this is the simplest model of using the sequential encoding method to characterise the bounding condition $l_{0, e_{2}} \leq \sum_{i=0}^{e_{2}} w_{i} \leq$ $m_{0, e_{2}}$.
Lemma 5. For cardinality constraint $\sum_{i=0}^{n-1} w_{i} \leq m, 2 \leq n$, if the bounding condition $l_{0, n-2} \leq \sum_{i=0}^{n-2} w_{i} \leq m_{0, n-2}$ is known, the following clauses can utilized all the information provided by the condition $l_{0, n-1} \leq \sum_{i=0}^{n-1} w_{i} \leq m_{0, n-1}$.

$$
\left\{\begin{array}{l}
\text { if } m_{0, n-1}=0:  \tag{10}\\
\quad \overline{w_{n-1}}=1 \\
\text { if } m_{0, n-1}>0: \\
\quad \text { if } m_{0, n-2}=m_{0, n-1} \text { and } l_{0, n-2}<m_{0, n-1}: \\
\overline{w_{n-1}} \vee \overline{u_{n-2, m_{0, n-1}-1}}=1 \\
\text { if } l_{0, n-2}=m_{0, n-1}: \\
\overline{w_{n-1}}=1
\end{array}\right.
$$

And this is the simplest SAT model of using sequential encoding method to characterise the bounding condition $l_{0, n-1} \leq \sum_{i=0}^{n-1} w_{i} \leq m_{0, n-1}$.
Proof. According to Lemma 3 and 4, we know that the auxiliary variables $u_{n-2, j}, l_{0, n-2} \leq j \leq m_{0, n-2}-1$ is introduced to describe the value of $\sum_{i=0}^{n-2} w_{i}$. For the bounding condition $l_{0, n-1} \leq \sum_{i=0}^{n-1} w_{i} \leq m_{0, n-1}$, we only need to know whether the condition is valid or not. Therefore, no auxiliary variables need to be introduced. Then, the value of $w_{n-1}$ should satisfy the following rules of sequential encoding method.

$$
\left\{\begin{array}{l}
\text { if } m_{0, n-1}=0 \text { then } w_{n-1}=0 ; \\
\text { if } l_{0, n-2}<m_{0, n-1}=m_{0, n-2}, w_{n-1}=1 \text { then } u_{n-2, m_{0, n-1}-1}=0 ; \\
\text { if } m_{0, n-1}>0, l_{0, n-2}=m_{0, n-1} \text { then } w_{n-1}=0 .
\end{array}\right.
$$

529 The above predicates can be interpreted as the clauses as Eq. (10). And all these clauses are the rules of sequential encoding method which can not be omit.
${ }_{531}$ Theorem 3. Based on the sequential encoding method, the following clauses bounding conditions $l_{0, e_{2}} \leq \sum_{i=0}^{e_{2}} w_{i} \leq m_{0, e_{2}}, 0 \leq e_{2} \leq n-1$ :

```
if \(l_{0,0}=0\) and \(m_{0,0}=1\) :
    \(\overline{w_{0}} \vee u_{0,0}=1\)
else if \(l_{0,0}=m_{0,0}=0\) :
    \(\overline{w_{0}}=1\)
else if \(l_{0,0}=1\) and \(m_{0,0}=1\) :
    \(w_{0}=1\)
    if \(m_{0, e_{2}}=0\) :
        \(\overline{w_{e_{2}}}=1\)
    if \(m_{0, e_{2}}>0\) :
        if \(l_{0, e_{2}}=0\) :
        \(\overline{w_{e_{2}}} \vee u_{e_{2}, 0}=1\)
        if \(l_{0, e_{2}-1}<m_{0, e_{2}-1}\) :
            \(\overline{u_{e_{2}-1,0}} \vee u_{e_{2}, 0}=1\)
            if \(j=l_{0, e_{2}-1}\)
                \(\overline{w_{e_{2}}} \vee u_{e_{2}, j}=1\)
            if \(j>l_{0, e_{2}-1}\) and \(\left.j \leq m_{0, e_{2}-1} \quad \max \left(l_{0, e_{2}}, 1\right) \leq j\right\} \begin{aligned} & -e_{2} \\ & \leq n-2\end{aligned}\)
                    \(\left.\overline{w_{e_{2}}} \vee \overline{u_{e_{2}-1, j-1}} \vee u_{e_{2}, j}=1 \quad\right\} \leq m_{0, e_{2}}-1\)
            if \(j \geq l_{0, e_{2}-1}\) and \(j \leq m_{0, e_{2}-1}-1\)
                    \(\overline{u_{e_{2}-1, j}} \vee u_{e_{2}, j}=1\)
    if \(m_{0, e_{2}-1}=m_{0, e_{2}}\) and \(l_{0, e_{2}-1}<m_{0, e_{2}}\)
        \(\overline{w_{e_{2}}} \vee \overline{u_{e_{2}-1, m_{0, e_{2}}-1}}=1\)
    if \(l_{0, e_{2}-1}=m_{0, e_{2}}\)
        \(\overline{w_{e_{2}}}=1\)
    if \(m_{0, n-1}=0\) :
        \(\overline{w_{n-1}}=0\)
if \(m_{0, n-1}>0\) :
    if \(m_{0, n-2}=m_{0, n-1}\) and \(l_{0, n-2}<m_{0, n-1}\) :
        \(\overline{w_{n-1}} \vee \overline{u_{n-2, m_{0, n-1}-1}}=1\)
    if \(l_{0, n-2}=m_{0, n-1}\) :
        \(\overline{w_{n-1}}=1\)
```

Proof. Any bounding condition $l_{0, e_{2}} \leq \sum_{i=0}^{e_{2}} w_{i} \leq m_{0, e_{2}}$ belongs to only one case of Lemma 3-5. Therefore, we can integrate them into Eq. (11) which is the simplest SAT model based on sequential encoding method.

According to Theorem 3, the number of variables and clauses of the simplest SAT model of combining bounding conditions with sequential encoding method is only related to the upper bound and lower bound of partial sum $\sum_{i=0}^{e_{2}} w_{e_{2}}, 0 \leq e_{2} \leq n-1$. Specifically, the total number of auxiliary variables needed is $\sum_{i=0}^{n-2}\left(m_{0, i}-l_{0, i}\right)$. And after checking the generation rules of each clause in Eq. (11), we can easily get the following corollary.
Corollary 3. For two conditions sets $\left\{l_{0, e_{2}} \leq \sum_{i=0}^{e_{2}} w_{i} \leq m_{0, e_{2}}, 0 \leq e_{2} \leq n-1\right\}$ and $\left\{L_{0, e_{2}} \leq \sum_{i=0}^{e_{2}} w_{i} \leq M_{0, e_{2}}, 0 \leq e_{2} \leq n-1\right\}$, if the inequalities $l_{0, e_{2}} \geq L_{0, e_{2}}$ and $m_{0, e_{2}} \leq M_{0, e_{2}}$ hold for all $0 \leq e_{2} \leq n-1$, when using Theorem 3 to give their SAT models, the numbers of variables and clauses needed to characterise $\left\{l_{0, e_{2}} \leq \sum_{i=0}^{e_{2}} w_{i} \leq m_{0, e_{2}}, 0 \leq e_{2} \leq n-1\right\}$ will not more than those of $\left\{L_{0, e_{2}} \leq \sum_{i=0}^{e_{2}} w_{i} \leq M_{0, e_{2}}, 0 \leq e_{2} \leq n-1\right\}$.

### 4.2 The Algorithm of Building Simplest SAT Model for Matsui's Bounding Conditions

When searching the best trail of $R$-round ciphers, we know the Matsui's probability bounds $P_{\text {opt }}(i), 1 \leq i \leq R-1$ and the initial estimation for the probability bound of $R$-round trail $P_{\text {ini }}(R)$. According to Theorem 2, we can get a bounding conditions set denoted as $C$ which can utilize all the information provided by $\left\{P_{\text {ini }}(R), P_{\text {opt }}(i), 1 \leq i \leq R-1\right\}$. According to Corollary 3 , if we get all the accurate bounds of partial sum $\sum_{i=0}^{e_{2}} w_{i}, 0 \leq e_{2} \leq n-1$ under the constraints of $C$, then we can get the simplest model of combining Matsui's bounding conditions set with sequential encoding method. In order to get the accurate lower bounds and upper bounds of $\sum_{i=0}^{e_{2}} w_{i}, 0 \leq e_{2} \leq n-1$, we will build some MILP models. Here, we give the framework of getting the accurate bounds in Algorithm 1.

For usual ciphers, because the number of variables and constrains in Algorithm 1 is small, the time needed to solve these models is little. Therefore, for all partial sums $\sum_{i=0}^{e_{2}} w_{i}, 0 \leq e_{2} \leq n-1$, we can use Algorithm 1 to get their accurate lower and upper bounds. Then, according to Theorem 3, the simplest SAT model of combining Matsui's bounding conditions and sequential encoding method can be obtained. And we can use it to search the best trails of $R$-round ciphers.

## 5 Applications to Block Ciphers

In this section, we apply the method for building simplest SAT model of combining Matsui's bounding conditions with sequential encoding method to several block ciphers. And we give a comparison with the primitive method of combining Matsui's bounding conditions with sequential encoding method proposed by Sun et al. [SWW21] on the number of variables, clauses and solving time. In order

```
Algorithm 1 Bound \(\left(C, w, \sum_{i=0}^{e_{2}} w_{i}\right)\)
    Input: The bounding conditions set \(C\);
            The probability weight variables \(w\);
            The partial sum \(\sum_{i=0}^{e_{2}} w_{i}\).
    Output: The accurate lower bound \(l_{0, e_{2}}\) and upper bound \(m_{0, e_{2}}\) of \(\sum_{i=0}^{e_{2}} w_{i}\).
    Let \(\mathcal{M}_{l}\) be an empty MILP model
    for \(c\) in \(C\) do
        \(\mathcal{M}_{l}\).addConstr ( \(c\) )
    \(\mathcal{M}_{l}\).setObjective( \(\sum_{i=0}^{e_{2}} w_{i}\),GRB.MINIMIZE)
    \(l_{0, e_{2}}=\mathcal{M}_{l}\).optimize()
    Let \(\mathcal{M}_{m}\) be an empty MILP model
    for \(c\) in \(C\) do
            \(\mathcal{M}_{m}\).addConstr (c)
    \(\mathcal{M}_{m}\).setObjective( \(\sum_{i=0}^{e_{2}} w_{i}\),GRB.MAXIMIZE)
    \(m_{0, e_{2}}=\mathcal{M}_{m}\).optimize()
    1 return \(\left(l_{0, e_{2}}, m_{0, e_{2}}\right)\)
```

to make the comparison as fair as possible, we implement the two methods on the same platform (a PC with AMD Ryzen 9 5950X 16-Core 3.4 GGHz ) and the same SAT solver (CaDiCal [Bie19]).

### 5.1 Description of Some Block Ciphers

SPN Ciphers. PRESENT [BKL $\left.{ }^{+} 07\right]$ has an SPN structure and uses 80and 128-bit keys with 64 -bit blocks through 31 rounds. In order to improve the hardware efficiency, it use a fully wired diffusion layer. RECTANGLE [ZBL+ ${ }^{+}$15] is very like PRESENT. It is a 25 -round SPN cipher with the 64 -bit block size. As an improved version of PRESENT, GIFT $\left[\mathrm{BPP}^{+} 17\right]$ is composed of two versions. GIFT-64 is a 28 -round SPN cipher with the 64 -bit block size, and GIFT-128 is a 40 -round SPN cipher with the 128 -bit block size.

Feistel Ciphers. LBlock [WZ11] is a lightweight block cipher proposed by Wu and Zhang. The block size is 64 bits and the key size is 80 bits. It employs a variant Feistel structure and consists of 32 rounds. And TWINE [SMMK12] is a 64 -bit lightweight block cipher supporting 80 - and 128 -bit keys. It has the alike structure as LBlock and consists of 36 rounds.

ARX Ciphers. SPECK $\left[\mathrm{BSS}^{+} 13\right]$ is a family of lightweight block ciphers published by National Security Agency (NSA). It adopts ARX structure which takes the modular addition as its nonlinear operation. According to block size, SPECK family of ciphers are composed of SPECK2n, where $n \in\{16,24,32,48,64\}$.

### 5.2 The Results of Applications

In order to better illustrate our results, the following notations are introduced.

- $M_{\text {sun }}$ : the method proposed by Sun el al. [SWW21].
- $M_{\text {sim }}$ : the simplest method proposed in Sect. 4.
- Var, Cnf, $T^{s o l}$ : the number of variables, clauses and solving time of models.
$-K_{v a r}=\frac{V a r_{s i m}}{V a r_{s u n}}:$ The ratio of the total number of variables.
- $K_{c n f}=\frac{C n f_{s i m}}{C n f_{s u n}}$ : The ratio of the total number of clauses.
$-K_{\text {sol }}=\frac{T_{\text {sion }}^{\text {sio }}}{T_{\text {sun }}}$ : The ratio of the total solving time of models.
- $P_{\text {opt }}$ : the optimal probability of differential trails.
- Cor opt: the optimal correlation of linear trails.

We apply the two methods $M_{\text {sun }}$ and $M_{\text {sim }}$ to the above SPN, Feistel and ARX ciphers to searching their optimal differential probabilities and linear correlations. The detailed results are shown in Table 4-14 in the Appendix. The comparison of the two methods on the total number of variables, clauses and solving time of models are presented in Table 2. According to the results, our method have greater advantages. Take PRESENT as an example, when searching the optimal differential probabilities of every round from 1 to 31, the total number of variables, clauses and the time of solving SAT models needed by our method is only $7.1 \%, 11.1 \%$ and $36.6 \%$ of the method $M_{\text {sun }}$, respectively.

Table 2. The comparison results of the two methods

| Cipher | Total round | Property | $K_{\text {var }}$ | $K_{\text {cnf }}$ | $K_{\text {sol }}$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| PRESENT | 31 (Full) | differential | 7.1\% | 11.1\% | 36.6\% |
|  |  | linear | 2.0\% | 4.7\% | 46.6\% |
| RECTANGLE | 25 (Full) | differential | 16.2\% | 20.0\% | $35.0 \%$ |
|  |  | linear | 14.1\% | 27.4\% | 94.0\% |
| GIFT64 | 28 (Full) | differential | 8.7\% | 12.3\% | 44.8\% |
|  |  | linear | 19.0\% | 24.1\% | 94.7\% |
| GIFT128 | 29 | differential | 19.0\% | 22.9\% | 30.7\% |
|  | 25 | linear | 24.2\% | 28.5\% | 61.2\% |
| LBlock | 32 (Full) | differential | 18.8\% | 52.5\% | 52.0\% |
|  |  | linear | 18.0\% | 31.8\% | 58.7\% |
| TWINE | 36 (Full) | differential | 14.4\% | 19.6\% | 45.5\% |
|  |  | linear | 18.0\% | 30.8\% | 60.0\% |
| SPECK32 | 22 (Full) | differential | 23.0\% | 28.5\% | 69.0\% |
|  |  | linear | 32.8\% | 43.0\% | 89.5\% |
| SPECK48 | 18 | differential | 22.1\% | 33.5\% | 84.0\% |
|  | 23 (Full) | linear | 29.9\% | 39.5\% | 67.0\% |
| SPECK64 | 27 (Full) | differential | 18.3\% | 22.7\% | 76.5\% |
|  |  | linear | 24.9\% | 34.2\% | 69.3\% |
| SPECK96 | 10 | differential | 49.3\% | 54.5\% | 82.7\% |
|  | 14 | linear | 47.2\% | 56.7\% | 67.8\% |
| SPECK128 | 9 | differential | 51.8\% | 57.8\% | 90.3\% |
|  | 10 | linear | 59.7\% | 68.3\% | 71.8\% |

For PRESENT, RECTANGLE, GIFT64, LBlock, TWINE, SPECK32 and SPECK64, all the optimal differential probabilities and linear correlations of the
full-round ciphers have been obtained. For GIFT128, SPECK48, SPECK96 and SPECK128, our method $M_{\text {sim }}$ finds some new differential probabilities or linear correlations covering more rounds which are listed Table 3.

Table 3. New optimal differential probabilities and linear correlations

| Differential Property |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Cipher | Round | $\log _{2}^{\text {Popt }}$ | Var | Cnf | $T^{\text {sol }}$ |
| GIFT128 | 30 | -193 | 838882 | 2119484 | 1548721.8 s |
| GIFT128 | 31 | -198.415 | 473100 | 1176426 | 137815.9s |
| GIFT128 | 32 | -204.415 | 527361 | 1331711 | 191841.5s |
| GIFT128 | 33 | -210.415 | 523013 | 1331731 | 200005.4s |
| GIFT128 | 34 | -217.415 | 607170 | 1550500 | 242581.9s |
| GIFT128 | 35 | -224.83 | 627866 | 1601828 | 211591.8s |
| GIFT128 | 36 | -234.415 | 947853 | 2384355 | 1191166.5s |
| GIFT128 | 37 | -240.415 | 642079 | 1604643 | 258131.2s |
| GIFT128 | 38 | -246.415 | 633699 | 1596599 | 313064.2 s |
| GIFT128 | 39 | -253.415 | 729939 | 1845704 | 115049.5s |
| GIFT128 | 40 | -260.415 | 644931 | 1633919 | 474680.7s |
| SPECK48 | 19 | -89 | 68632 | 177696 | 1736050.9s |
| Linear Property |  |  |  |  |  |
| Cipher | Round | $\log _{2}^{\text {Cor opt }}$ | Var | Cnf | $T^{s}$ |
| GIFT128 | 26 | -91 | 147345 | 379885 | 3580030.2s |
| GIFT128 | 27 | -94 | 91807 | 236723 | 2274569.6s |
| SPECK96 | 15 | -43 | 50325 | 165960 | 268094.1s |
| SPECK128 | 11 | -31 | 55745 | 175540 | 939954.9s |

## 6 Conclusion

In this paper, we aim at finding a better way of combining Matsui's bounding conditions with sequential encoding method. By quantifying the effect of bounding conditions, the general form of inequality constraint which can utilized all the information provided by Matsui's bounding conditions are proposed. Because the values of some auxiliary boolean variables in sequential encoding method can be determined, we proposed a new method of integrating bounding conditions into SAT model. Different from the previous methods, our new method can realize the bounding conditions by removing variables and clauses. In order to accelerate the search efficiency, the algorithm for building the simplest SAT model of combining Matsui's bounding conditions with sequential encoding method is proposed. When applying our new method to searching the optimal differential probability and linear correlation of block ciphers, the total number of variables, clauses and solving time of SAT models are decreased. And we find some new differential and linear characteristics covering more round. As a result, we obtain a more efficient search tool.

Because our method of combining bounding condition with sequential encoding method is general, it can be used to search other kinds of distinguishers for ciphers. The wide applications will be done in the future. And for GIFT128, SPECK48, SPECK96 and SPECK128, some optimal differential probabilities or linear correlations of the full round cipher can not be obtained by the existing methods. How to speed up the search of these ciphers is a problem worth studying.

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## ${ }_{827}$ Appendix

Table 4. Experimental results of PRESENT

| Differential Property |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Round | $\log _{2} P_{\text {opt }}$ | $M_{\text {sun }}$ |  |  | $M_{\text {sim }}$ |  |  |
|  |  | Var | Cnf | $T^{\text {sol }}$ | Var | Cnf | $T^{\text {sol }}$ |
| 1 | -2 | 669 | 3112 | 0.1s | 667 | 3059 | 0.1 s |
| 2 | -4 | 668 | 2659 | 0.1s | 472 | 2217 | 0.1s |
| 3 | -8 | 4203 | 14763 | 0.2 s | 2443 | 10799 | 0.2 s |
| 4 | -12 | 7839 | 24564 | 0.3 s | 3739 | 15479 | 0.3 s |
| 5 | -20 | 32809 | 92575 | 3.7s | 14973 | 53459 | 2.4 s |
| 6 | -24 | 22011 | 58386 | 2.2 s | 8491 | 29135 | 1.1 s |
| 7 | -28 | 29679 | 76683 | 2.4 s | 9211 | 32663 | 1.7 s |
| 8 | -32 | 38499 | 97428 | 2.8 s | 9931 | 36191 | 1.5 s |
| 9 | -36 | 48471 | 120621 | 3.0 s | 10651 | 39719 | 1.0 s |
| 10 | -41 | 80418 | 196930 | 3.9 s | 8999 | 31662 | 1.6 s |
| 11 | -46 | 98990 | 238786 | 8.1s | 14923 | 52427 | 2.4 s |
| 12 | -52 | 150790 | 358715 | 32.4 s | 28420 | 97945 | 9.7s |
| 13 | -56 | 107355 | 252813 | 5.4s | 18889 | 64523 | 3.3 s |
| 14 | -62 | 209460 | 489035 | 28.9 s | 35040 | 118125 | 16.7 s |
| 15 | -66 | 145437 | 337053 | 10.0 s | 22861 | 76631 | 3.1s |
| 16 | -70 | 164337 | 379110 | 18.8 s | 22717 | 78431 | 2.1 s |
| 17 | -74 | 184389 | 423615 | 8.3s | 22573 | 80231 | 2.3 s |
| 18 | -78 | 205593 | 470568 | 6.4 s | 22429 | 82031 | 2.5 s |
| 19 | -82 | 227949 | 519969 | 5.1s | 8334 | 29753 | 1.3 s |
| 20 | -86 | 251457 | 571818 | 7.1 s | 8334 | 30449 | 1.3 s |
| 21 | -90 | 276117 | 626115 | 7.6 s | 8334 | 31145 | 1.3 s |
| 22 | -96 | 508490 | 1148645 | 15.6 s | 28141 | 101795 | 4.0 s |
| 23 | -100 | 335511 | 755283 | 11.8 s | 27697 | 102995 | 4.6 s |
| 24 | -106 | 612280 | 1374005 | 33.3s | 34129 | 117935 | 16.6 s |
| 25 | -110 | 400665 | 896547 | 17.2s | 33397 | 118559 | 4.9 s |
| 26 | -116 | 725670 | 1619525 | 60.0s | 40117 | 134075 | 36.3 s |
| 27 | -120 | 471579 | 1049907 | 31.8 s | 39097 | 134123 | 12.5 s |
| 28 | -124 | 505167 | 1123068 | 20.8 s | 14034 | 47405 | 1.4 s |
| 29 | -128 | 539907 | 1198677 | 18.2 s | 13746 | 47525 | 2.3 s |
| 30 | -132 | 575799 | 1276734 | 19.1s | 13458 | 47645 | 4.9 s |
| 31 | -136 | 612843 | 1357239 | 18.3 s | 13170 | 47765 | 3.5 s |
| Total |  | 7575051 | 17154948 | 403.0s | 539417 | 1895896 | 147.3 s |
| Linear Property |  |  |  |  |  |  |  |
| Round | $\log _{2}$ Cor $_{\text {opt }}$ | $M_{\text {sun }}$ |  |  | $M_{\text {sim }}$ |  |  |
|  |  | Var | Cnf | $T^{\text {sol }}$ | Var | Cnf | $T^{\text {sol }}$ |
| 1 | -1 | 351 | 1790 | 0.6s | 351 | 1758 | 0.1s |
| 2 | -2 | 382 | 1977 | 0.4 s | 318 | 1817 | 0.1 s |
| 3 | -4 | 1369 | 6599 | 0.7 s | 983 | 5634 | 0.1 s |
| 4 | -6 | 2293 | 9945 | 0.7 s | 1391 | 7754 | 0.1 s |
| 5 | -8 | 3473 | 13867 | 0.7s | 1799 | 9874 | 0.2 s |
| 6 | -10 | 4909 | 18365 | 1.0 s | 2207 | 11994 | 0.3 s |
| 7 | -12 | 6601 | 23439 | 1.2 s | 2615 | 14114 | 0.4 s |
| 8 | -14 | 8549 | 29089 | 1.0 s | 3023 | 16234 | 0.4 s |
| 9 | -16 | 10753 | 35315 | 1.1 s | 3431 | 18354 | 0.7 s |
| 10 | -18 | 13213 | 42117 | 1.3 s | 3839 | 20474 | 0.8 s |
| 11 | -20 | 15929 | 49495 | 1.7 s | 4247 | 22594 | 0.6 s |
| 12 | -22 | 18901 | 57449 | 2.1s | 4655 | 24714 | 1.1 s |
| 13 | -24 | 22129 | 65979 | 2.2 s | 5063 | 26834 | 0.8 s |
| 14 | -26 | 25613 | 75085 | 2.5 s | 5471 | 28954 | 0.9 s |
| 15 | -28 | 29353 | 84767 | 2.8 s | 5879 | 31074 | 1.1s |
| 16 | -30 | 33349 | 95025 | 2.7s | 6287 | 33194 | 1.6 s |
| 17 | -32 | 37601 | 105859 | 5.0s | 6695 | 35314 | 1.9 s |
| 18 | -34 | 42109 | 117269 | 3.5 s | 7103 | 37434 | 2.1 s |
| 19 | -36 | 46873 | 129255 | 5.3 s | 7511 | 39554 | 1.6 s |
| 20 | -38 | 51893 | 141817 | 5.5 s | 7919 | 41674 | 1.7 s |
| 21 | -40 | 57169 | 154955 | 3.4 s | 8327 | 43794 | 2.2 s |
| 22 | -42 | 62701 | 168669 | 6.0 s | 8735 | 45914 | 2.2 s |
| 23 | -44 | 68489 | 182959 | 6.3 s | 9143 | 48034 | 3.0 s |
| 24 | -45 | 74533 | 197825 | 7.7s | 9551 | 50154 | 3.3 s |
| 25 | -48 | 80833 | 213267 | 8.0 s | 9959 | 52274 | 3.6 s |
| 26 | -50 | 87389 | 229285 | 8.8 s | 10367 | 54394 | 3.7 s |
| 27 | -52 | 94201 | 245879 | 8.9 s | 10775 | 56514 | 4.6 s |
| 28 | -54 | 101269 | 263049 | 8.5 s | 11183 | 58634 | 5.1s |
| 29 | -56 | 108593 | 280795 | 9.3s | 11591 | 60754 | 3.7s |
| 30 | -58 | 116173 | 299117 | 10.0 s | 11999 | 62874 | 4.9 s |
| 31 | -60 | 124009 | 318015 | 14.1 s | 12407 | 64994 | 9.5 s |
| Total |  | 9731820 | 22048710 | 133.3 s | 194824 | 1027681 | 62.1 s |

Table 5. Experimental results of RECTANGLE

| Differential Property |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Round | $\log _{2} P_{\text {opt }}$ | $M_{\text {sun }}$ |  |  | $M_{\text {sim }}$ |  |  |
|  |  | Var | Cnf | $T^{\text {sol }}$ | Var | Cnf | $T^{\text {sol }}$ |
| 1 | -2 | 669 | 2392 | 2.9 s | 667 | 2339 | 1.1s |
| 2 | -4 | 668 | 2179 | 0.4 s | 472 | 1737 | 0.3 s |
| 3 | -7 | 2659 | 8117 | 0.8 s | 1491 | 5486 | 0.7s |
| 4 | -10 | 4653 | 13313 | 1.2 s | 2129 | 7678 | 0.7 s |
| 5 | -14 | 11193 | 30351 | 1.3 s | 4501 | 15503 | 1.1s |
| 6 | -18 | 16845 | 43752 | 1.7s | 6085 | 20039 | 1.1s |
| 7 | -25 | 50313 | 125223 | 7.6s | 18281 | 55018 | 5.0s |
| 8 | -31 | 60335 | 145130 | 15.8 s | 21455 | 60545 | 9.9 s |
| 9 | -36 | 63766 | 150466 | 18.8 s | 20654 | 57228 | 14.1 s |
| 10 | -41 | 80418 | 187330 | 23.0 s | 23402 | 64540 | 16.6 s |
| 11 | -46 | 98990 | 228226 | 70.5 s | 26150 | 71852 | 42.8 s |
| 12 | -51 | 119482 | 273154 | 103.0s | 28898 | 79164 | 27.1 s |
| 13 | -56 | 141894 | 322114 | 227.8 s | 31646 | 86476 | 52.7 s |
| 14 | -61 | 166226 | 375106 | 140.7 s | 34394 | 93788 | 57.1 s |
| 15 | -66 | 192478 | 432130 | 256.9 s | 37142 | 101100 | 58.8 s |
| 16 | -71 | 220650 | 493186 | 203.8s | 39890 | 108412 | 75.2 s |
| 17 | -76 | 250742 | 558274 | 354.1 s | 42638 | 115724 | 76.6 s |
| 18 | -81 | 282754 | 627394 | 242.8 s | 45386 | 123036 | 98.5 s |
| 19 | -86 | 316686 | 700546 | 287.3 s | 48134 | 130348 | 132.7 s |
| 20 | -91 | 352538 | 777730 | 406.6 s | 50882 | 137660 | 137.9 s |
| 21 | -96 | 390310 | 858946 | 479.1s | 53630 | 144972 | 106.8 s |
| 22 | -101 | 430002 | 944194 | 497.5 s | 56378 | 152284 | 111.5 s |
| 23 | -106 | 471614 | 1033474 | 335.0s | 59126 | 159596 | 175.3 s |
| 24 | -111 | 515146 | 1126786 | 560.1 s | 61874 | 166908 | 170.5 s |
| 25 | -116 | 560598 | 1224130 | 621.7 s | 64622 | 174220 | 324.8s |
| Total |  | 4801629 | 10683643 | 4860.6 s | 779927 | 2135653 | 1698.9s |
| Linear Property |  |  |  |  |  |  |  |
| Round | $\log _{2}$ Cor $_{\text {opt }}$ | $M_{\text {sun }}$ |  |  | $M_{\text {sim }}$ |  |  |
|  |  | Var | Cnf | $T^{\text {sol }}$ | Var | Cnf | $T^{\text {sol }}$ |
| 1 | -1 | 367 | 1246 | 1.6 s | 351 | 1214 | 0.9 s |
| 2 | -2 | 446 | 1433 | 0.7s | 318 | 1273 | 0.4 s |
| 3 | -4 | 1705 | 4967 | 1.4 s | 983 | 4002 | 0.7 s |
| 4 | -6 | 2997 | 7769 | 1.2 s | 1391 | 5578 | 0.8 s |
| 5 | -8 | 4673 | 11147 | 1.3 s | 1799 | 7154 | 0.7 s |
| 6 | -10 | 6733 | 15101 | 1.3 s | 2207 | 8730 | 1.0 s |
| 7 | -13 | 14268 | 30114 | 3.6s | 4252 | 16115 | 2.5 s |
| 8 | -16 | 19731 | 39396 | 6.6 s | 5473 | 19691 | 4.5 s |
| 9 | -19 | 26058 | 49926 | 9.8 s | 6694 | 23267 | 10.8 s |
| 10 | -22 | 33249 | 61704 | 20.9s | 7915 | 26843 | 21.6 s |
| 11 | -25 | 41304 | 74730 | 48.2 s | 9136 | 30419 | 44.1 s |
| 12 | -28 | 50223 | 89004 | 104.5 s | 10357 | 33995 | 74.6 s |
| 13 | -31 | 60006 | 104526 | 234.6 s | 11578 | 37571 | 220.5 s |
| 14 | -34 | 70653 | 121296 | 292.6 s | 12799 | 41147 | 271.6 s |
| 15 | -37 | 82164 | 139314 | 380.6 s | 14020 | 44723 | 429.5 s |
| 16 | -40 | 94539 | 158580 | 1073.8 s | 15241 | 48299 | 778.5 s |
| 17 | -42 | 71037 | 118311 | 368.5 s | 10435 | 33506 | 205.9s |
| 18 | -45 | 119292 | 197409 | 507.8s | 16162 | 52415 | 875.7 s |
| 19 | -48 | 134115 | 220227 | 1286.6s | 17479 | 56183 | 1150.2s |
| 20 | -51 | 149802 | 244293 | 1312.7 s | 18796 | 59951 | 1081.4s |
| 21 | -54 | 166353 | 269607 | 1214.7 s | 20113 | 63719 | 1265.1s |
| 22 | -57 | 183768 | 296169 | 1467.1s | 21430 | 67487 | 1363.2s |
| 23 | -60 | 202047 | 323979 | 1781.8 s | 22747 | 71255 | 1745.2s |
| 24 | -63 | 221190 | 353037 | 1884.8 s | 24064 | 75023 | 1888.6s |
| 25 | -66 | 241197 | 383343 | 5480.7s | 25381 | 78791 | 5008.5s |
| Total |  | 1997917 | 3316628 | 17487.4s | 281121 | 908351 | 16446.6s |

Table 6. Experimental results of GIFT64

| Differential Property |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Round | $\log _{2} P_{\text {opt }}$ | $M_{\text {sun }}$ |  |  | $M_{\text {sim }}$ |  |  |
|  |  | Var | $C n f$ | $T^{\text {sol }}$ | Var | Cnf | $T^{\text {sol }}$ |
| 1 | -1.415 | 590 | 2747 | 0.3 s | 590 | 2699 | 0.2 s |
| 2 | -3.415 | 1560 | 6677 | 0.3 s | 1268 | 5947 | 0.2 s |
| 3 | -7 | 4554 | 16630 | 0.5 s | 2990 | 12916 | 0.3 s |
| 4 | -11.415 | 11663 | 36670 | 3.2 s | 6281 | 24437 | 0.5 s |
| 5 | -17 | 28744 | 81820 | 15.5 s | 13678 | 48259 | 2.4 s |
| 6 | -22.415 | 38950 | 103956 | 33.8 s | 16090 | 53830 | 19.4 s |
| 7 | -28.415 | 65899 | 168535 | 110.9s | 24275 | 78099 | 66.7s |
| 8 | -38 | 136625 | 334925 | 433.1 s | 49795 | 147570 | 343.9 s |
| 9 | -42 | 73534 | 175738 | 74.6 s | 23962 | 69556 | 25.8 s |
| 10 | -48 | 136911 | 323127 | 191.0s | 38249 | 112630 | 62.1 s |
| 11 | -52 | 110934 | 259130 | 33.0 s | 26634 | 79812 | 43.5 s |
| 12 | -58 | 198771 | 460311 | 189.2 s | 42257 | 128014 | 54.8 s |
| 13 | -62 | 156014 | 358650 | 56.6 s | 29306 | 90068 | 20.7s |
| 14 | -68 | 272151 | 621687 | 70.7s | 46265 | 143398 | 60.1s |
| 15 | -72 | 208774 | 474298 | 46.8 s | 31978 | 100324 | 5.1 s |
| 16 | -78 | 357051 | 807255 | 107.8 s | 28561 | 86231 | 38.6 s |
| 17 | -82 | 269214 | 606074 | 51.2 s | 27205 | 85367 | 13.7 s |
| 18 | -88 | 453471 | 1017015 | 119.7 s | 30997 | 94787 | 56.1s |
| 19 | -92 | 337334 | 753978 | 59.5 s | 29353 | 93347 | 34.6s |
| 20 | -98 | 561411 | 1250967 | 133.5 s | 33433 | 103343 | 59.6 s |
| 21 | -102 | 413134 | 918010 | 82.6 s | 31501 | 101327 | 16.2 s |
| 22 | -108 | 680871 | 1509111 | 125.7 s | 35869 | 111899 | 75.3 s |
| 23 | -112 | 496614 | 1098170 | 87.5 s | 33649 | 109307 | 35.5 s |
| 24 | -118 | 811851 | 1791447 | 239.1 s | 38305 | 120455 | 142.2 s |
| 25 | -122 | 587774 | 1294458 | 120.8 s | 35797 | 117287 | 40.4 s |
| 26 | -128 | 954351 | 2097975 | 251.9 s | 40741 | 129011 | 137.8 s |
| 27 | -132 | 686614 | 1506874 | 155.6 s | 37945 | 125267 | 11.8 s |
| 28 | -138 | 1108371 | 2428695 | 365.3s | 43177 | 137567 | 100.2 s |
| Total |  | 9163735 | 20504930 | 3160.9s | 800151 | 2512754 | 1416.4 s |

Linear Property

| Round | $\log _{2}$ Cor $_{\text {opt }}$ | $M_{\text {sun }}$ |  |  | $M_{\text {sim }}$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Var | $C n f$ | $T^{\text {sol }}$ | Var | $C n f$ | $T^{\text {sol }}$ |
| 1 | -1 | 351 | 1150 | 1.1s | 351 | 1118 | 0.8 s |
| 2 | -2 | 382 | 1337 | 0.3 s | 318 | 1177 | 0.4 s |
| 3 | -3 | 637 | 2245 | 0.4 s | 445 | 1765 | 0.4 s |
| 4 | -5 | 2039 | 6879 | 0.8 s | 1269 | 4954 | 0.7s |
| 5 | -7 | 3155 | 10033 | 0.8s | 1741 | 6562 | 0.8 s |
| 6 | -10 | 7077 | 21216 | 1.5 s | 3601 | 12815 | 1.5 s |
| 7 | -13 | 10236 | 29106 | 2.3 s | 4822 | 16247 | 2.2 s |
| 8 | -16 | 13971 | 38244 | 4.5 s | 6043 | 19679 | 3.7 s |
| 9 | -20 | 24950 | 65986 | 27.2 s | 10250 | 31940 | 18.8 s |
| 10 | -25 | 41805 | 106810 | 218.3 s | 16955 | 49845 | 182.2 s |
| 11 | -29 | 43090 | 107342 | 592.1 s | 16742 | 47540 | 460.1 s |
| 12 | -31 | 25795 | 63539 | 175.1s | 8893 | 25474 | 166.5 s |
| 13 | -34 | 45021 | 110115 | 218.2 s | 13705 | 39935 | 215.0 s |
| 14 | -37 | 52500 | 127317 | 250.5 s | 14638 | 42791 | 208.2 s |
| 15 | -40 | 60555 | 145767 | 500.8 s | 15571 | 45647 | 345.1 s |
| 16 | -43 | 69186 | 165465 | 462.0 s | 16504 | 48503 | 344.2 s |
| 17 | -46 | 78393 | 186411 | 351.7s | 17437 | 51359 | 357.0 s |
| 18 | -49 | 88176 | 208605 | 256.1s | 18370 | 54215 | 221.0s |
| 19 | -52 | 98535 | 232047 | 241.0s | 19303 | 57071 | 330.8 s |
| 20 | -55 | 109470 | 256737 | 227.0s | 20236 | 59927 | 214.9 s |
| 21 | -58 | 120981 | 282675 | 266.9s | 21169 | 62783 | 338.5 s |
| 22 | -61 | 133068 | 309861 | 253.0s | 22102 | 65639 | 307.0 s |
| 23 | -64 | 145731 | 338295 | 309.1s | 23035 | 68495 | 310.4 s |
| 24 | -67 | 158970 | 367977 | 271.8 s | 23968 | 71351 | 225.8 s |
| 25 | -70 | 172785 | 398907 | 264.5 s | 24901 | 74207 | 456.5 s |
| 26 | -73 | 187176 | 431085 | 283.2 s | 25834 | 77063 | 260.3 s |
| 27 | -76 | 202143 | 464511 | 285.6s | 26767 | 79919 | 262.8 s |
| 28 | -79 | 217686 | 499185 | 311.7s | 27700 | 82775 | 237.5 s |
| Total |  | 2113864 | 4978847 | 5777.5 s | 402670 | 1200796 | 5473.2 s |

Table 7. Experimental results of GIFT128

| Differential Property |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Round | $\log _{2} P_{\text {opt }}$ | $M_{\text {sun }}$ |  |  | $M_{\text {sim }}$ |  |  |
|  |  | Var | Cnf | $T^{\text {sol }}$ | Var | Cnf | $T^{\text {sol }}$ |
| 1 | -1.415 | 1182 | 5499 | 0.2 s | 1182 | 5403 | 0.2 s |
| 2 | -3.415 | 3128 | 13381 | 0.2 s | 2548 | 11931 | 0.2 s |
| 3 | -7 | 11939 | 42911 | 0.7s | 8057 | 33693 | 0.5 s |
| 4 | -11.415 | 23375 | 73502 | 1.5 s | 12713 | 49269 | 1.4 s |
| 5 | -17 | 48201 | 137955 | 7.9s | 22631 | 80998 | 6.9 s |
| 6 | -22.415 | 78022 | 208308 | 19.7s | 32698 | 108934 | 17.8 s |
| 7 | -28.415 | 131979 | 337655 | 98.1s | 49363 | 158179 | 83.3 s |
| 8 | -39 | 305162 | 746449 | 3832.1 s | 115588 | 337447 | 2553.6 s |
| 9 | -45.415 | 272180 | 645604 | 2657.7 s | 98536 | 273887 | 1867.7s |
| 10 | -49.415 | 239761 | 562598 | 542.7 s | 72419 | 206125 | 201.9 s |
| 11 | -54.415 | 345062 | 802966 | 726.5 s | 87710 | 256334 | 115.0 s |
| 12 | -60.415 | 483563 | 1114804 | 2172.2 s | 110573 | 324151 | 229.8 s |
| 13 | -67.83 | 664028 | 1515923 | 7202.8 s | 145314 | 418180 | 1015.5 s |
| 14 | -79 | 1218318 | 2747022 | 154725.1s | 316984 | 856761 | 29013.6s |
| 15 | -85.415 | 856156 | 1912402 | 82353.6s | 204874 | 538803 | 16675.4 s |
| 16 | -90.415 | 833262 | 1854320 | 23703.7s | 176946 | 472134 | 2261.1 s |
| 17 | -96.415 | 1095855 | 2430141 | 28299.3 s | 209023 | 564547 | 6249.6 s |
| 18 | -103.415 | 1416604 | 3128587 | 98258.3 s | 255346 | 687908 | 10032.7s |
| 19 | -110.83 | 1597380 | 3513947 | 153129.3s | 277578 | 742308 | 10794.1s |
| 20 | -121.415 | 2729099 | 5973181 | 2679475.9s | 495133 | 1285212 | 544635.4 s |
| 21 | -126.415 | 1528822 | 3334794 | 128549.4s | 272002 | 699574 | 29560.2 s |
| 22 | -132.415 | 1950067 | 4246118 | 87235.3s | 314263 | 818523 | 19879.2s |
| 23 | -139.415 | 2444925 | 5311943 | 159346.3s | 272403 | 971688 | 48047.9s |
| 24 | -146.83 | 2680964 | 5811667 | 222371.8s | 394602 | 1026020 | 95098.1s |
| 25 | -157.415 | 4447707 | 9611825 | 2680211.5s | 680957 | 1731196 | 1021543.7s |
| 26 | -162.415 | 2431742 | 5244388 | 138927.1s | 367058 | 927014 | 72698.5 s |
| 27 | -168.415 | 3046199 | 6562735 | 284765.3s | 419503 | 1072499 | 128264.8s |
| 28 | -174.415 | 3271885 | 7041002 | 302579.7s | 419187 | 1080583 | 143142.4 s |
| 29 | -181.83 | 4018764 | 8637027 | 454797.7s | 490994 | 1268484 | 202086.2 s |
| Total |  | 38175331 | 83568654 | 7695991.6s | 7265067 | 19127269 | 2366197.5s |
| 30 | -193 | - | - | - | 838882 | 2119484 | 1548721.8s |
| 31 | -198.415 | - | - | - | 464358 | 1158942 | 137815.9s |
| 32 | -204.415 | - | - | - | 527361 | 1331711 | 191841.5s |
| 33 | -210.415 | - | - | - | 523013 | 1331731 | 200005.4s |
| 34 | -217.415 | - | - | - | 607170 | 1550500 | 242581.9s |
| 35 | -224.83 | - | - | - | 627866 | 1601828 | 211591.8s |
| 36 | 234.415 | - | - | - | 947853 | 2384355 | 1191166.5s |
| 37 | 240.415 | - | - | - | 642079 | 1604643 | 258131.2s |
| 38 | 246.415 | - | - | - | 633699 | 1596599 | 313064.2 s |
| 39 | 253.415 | - | - | - | 729939 | 1845704 | 115049.5s |
| 40 | 260.415 | - | - | - | 644931 | 1633919 | 474680.7s |
| Linear Property |  |  |  |  |  |  |  |
| Round | $\log _{2}$ Cor $_{\text {opt }}$ | $M_{\text {sun }}$ |  |  | $M_{\text {sim }}$ |  |  |
|  |  | Var | Cnf | $T^{\text {sol }}$ | Var | Cnf | $T^{\text {sol }}$ |
| 1 | -1 | 703 | 2302 | 1.0 s | 703 | 2238 | 0.8 s |
| 2 | -2 | 766 | 2681 | 0.4 s | 638 | 2361 | 0.5 s |
| 3 | -3 | 1277 | 4501 | 0.4 s | 893 | 3541 | 0.4 s |
| 4 | -5 | 4087 | 13791 | 0.9 s | 2549 | 9946 | 1.0s |
| 5 | -7 | 6323 | 20113 | 1.0 s | 3501 | 13186 | 1.3 s |
| 6 | -10 | 14181 | 42528 | 2.1s | 7249 | 25775 | 1.9 s |
| 7 | -13 | 20508 | 58338 | 4.8 s | 9718 | 32711 | 4.6 s |
| 8 | -17 | 38338 | 104234 | 24.0 s | 17262 | 54884 | 25.9 s |
| 9 | -22 | 66780 | 173900 | 234.0 s | 29480 | 87725 | 224.1s |
| 10 | -26 | 70814 | 178870 | 640.3 s | 29642 | 84948 | 721.0 s |
| 11 | -31 | 113135 | 279355 | 4804.3 s | 44955 | 125305 | 5587.3 s |
| 12 | -36 | 142550 | 345035 | 28270.0s | 54430 | 147565 | 25064.7s |
| 13 | -38 | 67573 | 161991 | 5045.4 s | 23083 | 62978 | 1329.7s |
| 14 | -41 | 115848 | 276465 | 10202.9s | 24510 | 96239 | 7672.0s |
| 15 | -45 | 178898 | 423742 | 15362.0s | 49422 | 137796 | 15227.4 s |
| 16 | -48 | 153843 | 342028 | 10751.9s | 39427 | 110063 | 3818.8 s |
| 17 | -51 | 173226 | 405870 | 4591.6 s | 40360 | 113927 | 4207.0 s |
| 18 | -56 | 328690 | 765185 | 19648.9s | 74550 | 207765 | 20826.5 s |
| 19 | -59 | 222738 | 515616 | 9483.1 s | 48706 | 134603 | 13455.1s |
| 20 | -64 | 416330 | 958975 | 80615.3 | 88460 | 242225 | 63578.4 s |
| 21 | -68 | 373878 | 856594 | 148642.6s | 78746 | 212388 | 86316.8s |
| 22 | -74 | 629715 | 1434747 | 1931535.4s | 134681 | 355678 | 1278924.8s |
| 23 | -79 | 589055 | 1334575 | 1208961.7s | 129035 | 333305 | 691225.2 s |
| 24 | -82 | 387213 | 874722 | 206139.3s | 80821 | 208775 | 89751.8s |
| 25 | -86 | 560174 | 1262890 | 584729.2s | 109634 | 284772 | 305487.9s |
| Total |  | 4676643 | 10859048 | 4272597.4s | 1132455 | 3090699 | 2613454.2s |
| 26 | -91 | - | - | - | 147345 | 379885 | 3580030.2s |
| 27 | -94 | - | - | - | 91807 | 236723 | 2274569.6 s |

Table 8. Experimental results of LBlock

| Differential Property |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Round | $\log _{2} P_{\text {opt }}$ | $M_{\text {sun }}$ |  |  | $M_{\text {sim }}$ |  |  |
|  |  | Var | Cnf | $T^{\text {sol }}$ | Var | Cnf | $T^{\text {sot }}$ |
| 1 | 0 | 184 | 546 | 0.1s | 184 | 522 | 0.1s |
| 2 | -2 | 1053 | 3524 | 0.2 s | 1051 | 3401 | 0.2 s |
| 3 | -4 | 1911 | 6169 | 0.2 s | 1615 | 5360 | 0.2 s |
| 4 | -6 | 3057 | 9511 | 0.2 s | 2179 | 7319 | 0.2 s |
| 5 | -8 | 4491 | 13501 | 0.3 s | 2743 | 9278 | 0.2 s |
| 6 | -12 | 11070 | 31656 | 0.5 s | 6210 | 20115 | 0.5 s |
| 7 | -16 | 16210 | 44036 | 0.7s | 8410 | 25880 | 0.5 s |
| 8 | -22 | 32571 | 84505 | 1.8 s | 16149 | 46879 | 1.2 s |
| 9 | -28 | 45633 | 113891 | 2.8 s | 21609 | 59682 | 1.8 s |
| 10 | -36 | 80208 | 193906 | 5.0s | 36876 | 97323 | 3.4s |
| 11 | -44 | 107136 | 252370 | 8.5 s | 47748 | 121452 | 5.8 s |
| 12 | -48 | 73530 | 170916 | 4.0 s | 29770 | 75305 | 2.3 s |
| 13 | -56 | 160164 | 368326 | 13.3 s | 60420 | 151638 | 9.2 s |
| 14 | -62 | 150563 | 342553 | 14.1s | 53837 | 133497 | 10.0s |
| 15 | -66 | 124200 | 281046 | 9.2 s | 40110 | 100020 | 6.2 s |
| 16 | -72 | 198877 | 447903 | 13.4s | 58849 | 147315 | 11.4s |
| 17 | -76 | 161110 | 361336 | 11.7 s | 43690 | 109890 | 7.7s |
| 18 | -82 | 253911 | 567365 | 19.0 s | 63861 | 161133 | 12.8 s |
| 19 | -86 | 202820 | 451706 | 20.8 s | 47270 | 119760 | 13.6 s |
| 20 | -92 | 315665 | 700939 | 20.7s | 68873 | 174951 | 14.7 s |
| 21 | -96 | 249330 | 552156 | 11.7s | 50850 | 129630 | 6.5 s |
| 22 | -102 | 384139 | 848625 | 18.2 s | 73885 | 188769 | 11.6 s |
| 23 | -106 | 300640 | 662686 | 20.5 s | 54430 | 139500 | 9.7s |
| 24 | -112 | 459333 | 1010423 | 21.8 s | 78897 | 202587 | 9.7 s |
| 25 | -115 | 284202 | 624243 | 10.4s | 45218 | 117120 | 5.7 s |
| 26 | -121 | 536886 | 1177618 | 22.3 s | 79926 | 208453 | 12.1 s |
| 27 | -126 | 499251 | 1092904 | 36.3 s | 72563 | 188404 | 16.5 s |
| 28 | -131 | 537885 | 1175710 | 26.5 s | 74789 | 194482 | 10.8s |
| 29 | -135 | 479895 | 1047811 | 17.3 s | 62455 | 163690 | 8.4s |
| 30 | -141 | 720202 | 1570430 | 34.3 s | 90300 |  | 9.6 s |
| 31 | -146 | 662427 | 1442272 | 51.5 s | 81743 | 236789 | 18.5 s |
| 32 <br> Total | -151 |  | 1537174 | 49.2 s | 83969 | $\begin{array}{\|c\|} \hline 219346 \\ \hline 3772758 \\ \hline \end{array}$ | $\begin{array}{\|c\|} \hline 16.3 \mathrm{~s} \\ \hline 237.3 \mathrm{~s} \\ \hline \end{array}$ |
|  |  | 7765375 |  |  | 1460479 |  |  |
| Linear Property |  |  |  |  |  |  |  |
| Round | $\log _{2}$ Cor $_{\text {opt }}$ | $M_{\text {sun }}$ |  |  | $M_{\text {sim }}$ |  |  |
|  |  | Var | Cnf | $T^{\text {sol }}$ | Var | Cnf | $T^{\text {sol }}$ |
| 1 | 0 | 176 | 481 | 0.1s | 176 | 465 | 0.1 s |
| 2 | -1 | 623 | 1981 | 0.1s | 607 | 1918 | 0.1s |
| 3 | -2 | 1013 | 3156 | 0.1 s | 877 | 2934 | 0.1s |
| 4 | -3 | 1499 | 4524 | 0.1 s | 1147 | 3950 | 0.1s |
| 5 | -4 | 2081 | 6052 | 0.1 s | 1417 | 4966 | 0.1 s |
| 6 | -6 | 4353 | 11893 | 0.2 s | 2671 | 9251 | 0.2 s |
| 7 | -8 | 6051 | 15376 | 0.3 s | 3331 | 11279 | 0.3 s |
| 8 | -11 | 11098 | 26227 | 0.5 s | 5570 | 18236 | 0.5 s |
| 9 | -14 | 15038 | 33227 | 0.8 s | 6910 | 21852 | 0.8 s |
| 10 | -18 | 25040 | 52116 | 1.4 s | 10700 | 32605 | 1.3 s |
| 11 | -22 | 32780 | 64771 | 2.6 s | 13100 | 38565 | 2.2 s |
| 12 | -24 | 24027 | 46129 | 1.3s | 8737 | 25595 | 1.2 s |
| 13 | -27 | 37802 | 71199 | 3.2 s | 12554 | 36876 | 2.3 s |
| 14 | -30 | 44718 | 82487 | 2.8 s | 13830 | 40364 | 1.9 s |
| 15 | -33 | 52210 | 94607 | 3.7 s | 15106 | 43852 | 3.5 s |
| 16 | -36 | 60278 | 107559 | 7.8 s | 16382 | 47340 | 3.7s |
| 17 | -37 | 33647 | 59590 | 2.5 s | 8291 | 24342 | 1.7 s |
| 18 | -40 | 74694 | 131375 | 4.2 s | 16918 | 50300 | 2.4 s |
| 19 | -42 | 62541 | 109018 | 3.4 s | 13291 | 39635 | 2.4 s |
| 20 | -45 | 92562 | 160043 | 4.3 s | 18594 | 55532 | 3.1 s |
| 21 | -47 | 76662 | 131575 | 4.1s | 14548 | 43559 | 2.3 s |
| 22 | -50 | 112350 | 191527 | 5.1s | 20270 | 60764 | 3.1 s |
| 23 | -52 | 92223 | 156244 | 4.5 s | 15805 | 47483 | 2.4 s |
| 24 | -55 | 134058 | 225827 | 5.5 s | 21946 | 65996 | 3.6 s |
| 25 | -56 | 72217 | 121220 | 2.8 s | 10977 | 33478 | 1.8 s |
| 26 | -59 | 155194 | 259627 | 6.7 s | 22098 | 68188 | 2.1 s |
| 27 | -62 | 168926 | 280835 | 9.3 s | 23822 | 72572 | 6.9 s |
| 28 | -65 | 183234 | 302875 | 16.1 s | 25546 | 76956 | 5.2 s |
| 29 | -66 | 97669 | 161024 | 4.3 s | 12713 | 38830 | 3.4s |
| 30 | -69 | 207826 | 341795 | 6.3 s | 25442 | 78636 | 5.7 s |
| 31 | -72 | 223670 | 366075 | 16.2 s | 27294 | 83276 | 5.7 s |
| 32 | -74 | 178917 | 291859 | 10.2 s | 21097 | 64415 | 6.2 s |
| Total |  | 2285177 | 3912294 | 130.4s | 411767 | 1244010 | 76.5 s |

Table 9. Experimental results of TWINE

| Differential Property |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Round | $\log _{2} P_{o p t}$ | $M_{\text {sun }}$ |  |  | $M_{\text {sim }}$ |  |  |
|  |  | Var | Cnf | $T^{\text {sol }}$ | Var | Cnf | $T^{\text {sol }}$ |
| 1 | 0 | 184 | 761 | 0.6 s | 184 | 737 | 0.4 s |
| 2 | -2 | 1053 | 4814 | 1.0 s | 1051 | 4691 | 1.1 s |
| 3 | -4 | 1911 | 8104 | 1.1 s | 1615 | 7295 | 1.2 s |
| 4 | -6 | 3057 | 12091 | 1.1 s | 2179 | 9899 | 1.3 s |
| 5 | -8 | 4491 | 16726 | 1.1 s | 2743 | 12503 | 1.1 s |
| 6 | -12 | 11070 | 38106 | 2.0 s | 6210 | 26565 | 1.9 s |
| 7 | -16 | 16210 | 51561 | 2.1 s | 8410 | 33405 | 2.5 s |
| 8 | -22 | 32571 | 96545 | 3.6 s | 16149 | 58919 | 3.3 s |
| 9 | -28 | 45633 | 127436 | 4.1 s | 21609 | 73227 | 4.0 s |
| 10 | -38 | 100661 | 265893 | 10.9 s | 47575 | 147587 | 8.6 s |
| 11 | -46 | 111870 | 283105 | 15.2 s | 51312 | 149829 | 11.3 s |
| 12 | -51 | 92541 | 229174 | 11.0 s | 38657 | 111682 | 7.9 s |
| 13 | -58 | 148588 | 362181 | 22.8 s | 56940 | 163576 | 20.9s |
| 14 | -64 | 155253 | 372989 | 30.1 s | 55307 | 157479 | 15.8 s |
| 15 | -68 | 127790 | 304341 | 14.3 s | 40920 | 117745 | 9.4 s |
| 16 | -74 | 204239 | 482693 | 39.5 s | 59647 | 172963 | 28.9s |
| 17 | -77 | 131330 | 308567 | 15.0 s | 34410 | 101436 | 7.6 s |
| 18 | -83 | 256928 | 600482 | 32.3 s | 61348 | 183183 | 17.8 s |
| 19 | -88 | 247479 | 574738 | 35.2 s | 55775 | 166306 | 27.4 s |
| 20 | -94 | 322371 | 744437 | 60.4 s | 68985 | 205247 | 21.8 s |
| 21 | -97 | 202482 | 465815 | 14.0 s | 39554 | 119500 | 7.8 s |
| 22 | -103 | 387828 | 889106 | 26.3 s | 70014 | 214123 | 12.6 s |
| 23 | -107 | 303395 | 692916 | 10.5 s | 51545 | 158445 | 5.6 s |
| 24 | -113 | 463358 | 1054586 | 24.9s | 74690 | 230279 | 13.5 s |
| 25 | -116 | 286598 | 650531 | 11.1 s | 42718 | 133612 | 4.6 s |
| 26 | -122 | 541247 | 1225463 | 17.2 s | 75383 | 238483 | 7.9 s |
| 27 | -126 | 417660 | 943011 | 18.5 s | 55500 | 176085 | 5.8 s |
| 28 | -132 | 629881 | 1418495 | 28.5 s | 60760 | 189025 | 6.6 s |
| 29 | -136 | 483370 | 1085931 | 21.8 s | 59080 | 188105 | 9.2 s |
| 30 | -142 | 725235 | 1625639 | 54.7s | 64580 | 201525 | 12.6 s |
| 31 | -146 | 553880 | 1238931 | 28.3 s | 62660 | 200125 | 12.0 s |
| 32 | -152 | 827309 | 1846895 | 41.3 s | 68400 | 214025 | 15.1 s |
| 33 | -155 | 501770 | 1118447 | 22.8 s | 51418 | 166572 | 7.6 s |
| 34 | -161 | 930398 | 2070860 | 39.1 s | 56350 | 178372 | 6.8 s |
| 35 | -166 | 848643 | 1885174 | 68.0 s | 70310 | 225145 | 23.7 s |
| 36 | -172 | 1051617 | 2331743 | 74.8s | 76510 | 239965 | 21.4 s |
| Total |  | 11169901 | 25428287 | 805.3s | 1610498 | 4977660 | 366.8 s |
| Linear Property |  |  |  |  |  |  |  |
| Round | $\log _{2}$ Cor $_{\text {opt }}$ | $M_{\text {sun }}$ |  |  | $M_{\text {sim }}$ |  |  |
|  |  | Var | Cnf | $T^{\text {sol }}$ | Var | Cnf | $T^{\text {sol }}$ |
| 1 | 0 | 176 | 777 | 0.6 s | 176 | 761 | 0.3 s |
| 2 | -1 | 607 | 3165 | 0.7 s | 607 | 3102 | 0.7 s |
| 3 | -2 | 941 | 4932 | 0.7 s | 877 | 4710 | 0.7 s |
| 4 | -3 | 1339 | 6892 | 0.8 s | 1147 | 6318 | 0.8 s |
| 5 | -4 | 1801 | 9012 | 0.7 s | 1417 | 7926 | 0.7 s |
| 6 | -6 | 3633 | 17221 | 1.2 s | 2671 | 14579 | 1.1 s |
| 7 | -8 | 4875 | 21592 | 1.4 s | 3331 | 17495 | 1.4 s |
| 8 | -11 | 8666 | 35699 | 2.3 s | 5570 | 27708 | 1.9 s |
| 9 | -14 | 11438 | 43883 | 2.4 s | 6910 | 32508 | 2.3 s |
| 10 | -18 | 18640 | 66916 | 4.0 s | 10700 | 47405 | 3.0 s |
| 11 | -22 | 23980 | 81051 | 4.7 s | 13100 | 54845 | 3.6 s |
| 12 | -24 | 17403 | 56785 | 2.7s | 8737 | 36251 | 2.3 s |
| 13 | -27 | 27194 | 86591 | 4.7 s | 12554 | 52268 | 3.6 s |
| 14 | -30 | 31950 | 99063 | 5.0 s | 13830 | 56940 | 4.3 s |
| 15 | -32 | 27459 | 83560 | 4.0 s | 10975 | 45503 | 2.8 s |
| 16 | -35 | 41594 | 124467 | 6.2 s | 15506 | 64540 | 4.3 s |
| 17 | -36 | 23177 | 68572 | 2.9 s | 7885 | 33598 | 1.6 s |
| 18 | -39 | 51370 | 150395 | 5.3 s | 16170 | 70124 | 3.1s |
| 19 | -41 | 42936 | 124075 | 4.5 s | 12778 | 55487 | 3.0 s |
| 20 | -44 | 63446 | 181175 | 6.4 s | 17974 | 77980 | 4.1 s |
| 21 | -45 | 34647 | 98142 | 3.1 s | 9087 | 40254 | 1.2 s |
| 22 | -48 | 75398 | 211967 | 5.2 s | 18510 | 83308 | 3.1 s |
| 23 | -50 | 61869 | 172270 | 4.1 s | 14581 | 65471 | 2.2 s |
| 24 | -53 | 89906 | 248123 | 5.8 s | 20442 | 91420 | 3.9 s |
| 25 | -54 | 48421 | 132832 | 3.4s | 10289 | 46910 | 2.0 s |
| 26 | -57 | 104034 | 283779 | 5.6 s | 20850 | 96492 | 2.6 s |
| 27 | -59 | 84258 | 228145 | 5.0 s | 16384 | 75455 | 3.2 s |
| 28 | -62 | 120974 | 325311 | 8.0 s | 17851 | 79979 | 3.5 s |
| 29 | -63 | 64499 | 172642 | 3.7s | 11491 | 53566 | 2.2 s |
| 30 | -66 | 137278 | 365831 | 7.8 s | 12549 | 56742 | 3.4 s |
| 31 | -68 | 110103 | 291700 | 5.4 s | 12619 | 57946 | 2.5 s |
| 32 | -71 | 156650 | 412739 | 7.0 s | 13707 | 61182 | 3.7 s |
| 33 | -72 | 82881 | 217572 | 4.4 s | 12693 | 60222 | 2.3 s |
| 34 | -75 | 175130 | 458123 | 7.4 s | 13847 | 63590 | 3.7 s |
| 35 | -77 | 139404 | 362935 | 5.8 s | 13885 | 64730 | 2.9 s |
| 36 | -80 | 196934 | 510407 | 9.4s | 15069 | 68158 | 3.2 s |
| Total |  | 2085011 | 5758341 | 152.1 s | 396769 | 1775473 | 91.2 s |

Table 10. Experimental results of SPECK32

| Differential Property |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Round | $\log _{2} P_{o p t}$ | $M_{\text {sun }}$ |  |  | $M_{\text {sim }}$ |  |  |
|  |  | Var | Cnf | $T^{\text {sol }}$ | Var | Cnf | $T^{\text {sol }}$ |
| 1 | 0 | 79 | 294 | 0.5 s | 79 | 279 | 0.1s |
| 2 | -1 | 281 | 1229 | 1.9 s | 281 | 1170 | 0.1 s |
| 3 | -3 | 783 | 3154 | 2.1 s | 691 | 2837 | 0.2 s |
| 4 | -5 | 1368 | 5002 | 1.7s | 1000 | 3995 | 0.2 s |
| 5 | -9 | 3925 | 12826 | 2.6 s | 2535 | 9285 | 0.6 s |
| 6 | -13 | 6465 | 19176 | 3.4s | 3665 | 12425 | 1.8 s |
| 7 | -18 | 11838 | 32782 | 9.3 s | 6050 | 19264 | 6.7 s |
| 8 | -24 | 20349 | 53299 | 55.2 s | 9653 | 28875 | 41.9s |
| 9 | -30 | 28511 | 71702 | 417.5 s | 12565 | 35903 | 299.9s |
| 10 | -34 | 26350 | 64751 | 484.3 s | 10340 | 29245 | 248.0 s |
| 11 | -38 | 32265 | 78226 | 805.1 s | 11095 | 31635 | 764.8 s |
| 12 | -42 | 38780 | 92976 | 1211.5 s | 11850 | 34025 | 852.1 s |
| 13 | -45 | 36328 | 86427 | 680.1 s | 9704 | 28376 | 292.8 s |
| 14 | -49 | 52565 | 124216 | 1071.1s | 12495 | 37085 | 698.4 s |
| 15 | -54 | 73638 | 172510 | 2213.9s | 16646 | 48856 | 878.3s |
| 16 | -58 | 70840 | 164726 | 1368.0s | 15160 | 44165 | 690.1s |
| 17 | -63 | 97188 | 224542 | 4808.5 s | 19844 | 57352 | 3472.7 s |
| 18 | -69 | 130424 | 299069 | 32243.4s | 26796 | 75411 | 20902.7s |
| 19 | -74 | 127386 | 290218 | 101072.8s | 25982 | 71704 | 58801.5s |
| 20 | -77 | 94186 | 213859 | 20315.6s | 17642 | 49148 | 15312.9s |
| 21 | -81 | 129125 | 292506 | 35272.9s | 21855 | 61925 | 36305.5 s |
| 22 | -85 | 141865 | 320456 | 31015.1s | 22385 | 63865 | 21320.6s |
| Total |  | 1124539 | 2623946 | 233056.3 s | 258313 | 746825 | 160891.4s |
| Linear Property |  |  |  |  |  |  |  |
| Round | $\log _{2}$ Cor $_{\text {opt }}$ | $M_{\text {sun }}$ |  |  | $M_{\text {sim }}$ |  |  |
|  |  | Var | Cnf | $T^{\text {sol }}$ | Var | Cnf | $T^{\text {sol }}$ |
| 1 | 0 | 111 | 455 | 0.1 s | 111 | 440 | 0.1s |
| 2 | 0 | 190 | 924 | 0.1s | 190 | 879 | 0.1s |
| 3 | -1 | 582 | 2855 | 0.1 s | 582 | 2722 | 0.1 s |
| 4 | -3 | 1398 | 6232 | 0.2 s | 1306 | 5783 | 0.2 s |
| 5 | -5 | 2169 | 8788 | 0.2 s | 1801 | 7604 | 0.3 s |
| 6 | -7 | 3120 | 11749 | 0.5 s | 2296 | 9425 | 0.5 s |
| 7 | -9 | 4251 | 15115 | 1.1s | 2791 | 11246 | 0.8 s |
| 8 | -12 | 7654 | 25655 | 3.8 s | 4614 | 17884 | 3.9s |
| 9 | -14 | 7455 | 23863 | 10.8 s | 4081 | 15482 | 6.1 s |
| 10 | -17 | 12526 | 38639 | 46.1s | 6334 | 23532 | 28.8 s |
| 11 | -19 | 11559 | 34591 | 48.4s | 5371 | 19718 | 37.6 s |
| 12 | -20 | 8941 | 26418 | 17.0s | 3673 | 13886 | 30.0 s |
| 13 | -22 | 15399 | 44977 | 41.7s | 5695 | 22034 | 25.9 s |
| 14 | -24 | 17835 | 51268 | 12.8 s | 6145 | 23765 | 26.4 s |
| 15 | -26 | 20451 | 57964 | 15.8 s | 6595 | 25496 | 23.2 s |
| 16 | -28 | 23247 | 65065 | 38.9 s | 7045 | 27227 | 35.7 s |
| 17 | -30 | 26223 | 72571 | 62.2 s | 7495 | 28958 | 31.7s |
| 18 | -34 | 50310 | 136821 | 1315.2 s | 14570 | 53795 | 622.0 s |
| 19 | -36 | 34419 | 92200 | 1346.1 s | 9889 | 35396 | 1578.2s |
| 20 | -38 | 38025 | 101101 | 2133.8 s | 10249 | 36947 | 1549.7 s |
| 21 | -40 | 41811 | 110407 | 1227.7 s | 10609 | 38498 | 1518.5 s |
| 22 | -42 | 45777 | 120118 | 1185.8 s | 10969 | 40049 | 1199.1s |
| Total |  | 373453 | 1047776 | 7508.3 s | 122411 | 460766 | 6718.7s |

Table 11. Experimental results of SPECK48

| Differential Property |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Round | $\log _{2} P_{\text {opt }}$ | $M_{\text {sun }}$ |  |  | $M_{\text {sim }}$ |  |  |
|  |  | Var | Cnf | $T^{\text {sol }}$ | Var | Cnf | $T^{\text {sol }}$ |
| 1 | 0 | 119 | 446 | 0.1s | 119 | 423 | 0.1s |
| 2 | -1 | 425 | 1869 | 0.3 s | 425 | 1778 | 0.1 s |
| 3 | -3 | 1191 | 4810 | 0.5 s | 1051 | 4325 | 0.2 s |
| 4 | -6 | 2966 | 10551 | 0.8 s | 2214 | 8492 | 0.3 s |
| 5 | -10 | 6575 | 20761 | 1.9 s | 4215 | 14875 | 1.3 s |
| 6 | -14 | 10590 | 30741 | 6.4 s | 5870 | 19545 | 2.9 s |
| 7 | -19 | 19110 | 52168 | 23.2 s | 9494 | 29980 | 18.4s |
| 8 | -26 | 37868 | 97805 | 174.1s | 17836 | 52472 | 155.2 s |
| 9 | -33 | 54112 | 133941 | 1764.7s | 24176 | 67280 | 2170.1 s |
| 10 | -40 | 72932 | 175413 | 15030.6 s | 30516 | 82088 | 15476.6s |
| 11 | -45 | 69234 | 163648 | 18668.9 s | 26174 | 69748 | 19057.5 s |
| 12 | -49 | 69125 | 161871 | 11095.6s | 22805 | 61465 | 9322.1 s |
| 13 | -54 | 97908 | 227464 | 20309.8s | 28712 | 78076 | 16776.3s |
| 14 | -58 | 95090 | 219421 | 4787.1 s | 24920 | 68405 | 3966.3s |
| 15 | -63 | 131550 | 301768 | 22354.6s | 31250 | 86404 | 14627.8 s |
| 16 | -68 | 151335 | 345052 | 31069.3s | 33527 | 92578 | 17658.7s |
| 17 | -75 | 233120 | 527877 | 214052.9s | 50800 | 137776 | 198543.5s |
| 18 | -82 | 269972 | 606885 | 692164.7s | 59716 | 157736 | 568723.1s |
| Total |  | 1323222 | 3082491 | 1031574.8s | 373820 | 1033446 | 866500.5s |
| 19 | -89 | - | - | - | 68632 | 177696 | 1736050.9s |
| Linear Property |  |  |  |  |  |  |  |
| Round | $\log _{2} \operatorname{Cor}_{\text {opt }}$ | $M_{\text {sun }}$ |  |  | $M_{\text {sim }}$ |  |  |
|  |  | Var | Cnf | $T^{\text {sol }}$ | Var | Cnf | $T^{\text {sol }}$ |
| 1 | 0 | 167 | 695 | 0.1 s | 167 | 672 | 0.1 s |
| 2 | 0 | 286 | 1412 | 0.2 s | 286 | 1343 | 0.1 s |
| 3 | -1 | 878 | 4367 | 0.4 s | 878 | 4162 | 0.2 s |
| 4 | -3 | 2118 | 9544 | 0.4 s | 1978 | 8855 | 0.3 s |
| 5 | -6 | 4624 | 18411 | 0.6 s | 3872 | 15988 | 0.5 s |
| 6 | -8 | 5163 | 18832 | 1.4 s | 3757 | 14981 | 1.0 s |
| 7 | -12 | 12405 | 41821 | 21.8 s | 8195 | 30970 | 10.4 s |
| 8 | -15 | 13882 | 43731 | 79.5 s | 8266 | 29900 | 63.8 s |
| 9 | -19 | 23105 | 69231 | 1190.9s | 12595 | 44030 | 1303.9s |
| 10 | -22 | 23730 | 68419 | 3425.5 s | 11786 | 40348 | 3016.2s |
| 11 | -25 | 29116 | 81827 | 13328.0s | 13100 | 44684 | 12381.6 s |
| 12 | -28 | 35054 | 96431 | 23989.9s | 14414 | 49020 | 21814.9 s |
| 13 | -30 | 30711 | 83281 | 11245.4 s | 11353 | 39134 | 8996.6s |
| 14 | -33 | 47302 | 126663 | 36999.4s | 15958 | 55532 | 28682.4 s |
| 15 | -37 | 69365 | 182556 | 144397.5 s | 22555 | 76760 | 131326.2s |
| 16 | -39 | 47694 | 124006 | 105626.1s | 14476 | 49223 | 90098.0s |
| 17 | -43 | 90305 | 232291 | 449659.4s | 25945 | 87810 | 382129.5s |
| 18 | -45 | 61086 | 155641 | 310300.9s | 16510 | 55853 | 154346.7s |
| 19 | -48 | 90332 | 228663 | 205234.8s | 22604 | 77364 | 139713.7s |
| 20 | -51 | 100594 | 252651 | 184329.7s | 24010 | 81884 | 62696.2 s |
| 21 | -54 | 111408 | 277835 | 782536.3s | 25416 | 86404 | 543774.3 s |
| 22 | -57 | 122774 | 304215 | 1208767.8s | 26822 | 90924 | 806042.5s |
| 23 | -59 | 100227 | 247261 | 189832.5 s | 20383 | 70010 | 74138.0s |
| Total |  | 1022326 | 2669784 | 3670966.4s | 305326 | 1055851 | 2460536.3 s |

Table 12. Experimental results of SPECK64

| Differential Property |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Round | $\log _{2} P_{\text {opt }}$ | $M_{\text {sun }}$ |  |  | $M_{\text {sim }}$ |  |  |
|  |  | Var | Cnf | $T^{\text {sol }}$ | Var | Cnf | $T^{\text {sol }}$ |
| 1 | 0 | 159 | 598 | 0.1s | 159 | 567 | 0.1s |
| 2 | -1 | 569 | 2509 | 0.3 s | 569 | 2386 | 0.1 s |
| 3 | -3 | 1599 | 6466 | 0.4 s | 1411 | 5813 | 0.2 s |
| 4 | -6 | 3990 | 14199 | 1.0 s | 2982 | 11436 | 0.5 s |
| 5 | -10 | 8855 | 27961 | 2.7 s | 5695 | 20075 | 2.4 s |
| 6 | -15 | 17679 | 50812 | 15.8 s | 10079 | 32782 | 11.0s |
| 7 | -21 | 32319 | 86556 | 78.0 s | 16779 | 50841 | 78.6 s |
| 8 | -29 | 62991 | 159427 | 1414.9 s | 30945 | 87369 | 1382.8 s |
| 9 | -34 | 58056 | 142108 | 1954.5 s | 25640 | 70444 | 1665.8 s |
| 10 | -38 | 60690 | 146291 | 1266.6 s | 23050 | 63905 | 1971.9s |
| 11 | -42 | 73545 | 175406 | 518.8 s | 24065 | 67775 | 551.8 s |
| 12 | -46 | 87640 | 207156 | 524.9 s | 25080 | 71645 | 333.0s |
| 13 | -50 | 102975 | 241541 | 685.1 s | 26095 | 75515 | 508.7 s |
| 14 | -56 | 170401 | 396040 | 1793.7s | 40943 | 117103 | 1458.5 s |
| 15 | -62 | 202055 | 464969 | 7300.5 s | 48083 | 133931 | 7970.2 s |
| 16 | -70 | 308286 | 702316 | 171274.8s | 75378 | 202569 | 124237.1s |
| 17 | -73 | 157152 | 355875 | 3821.9s | 36120 | 96728 | 3618.4 s |
| 18 | -76 | 173082 | 391331 | 2644.1 s | 33922 | 93812 | 1200.3 s |
| 19 | -81 | 288162 | 649648 | 2777.5 s | 51086 | 143332 | 1894.5 s |
| 20 | -85 | 266705 | 599311 | 2356.3 s | 43945 | 124025 | 1623.7 s |
| 21 | -89 | 293045 | 656946 | 1274.9s | 43875 | 125725 | 1064.8 s |
| 22 | -94 | 386793 | 864742 | 1874.5 s | 54593 | 156958 | 1809.3 s |
| 23 | -99 | 425742 | 948952 | 4186.1 s | 58454 | 166876 | 3068.2s |
| 24 | -107 | 709857 | 1575649 | 53855.4s | 103395 | 285009 | 43906.8s |
| 25 | -112 | 523152 | 1156936 | 40157.5 s | 78776 | 211876 | 36288.7 s |
| 26 | -116 | 471520 | 1040961 | 13957.4s | 66400 | 179905 | 9877.2s |
| 27 | -121 | 610170 | 1344904 | 62226.7s | 80786 | 220300 | 43099.3s |
| Total |  | 5497189 | 12409610 | 375954.0s | 1008305 | 2818702 | 287617.3s |
| Linear Property |  |  |  |  |  |  |  |
| Round | $\log _{2}$ Cor $_{\text {opt }}$ | $M_{\text {sun }}$ |  |  | $M_{\text {sim }}$ |  |  |
|  |  | Var | Cnf | $T^{\text {sol }}$ | Var | Cnf | $T^{\text {sol }}$ |
| 1 | 0 | 223 | 935 | 0.1 s | 223 | 904 | 0.1 s |
| 2 | 0 | 382 | 1900 | 0.2 s | 382 | 1807 | 0.2 s |
| 3 | -1 | 1174 | 5879 | 0.3 s | 1174 | 5602 | 0.2 s |
| 4 | -3 | 2838 | 12856 | 0.4 s | 2650 | 11927 | 0.3 s |
| 5 | -6 | 6208 | 24811 | 1.4 s | 5200 | 21556 | 1.0 s |
| 6 | -9 | 9622 | 34583 | 3.9 s | 7102 | 27676 | 3.2 s |
| 7 | -13 | 17765 | 58536 | 55.2 s | 11785 | 43300 | 40.1s |
| 8 | -17 | 25205 | 77401 | 452.1 s | 15135 | 52885 | 440.0 s |
| 9 | -19 | 19497 | 57676 | 787.2 s | 10267 | 35840 | 417.7 s |
| 10 | -21 | 23502 | 68269 | 161.9 s | 10732 | 38513 | 231.5 s |
| 11 | -24 | 37852 | 107623 | 570.3 s | 15604 | 56260 | 377.1 s |
| 12 | -27 | 45730 | 127067 | 742.3 s | 17506 | 62380 | 577.2 s |
| 13 | -30 | 54352 | 148123 | 2064.8 s | 19408 | 68500 | 1918.9s |
| 14 | -33 | 63718 | 170791 | 2508.2 s | 21310 | 74620 | 2327.5 s |
| 15 | -37 | 93445 | 246156 | 58259.1s | 30165 | 103220 | 23275.5 s |
| 16 | -41 | 109565 | 283621 | 246564.5 s | 34755 | 115285 | 168923.4s |
| 17 | -43 | 74577 | 191080 | 15661.2 s | 22039 | 73280 | 12542.8s |
| 18 | -45 | 82302 | 209857 | 2447.7 s | 21760 | 74465 | 1987.3 s |
| 19 | -47 | 90399 | 229471 | 2184.9 s | 21481 | 75650 | 2085.4s |
| 20 | -49 | 98868 | 249922 | 549.0 s | 21202 | 76835 | 643.7 s |
| 21 | -52 | 144912 | 364211 | 108.0s | 29192 | 106612 | 96.8 s |
| 22 | -54 | 118965 | 297418 | 51.0s | 22489 | 82889 | 32.2 s |
| 23 | -59 | 263694 | 653938 | 2745.4 s | 50606 | 180502 | 2440.3s |
| 24 | -63 | 246015 | 603951 | 136591.4s | 50065 | 169085 | 106329.4s |
| 25 | -66 | 215848 | 526530 | 151105.9s | 43424 | 144324 | 112890.8s |
| 26 | -68 | 174399 | 423994 | 55103.8 s | 32791 | 110429 | 30689.2s |
| 27 | -70 | 186123 | 451606 | 1843.6 s | 31861 | 110312 | 1640.3 s |
| Total |  | 2207180 | 5628206 | 677816.7s | 550308 | 1924658 | 469908.9 s |

Table 13. Experimental results of SPECK96

| Differential Property |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Round | $\log _{2} P_{o p t}$ | $M_{\text {sun }}$ |  |  | $M_{\text {sim }}$ |  |  |
|  |  | Var | Cnf | $T^{\text {sol }}$ | Var | Cnf | $T^{\text {sol }}$ |
| 1 | 0 | 239 | 902 | 0.8 s | 239 | 855 | 0.1s |
| 2 | -1 | 857 | 3789 | 1.9 s | 857 | 3602 | 0.1s |
| 3 | -3 | 2415 | 9778 | 2.6s | 2131 | 8789 | 0.2 s |
| 4 | -6 | 6038 | 21495 | 4.2 s | 4518 | 17324 | 0.7s |
| 5 | -10 | 13415 | 42361 | 6.4 s | 8655 | 30475 | 3.4s |
| 6 | -15 | 26799 | 77020 | 24.4 s | 15359 | 49870 | 22.7 s |
| 7 | -21 | 49007 | 131244 | 163.8 s | 25627 | 77497 | 230.4 s |
| 8 | -30 | 108025 | 272406 | 5512.4 s | 54445 | 151910 | 5358.7s |
| 9 | -39 | 159420 | 384536 | 149122.6s | 76920 | 202360 | 145998.0s |
| 10 | -49 | 243782 | 570615 | 1628937.4s | 111848 | 283107 | 1323894.2s |
| Total |  | 609997 | 1514146 | 1783776.5 s | 300599 | 825789 | 1475508.5 s |
| Linear Property |  |  |  |  |  |  |  |
| Round | $\log _{2}^{C o r_{o p t}}$ | $M_{\text {sun }}$ |  |  | $M_{\text {sim }}$ |  |  |
|  |  | Var | Cnf | $T^{\text {sol }}$ | Var | Cnf | $T^{\text {sol }}$ |
| 1 | 0 | 335 | 1415 | 0.1s | 335 | 1368 | 0.1 s |
| 2 | 0 | 574 | 2876 | 0.1s | 574 | 2735 | 0.1 s |
| 3 | -1 | 1766 | 8903 | 0.2 s | 1766 | 8482 | 0.2 s |
| 4 | -3 | 4278 | 19480 | 0.2 s | 3994 | 18071 | 0.2 s |
| 5 | -6 | 9376 | 37611 | 1.3 s | 7856 | 32692 | 1.1 s |
| 6 | -9 | 14550 | 52439 | 12.6 s | 10750 | 42012 | 10.5 s |
| 7 | -13 | 26885 | 88776 | 200.6 s | 17865 | 65780 | 180.4 s |
| 8 | -18 | 46923 | 143128 | 4483.5 s | 28679 | 98698 | 4025.3 s |
| 9 | -22 | 53435 | 154236 | 36875.5s | 29685 | 98220 | 25305.9s |
| 10 | -27 | 83859 | 232396 | 457549.1s | 42863 | 137626 | 387357.7s |
| 11 | -31 | 88445 | 237556 | 936813.7s | 41505 | 130660 | 624957.1s |
| 12 | -33 | 62940 | 166486 | 129785.2s | 26008 | 83255 | 50454.2 s |
| 13 | -36 | 96992 | 253923 | 158613.9s | 35328 | 115844 | 87626.0s |
| 14 | -39 | 112318 | 290559 | 161359.4s | 37094 | 122908 | 97441.6s |
| Total |  | 602676 | 1689784 | 1885695.4s | 284302 | 958351 | 1277360.4s |
| 15 | -43 | - | - | - | 50325 | 165960 | 268094.1 s |

Table 14. Experimental results of SPECK128

| Differential Property |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Round | $\log _{2} P_{\text {opt }}$ | $M_{\text {sun }}$ |  |  | $M_{\text {sim }}$ |  |  |
|  |  | Var | Cnf | $T^{\text {sol }}$ | Var | Cnf | $T^{\text {sol }}$ |
| 1 | 0 | 319 | 1206 | 0.1s | 319 | 1143 | 0.1s |
| 2 | -1 | 1145 | 5069 | 0.1s | 1145 | 4818 | 0.1 s |
| 3 | -3 | 3231 | 13090 | 0.3 s | 2851 | 11765 | 0.3 |
| 4 | -6 | 8086 | 28791 | 1.0 s | 6054 | 23212 | 0.7s |
| 5 | -10 | 17975 | 56761 | 3.5 s | 11615 | 40875 | 4.2 |
| 6 | -15 | 35919 | 103228 | 36.7s | 20639 | 66958 | 30.3 |
| 7 | -21 | 65695 | 175932 | 343.8 s | 34475 | 104153 | 286.3 |
| 8 | -30 | 144825 | 36520 | 9874.4s | 73325 | 204390 | 9773.7s |
| 9 | -39 | 213740 | 365206 | 274980.4s | 103720 | 272600 | 247510.6 s |
| Total |  | 490935 | 1264859 | 285240.3 s | 254143 | 729914 | 257606.3 s |
| Linear Property |  |  |  |  |  |  |  |
| Round | $\log _{2}^{C o r_{o p t}}$ | $M_{\text {sun }}$ |  |  | $M_{\text {sim }}$ |  |  |
|  |  | Var | Cnf | $T^{\text {sol }}$ | Var | Cnf | $T^{\text {sol }}$ |
| 1 | 0 | 447 | 1895 | 0.1s | 447 | 1832 | 0.1s |
| 2 | 0 | 766 | 3852 | 0.2 s | 766 | 3663 | 0.1 s |
| 3 | -1 | 2358 | 11927 | 0.2 s | 2358 | 11362 | 0.2 s |
| 4 | -3 | 5718 | 26104 | 0.4 s | 5338 | 24215 | 0.3 s |
| 5 | -6 | 12544 | 50411 | 3.6 s | 10512 | 43828 | 2.9 s |
| 6 | -9 | 19478 | 70295 | 23.2s | 14398 | 56348 | 18.1s |
| 7 | -13 | 36005 | 119016 | 463.5 s | 23945 | 88260 | 308.5s |
| 8 | -18 | 62859 | 191896 | 10263.7s | 38471 | 132490 | 8422.5 s |
| 9 | -22 | 71595 | 206796 | 11079.5s | 39845 | 131900 | 8468.6s |
| 10 | -27 | 112371 | 311596 | 355623.7 s | 57551 | 184858 | 253834.6s |
| Total |  | 324141 | 993788 | 377458.1s | 193631 | 678756 | 271055.9 s |
| 11 | -31 | - | - | - | 55745 | 175540 | 939954.9 s |


[^0]:    ${ }^{3} \mathrm{http}: / /$ windows.dailydownloaded.com/en/educational-software/student-tools/44924-logic-friday-download-install

