# Provable Lattice Reduction of $\mathbb{Z}^{n}$ with Blocksize $n / 2$ 

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#### Abstract

The Lattice Isomorphism Problem (LIP) is the computational task of recovering, assuming it exists, an orthogonal linear transformation sending one lattice to another. For cryptographic purposes, the case of the trivial lattice $\mathbb{Z}^{n}$ is of particular interest (ZLIP). Heuristic analysis suggests that the BKZ algorithm with blocksize $\boldsymbol{\beta}=\boldsymbol{n} / \mathbf{2}+\boldsymbol{o}(\boldsymbol{n})$ solves such instances (Ducas, Postlethwaite, Pulles, van Woerden, ASIACRYPT 2022). In this work, I propose a provable version of this statement, namely, that $\mathbb{Z}$ LIP can indeed be solved by making polynomially many calls to a Shortest Vector Problem (SVP) oracle in dimension at most $\boldsymbol{n} / \mathbf{2}+\mathbf{1}$.


Keywords: Lattice Isomorphism Problem, Lattice Reduction, Provable Algorithm

## 1 Introduction

Two lattices $\Lambda, \Lambda^{\prime} \subset \mathbb{R}^{n}$ are said to be isomorphic if there exists a rotation between them, that is a linear orthogonal map $O \in \mathcal{O}_{n}(\mathbb{R})$ such that $O \cdot \Lambda=\Lambda^{\prime}$. Determining isomorphism and finding it if it exists is called the Lattice Isomorphism Problem (LIP). The best known provable algorithm [1] has super-exponential time $n^{O(n)}$, but in practice other methods are often preferred [1-4]. They essentially consist in finding all the shortest vectors, to then solve a (potentially exponentially large) instance of the Graph Isomorphism Problem.

The Lattice Isomorphism Problem has recently been proposed as a foundation for cryptographic construction [5, 6], and the case of rotations of $\mathbb{Z}^{n}$ quickly arose as a natural instantiation for simple and efficient cryptographic design [7, 8]. In this case (coined $\mathbb{Z} L I P[6]$ ), finding the shortest vectors is sufficient, which generically implies a
provable algorithm in time $2^{n+o(n)}$ thanks to the worst-case Shortest Vector Problem (SVP) algorithm [9, 10].

## Prior Provable Algorithms for $\mathbb{Z} L I P$

Yet, one might doubt that finding the shortest vector in rotations of $\mathbb{Z}^{n}$ should be as hard as in a worst-case lattice. It was suggested already by Szydlo [11] than finding rather short yet not necessarily the shortest vector could be sufficient to solve LIP over $\mathbb{Z}^{n}$, though it was not exactly clear at the time how short of a vector is required nor how costly it would be to find it. The only formal statement of Szydlo is a reduction from $\mathbb{Z L I P}$ to a decisional version of LIP for mild sparsification of $\mathbb{Z}^{n}$.

Bennett, Ganju, Peetathawatchai, and Stephens-Davidowitz [6] indeed proposed a provable algorithm with complexity $2^{n / 2+o(n)}$ for this task, via a polynomial time reduction Gap-SVP in the same dimension $n$, with a constant approximation factor. Despite the relaxation to an Gap version of SVP, block reductions algorithm remain insufficient to reach this result, as they are only known to provide $\Omega(\sqrt{n})$ approximation factors even when the blocksize is close to the full dimension [12-14]. Instead, they rely on an algorithm of [9] tailored to Gap-SVP; the core of this algorithm is similar to the $2^{n+o(n)}$ algorithm for exact-SVP, in particular it operate on lattices of full dimension $n$, but the gap allows for some complexity improvements.

## Heuristic Algorithms for $\mathbb{Z}$ LIP

As for many other lattice problems, the best provable complexity stands in contrast with the heuristic state of the art. Using standard heuristic analysis (see [15] for a survey), Ducas, Postlethwaite, Pulles, and van Woerden [8, Sec. 4.2] argued that the block reduction algorithm BKZ $[16,17]$ should be successful in finding those shortest vectors using a blocksize of $\beta=n / 2+o(n)$ because the shortest vectors are unusually short compared to that of a random lattice by a factor $\Theta(\sqrt{n})$.

More specifically, it is argued that when the lattice is sufficiently reduced, the last block of the lattice has a large volume, and therefore it is not expected to contain a vector shorter than the ones we are looking for. This step of the reasoning is entirely heuristic. From there, one concludes that an SVP call on this last block should indeed find (a projection ${ }^{1}$ of) some unit vectors of the full $\mathbb{Z}^{n}$ lattice. This heuristic conclusion is confirmed by extensive experiments.

Plugging the best heuristic complexity of $2^{292 \beta+o(\beta)}$ for SVP [19] in dimension $\beta$ leads to a heuristic complexity of $2^{146 n+o(n)}$.

## The result

In this work, I propose a provable variant of the heuristic claim of [8, Sec. 4.2], namely, exhibiting a block reduction algorithm for solving $\mathbb{Z}$ LIP, that indeed relies on polynomially many calls to an SVP oracle in dimensions less than $n / 2+1$. The algorithm is however not exactly BKZ [16, 17], but rather a specialization of the Slide algorithm [12-14]. The key remark is that projected lattices of $\mathbb{Z}^{n}$ have a shortest vector

[^0]of length either 1 or smaller than $\sqrt{1-1 / n}$ (Lemmas 3 and 4 ). This implies that the slide algorithm makes significant progress at each iteration, until the first block is itself a rotation of $\mathbb{Z}^{k}$ where $n=2 k+1$.

Note that this does not directly improve the best provable complexity for $\mathbb{Z} L I P$, as plugging in the best provable algorithm [9, 10] for SVP in dimension $n / 2$ also leads to a $2^{n / 2+o(n)}$ complexity, as reached by different means in [6]. While those final complexity are similar, the complexity theoretic reduction underlying these results are different. The approach of [6] maintain the dimension of the lattice to $n$, but relax the problem to a gap version with an constant approximation factor ${ }^{2}$. On the other hand the approach of this work divides the SVP dimension but doesn't relax the problem ${ }^{3}$. Another difference is that our reduction is deterministic while that of [6] is probabilistic.

Despite the lack of direct impact on the complexity of $\mathbb{Z}$ LIP of our approach, we found it motivating for the following reason. It appears to be the first case where we can prove that block reduction does find the shortest vector with a blocksize $\beta<n$ despite the lack of uniqueness of the shortest vector. Indeed, to the best of my knowledge, this was only proved $[13,14]$ for lattices with polynomial gap of at least $\Omega(\sqrt{n})$ between the first and second minima $\lambda_{1}(L)$ and $\lambda_{2}(L)$. On the contrary, lattices that are rotation of $\mathbb{Z}^{n}$ have all their successive minima equal $\lambda_{1}(L)=\lambda_{2}(L)=\cdots=\lambda_{n}(L)=1$.

In that sense, this result is a step toward closing the gap between the theory and practice. Indeed heuristic and experiments suggested that the uniqueness of the shortest vector is essentially irrelevant in practice, what matter is how unusually short it is compared to Minkowski's bound [5, 8, 18].

## 2 Preliminaries

We write a matrix $B \in \mathbb{R}^{m \times n}$ as $B=\left(b_{0}, \ldots, b_{n-1}\right)$ where $b_{i}$ is the $i$-th column vector of $B$. We denote by $I_{n}$ the $n \times n$ identity matrix.

## Lattices

If $B \in \mathbb{R}^{m \times n}$ has full-column rank $n$, the lattice $\mathcal{L}$ generated by the basis $B$ is denoted by $\mathcal{L}(B)=B \cdot \mathbb{Z}^{n}=\left\{B \cdot x \mid x \in \mathbb{Z}^{n}\right\}$. We denote by $B^{\star}=\left(b_{0}^{\star}, \ldots, b_{n-1}^{\star}\right)$ the GramSchmidt orthogonalization (GS) of the matrix $\left(b_{0}, \ldots, b_{n-1}\right)$. For $i \in\{0, \ldots, n-1\}$, we denote the projection orthogonal to the span of $\left(b_{0}, \ldots, b_{i-1}\right)$ by $\pi_{i}$; $\pi_{0}$ denotes "no projection", i.e. the identity. For $0 \leq i \leq j<d$, we denote by $B_{[i: j]}$ the local projected block $\left(\pi_{i}\left(b_{i}\right), \ldots, \pi_{i}\left(b_{j}\right)\right)$, and when the basis is clear from context, by $\mathcal{L}_{[i: j]}$ the lattice generated by $B_{[i: j]}$. Note that both bounds of the interval $[i: j]$ are inclusive in this notation.

## Metric and Volumetric Properties

The Euclidean norm of a vector $v$ is denoted by $\|v\|$. The volume (or determinant) of a lattice $\mathcal{L}(B)$ is $\operatorname{vol}(\mathcal{L}(B))=\sqrt{\left|\operatorname{det}\left(B^{T} \cdot B\right)\right|}=\prod_{i}\left\|b_{i}^{\star}\right\|$. It is an invariant of the

[^1]lattice, it is also invariant under rotation, and is non-negative for any lattice $L$. The first minimum of a lattice $\mathcal{L}$ is the norm of a shortest non-zero vector, denoted by $\lambda_{1}(\mathcal{L})$. We use the abbreviations $\operatorname{vol}(B)=\operatorname{vol}(\mathcal{L}(B))$ and $\lambda_{1}(B)=\lambda_{1}(\mathcal{L}(B))$.

The $i$-th minimal distance $\lambda_{i}(L)$ is defined as the smallest radius $r>0$ such that $L$ contains $i$ many linearly independent vectors. These quantities are also invariants under rotation.

## Primitivity

We write $\pi_{X}^{\perp}$ for the projection orthogonal to the space spanned by $X$ for any set $X \subset \mathbb{R}^{m}$. A sublattice $S$ of $L$ is said to be primitive if $S=\operatorname{Span}_{\mathbb{R}}(S) \cap L$. Equivalently, $S \subset L$ is primitive if and only if there exists another sublattice $S^{\prime} \subset L$ such the sum $S+S^{\prime}$ is direct and $L=S \oplus S^{\prime}$. In particular, if $B$ is a basis of $L$, then the lattice generated by any subset of the column of $B$ is a primitive sublattice of $L$.

The main purpose of primitivity in this work is the following property. For a primitive sublattice $S \subset L$ and any $x \in L \backslash S$, it holds that the projection of $x$ orthogonally to $S$ is a non-zero lattice vectors of $\pi \frac{\perp}{S}(L): \pi \frac{1}{S}(x) \neq 0$.

### 2.1 Reduction

Definition 1 (Size reduction). A basis $B \in \mathbb{R}^{m \times n}$ of a lattice $L \subset \mathbb{R}^{m}$ is said to be size-reduced if $\left\langle b_{j}, b_{i}^{\star}\right\rangle \leq \frac{1}{2}\left\|b_{i}^{\star}\right\|^{2}$ for all $j>i$.

We recall that there is a polynomial-time algorithm that size-reduces a basis [20, 21], and that this algorithms does not affect the Gram-Schmidt orthogonalization $B^{\star}$. Definition 2 (SVP and HKZ reduction). A basis $B \in \mathbb{R}^{m \times n}$ of a lattice $L \subset \mathbb{R}^{m}$ is said to be SVP-reduced if $b_{1}$ is a shortest vector of L. It is said to be HKZ-reduced if it is size-reduced and if each block $B_{[i: n-1]}$ for $i \in\{0, \ldots, n-1\}$ is SVP-reduced.

Note that by the volume invariance, SVP reduction minimizes $\left\|b_{0}\right\|=\left\|b_{0}^{\star}\right\|$, it also maximizes the remaining volume $\operatorname{vol}\left(B_{[1: n-1]}\right)=\prod_{i=1}^{n-1}\left\|b_{i}^{\star}\right\|$.

### 2.2 Duality

Definition 3 (Dual Lattice). The dual lattice $\mathcal{L}^{\vee}$ of a lattice $\mathcal{L} \subset \mathbb{R}^{m}$ is the set of all $w \in \operatorname{Span}_{\mathbb{R}}(\Lambda)$ such that $\langle w, \mathcal{L}\rangle \subseteq \mathbb{Z}$.

An important fact for our proof is that $\mathbb{Z}^{n}$ is self-dual, and so are all of its rotations.
There is a natural correspondence between bases of the primal and bases of the dual, given by the (pseudo-)inverse transpose: if $B$ is a basis of $\Lambda$ then $D=B$. $\left(B^{T} \cdot B\right)^{-1}$ is a basis of the dual lattice $\mathcal{L}^{\vee}$. For our purpose, we will only need the fact that the last dual vector $d_{n}$ is the reciprocal of the last Gram-Schmidt vector: $d_{n-1}=b_{n-1}^{\star} /\left\|b_{n-1}^{\star}\right\|^{2}$; in particular $\left\|d_{n-1}\right\|=1 /\left\|b_{n-1}^{\star}\right\|$. We refer to $[13,14]$ for more background on reduction and duality.

For this reason, it is natural to consider the dual basis in reversed order. In particular, by applying SVP reduction in the dual, we mean to minimize $\left\|d_{n-1}\right\|$, or equivalently maximize $\left\|b_{n-1}^{\star}\right\|$.

## 2.3 $\mathbb{Z}$ LIP

Let $\Lambda$ be a rotation of $\mathbb{Z}^{n}$. We assume $n$ to be odd and write $n=2 k+1$ for some integer $k$. The case of even $n$ can be treated by artificially adding an extra orthogonal component defining a lattice $\Lambda^{+}=\Lambda \oplus \mathbb{Z}$. Note that this restriction seemingly prevents direct reduction from $\mathbb{Z S V P}$ to $\mathbb{Z}$ LIP by induction ${ }^{4}$ : instead we will directly solve $\mathbb{Z}$ LIP.

We denote $E=\left(e_{0}, \ldots, e_{2 k}\right)$ some orthogonal basis of $\Lambda$. The problem is to find any such orthogonal basis given any basis of $\Lambda$ as input ${ }^{5}$, i.e. to find $E$ up to signs and permutation. Note that the set $\left\{ \pm e_{i}\right\}$ is precisely the set of shortest vectors of $\Lambda$.

Note further that this is equivalent to finding an HKZ-reduced basis of $\Lambda$ (a statement that is not necessarily true for all lattices). Indeed, the shortest vectors are exactly $\pm e_{i}$ so an HKZ basis must start with such a vector. Projecting orthogonally to any of those vectors gives a rotation of $\mathbb{Z}^{n-1}$; it remains to unroll the inductive definition of HKZ reduction.

## 3 A Provable $\mathbb{Z L I P}$ algorithm

We consider the following algorithm, which may be viewed as a specialization of the Slide algorithm [12-14], namely the number of block is fixed to 2 and the stopping condition is tailored to the special case of rotations of $\mathbb{Z}^{n}$.

Note that the algorithm is invariant by rotation of the input. Hence, it is sufficient to analyze its behavior for the case $\Lambda=\mathbb{Z}^{n}$.

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Algorithm 1 An algorithm for ZLIP
Require: A basis \(B\) of \(\Lambda, \Lambda\) being a rotation of \(\mathbb{Z}^{n}\), where \(n=2 k+1\) is odd.
Ensure: An orthonormal basis \(B\) of \(\Lambda\)
    while \(\operatorname{vol}\left(B_{[0 \ldots k-1]}\right)>1\) do
        Dual-SVP reduce the block \(B_{[0: k]}\)
        Primal-SVP reduce the block \(B_{[k: 2 k]}\)
    end while
    Primal-HKZ reduce the block \(B_{[0: k-1]}\)
    Primal-HKZ reduce the block \(B_{[k: 2 k]}\)
    return \(B\)
```


### 3.1 Partial Correctness

Let us start by explaining why the algorithm succeeds when it terminates. The central argument will be that the first block is isometric to $\mathbb{Z}^{k}$ (Lemma 2). To establish it, let us first state the following.

[^2]Lemma 1. Let $A, B \in \mathbb{R}^{n \times n}$ be two positive symmetric definite matrices. Then $\operatorname{det}(A+B) \geq \operatorname{det}(A)$.

Proof. This follows directly from the fact that $H \mapsto \operatorname{det}(H)^{1 / n}$ is concave on the space of positive symmetric definite matrices. ${ }^{6}$ In particular it holds that $\operatorname{det}(A+B)^{1 / n} \geq$ $\operatorname{det}(A)^{1 / n}+\operatorname{det}(B)^{1 / n}$. Because $\operatorname{det}(B) \geq 0$, we have $\operatorname{det}(A+B)^{1 / n} \geq \operatorname{det}(A)^{1 / n}$, and we conclude.

Lemma 2. Any sublattice $L \subset \mathbb{Z}^{n}$ of rank $k \geq 1$ has non-zero integer squared volume. Furthermore, if $\operatorname{vol}(L)=1$, then $L$ is isomorphic to $\mathbb{Z}^{k}$.
Proof. Let $B \in \mathbb{R}^{n \times k}$ be a basis of $L$. Because $L \subset \mathbb{Z}^{n}, B$ must be an integer matrix, and $\operatorname{vol}(L)^{2}=\operatorname{det}\left(\left|B^{T} \cdot B\right|\right)$ is therefore an integer. It is also non-zero, because $L$ is a lattice.

For the second property, consider a basis $B$ of $L$ in Hermite Normal Form. Up to a permutation of the rows, $B=\left[\begin{array}{c}X \\ Y\end{array}\right]$ where $X$ is lower triangular and non-degenerate. Note that $B^{T} B=X^{T} X+Y^{T} Y$. Lemma 1 gives that $\operatorname{det}\left(X^{T} X+Y^{T} Y\right) \geq \operatorname{det}\left(X^{T} X\right)$. Because both $X^{T} X$ is integral and non-degenerate, and since $\operatorname{det}\left(B^{T} B\right)=1$, we have $\operatorname{det}\left(X^{T} X\right)=1$. By the properties of Hermite Normal Form, it must therefore be the case that $X$ is the identity matrix $I_{k}$.

Let $\eta_{1}, \ldots, \eta_{k} \geq 0$ be the eigenvalues of $Y^{T} Y$. Because the identity $I_{k}$ is codiagonalizable with $Y^{T} Y$, the eigenvalues of $B^{T} B=I_{k}+Y^{T} Y$ are exactly $1+$ $\eta_{1}, \ldots, 1+\eta_{k}$. It remains to write $\operatorname{det}\left(B^{T} B\right)=\Pi\left(1+\eta_{i}\right)$ to conclude that $\eta_{i}=0$ for all $i$, and therefore that $Y=0$. That is, up to permutation of the rows, $B=\left[\begin{array}{c}I_{k} \\ 0\end{array}\right]$. The lattice $L$ is indeed isomorphic to $\mathbb{Z}^{k}$.

Theorem 1. Algorithm 1 is partially correct, that is, if it terminates on a valid input, it outputs an orthogonal basis of the input lattice.

Proof. By Lemma 2, when the while loop terminates (Steps 1-4 of Algorithm 1), the block $B_{[0: k-1]}$ has volume 1 and it is therefore isomorphic to $\mathbb{Z}^{k}$; after HKZ reduction (Step 5) we have recovered $k$ orthogonal unit vectors. Then, the projected block $B_{[k: 2 k]}$ is also isomorphic to $\mathbb{Z}^{k+1}$ and we recover the remaining $k+1$ orthogonal vectors at Step 6.

### 3.2 Termination

We now move to proving termination, which is done by showing that the volume of the first block decrease significantly at each loop iteration.
Lemma 3. Let $L$ be a primitive sublattice of $\mathbb{Z}^{n}$ of rank $k<n$, and let $L^{\prime}=\pi_{L}^{\perp}\left(\mathbb{Z}^{n}\right)$. Then $\lambda_{1}\left(L^{\prime}\right)^{2} \leq 1$.

Proof. Because $L$ is not a full rank, there must exist an index $j$ such that $e_{j} \notin L$. Therefore, by primitivity of $L, \pi_{L}^{\perp}\left(e_{j}\right) \in L^{\prime}$ is non-zero, and $\left\|\pi_{L}^{\perp}\left(e_{j}\right)\right\| \leq\left\|e_{j}\right\| \leq 1$.
Lemma 4. Let $L$ be a primitive sublattice of $\mathbb{Z}^{n}$ of rank $k<n$ and volume $\operatorname{vol}(L)>1$, and let $L^{\prime}=\pi_{L}^{\perp}\left(\mathbb{Z}^{n}\right)$. Then $\lambda_{1}\left(L^{\prime}\right)^{2} \leq 1-\frac{1}{n}$.

[^3]Proof. Consider an HKZ-reduced and size-reduced basis $B=\left[b_{0}, \ldots, b_{m-1}\right] \in \mathbb{Z}^{m \times n}$ of $L$. Because $\operatorname{vol}(L)>1$, there is at least one $b_{i}$ that is not a unit vector $e_{j}$. Let $i$ be the minimal such index, and let $S$ be the subset of indices $j$ such at $e_{j} \in L$. Because the basis is HKZ-reduced and therefore size-reduced, $b_{i}$ is orthogonal to all the $e_{k}$ 's such that $e_{k} \in L$. That is, $b_{i}=\sum_{k \notin S} v_{k} e_{k}$ where $v_{k} \in \mathbb{Z}$.

Now consider an index $j$ that maximizes $\left|v_{j}\right|$, i.e., $\left|v_{j}\right|=\left\|b_{i}\right\|_{\infty}$; in particular $\left\langle e_{j}, b_{i}\right\rangle=\left\|b_{i}\right\|_{\infty}$. Note that $e_{j}$ does not belong to $L$ and $L$ is a primitive sublattice of $\mathbb{Z}^{n}$, so $\pi_{L}^{\perp}\left(e_{j}\right) \in L^{\prime}$ is non-zero. Furthermore,

$$
\left\|\pi_{L}^{\perp}\left(e_{j}\right)\right\| \leq\left\|\pi_{b_{i}}^{\perp}\left(e_{j}\right)\right\|=\left\|e_{j}-\frac{\left\langle e_{j}, b_{i}\right\rangle}{\left\|b_{i}\right\|^{2}} b_{i}\right\| .
$$

We now apply the polar identity $\|x-y\|^{2}=\|x\|^{2}+\|y\|^{2}-2 \cdot\langle x, y\rangle$ to conclude

$$
\begin{aligned}
\left\|\pi_{L}^{\perp}\left(e_{j}\right)\right\|^{2} & \leq 1+\frac{\left\langle e_{j}, b_{i}\right\rangle^{2} \cdot\left\|b_{i}\right\|^{2}}{\left\|b_{i}\right\|^{4}}-2 \cdot \frac{\left\langle e_{j}, b_{i}\right\rangle^{2}}{\left\|b_{i}\right\|^{2}} \\
& \leq 1-\frac{\left\langle e_{j}, b_{i}\right\rangle^{2}}{\left\|b_{i}\right\|^{2}} \\
& \leq 1-\frac{\left\|b_{i}\right\|_{\infty}^{2}}{\left\|b_{i}\right\|^{2}} \leq 1-\frac{1}{n}
\end{aligned}
$$

We are now ready to prove that Algorithm 1 terminates after polynomially many loop iterations.
Theorem 2. On a valid input $B \in \mathbb{R}^{n \times n}$, Algorithm 1 terminates after at most $O\left(n^{2} \log \max _{i}\left\|b_{i}\right\|\right)$ iterations of the main loop.

Note that the number of iteration is polynomial in the input size. One may further apply the LLL algorithm to the input basis to enforce $\max _{i}\left\|b_{i}\right\| \leq 2^{n}$, to bound the number of iteration by $O\left(n^{3}\right)$.

Proof. The core claim is that, at each loop iteration (Steps 1-4 of Algorithm 1), the volume of the block $B_{[0: k-1]}$ decreases by at least $\sqrt{1-1 / n}$.

Indeed, the primal-SVP reduction step (Step 3) does not affect this block. Furthermore, this Step 3 leaves the Gram-Schmidt norm at position $k$ to a value less than $\sqrt{1-1 / n}$, by application of Lemma 4. Then, the dual-SVP reduction step (Step 2) is going to increase this Gram-Schmidt norm to at least 1, by dual application of Lemma 3. This step therefore decreases the volume of the block $B_{[0: k-1]}$ by a factor $\sqrt{1-1 / n}$.

Note that at the beginning of the algorithm, the volume of that block is at $\operatorname{most}\left(\max _{i}\left\|b_{i}\right\|\right)^{k}$. There are therefore at most $\log \left(\left(\max \left\|b_{i}\right\|\right)^{k}\right) / \log (\sqrt{1-1 / n})=$ $O\left(n^{2} \log \left(\max _{i}\left\|b_{i}\right\|\right)\right)$ loop iterations.

## Remark

One may note that the algorithm and its proof should still work if we replace exact SVP solvers with approximate SVP solver with approximation factor strictly less than $1 / \sqrt{1-1 / n}=1+1 /(2 n)+O\left(1 / n^{2}\right)$.

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[^0]:    ${ }^{1}$ Lifting this projected solution to a full solution should then be rather easy according to further heuristic reasoning [18, Claim 1].

[^1]:    ${ }^{2}$ They in fact propose a trade-off, which can reach larger approximation factors at the cost of making super-polynomially or even exponentially many calls to the Gap-SVP oracle
    ${ }^{3}$ or only just a little bit: we remark later on that our approach would survive an tiny approximation factor of $1+o\left(n^{-1 / 2}\right)$

[^2]:    ${ }^{4}$ or at least makes it less straightforward: the expert reader might see a proof path invoking the random self-reducibility of LIP [5, Lemma 3.9] and the automorphism group of $\mathbb{Z}^{n}$.
    ${ }^{5}$ There exist an equivalent and sometime advatageous formulation of LIP using positive definite quadratic forms, where basis are replaced by their Gram matrices. In our context, we find the explicit basis formalism to be more convenient. We refer to [1, 5] for this alternative formulation.

[^3]:    ${ }^{6}$ See exercises 209, 218 and 219 of http://perso.ens-lyon.fr/serre/DPF/exobis.pdf for three different proofs of this fact. One may alternatively invoke the Brunn-Minkowski theorem.

